



Landsat Data Gap Studies: Potential Data Gap Sources

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U.S. Department of the Interior
U.S. Geological Survey



Project Introduction

- **USGS Remote Sensing Technologies (RST) Project**
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 - ◆ Greg Stensaas - (605) 594-2569 - stensaas@usgs.gov
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- Project provides:
 - ◆ characterization and calibration of aerial and satellite systems in support of quality acquisition and understanding of remote sensing data,
 - ◆ and verifies and validates the associated data products with respect to ground and atmospheric truth so that accurate value-added science can be performed.
 - ◆ assessment of new remote sensing technologies
- Working with many organizations and agencies; US and International

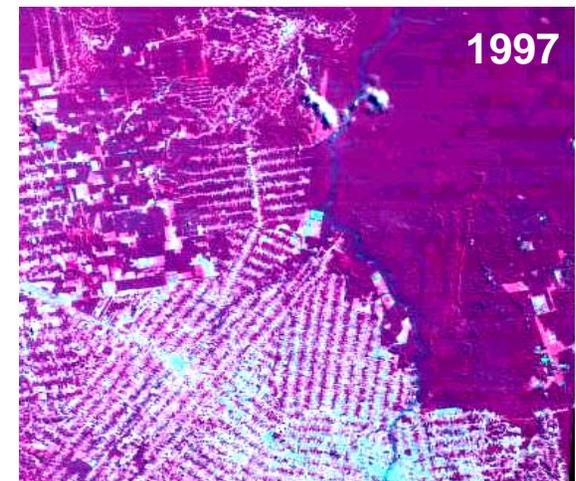
System/Product Characterization

- **System Characterization** is related to understanding the sensor system, how it produces data, and the quality of the produced data
- **Imagery** attempts to accurately report the conditions of the Earth's surface at a given the time.
 - ◆ Assessed by *product characterization* categories:
 - **Geometric/Geodetic:** The positional accuracy with which the image represents the surface (pixel coordinates vs. known ground points)
 - **Spatial:** The accuracy with which each pixel represents the image within its precise portion of the surface and no other portion
 - **Spectral:** The wavelengths of light measured in each spectral "band" of the image
 - **Radiometric:** The accuracy of the spectral data in representing the actual reflectance from the surface
 - **Dataset Usability:** The image data and understanding of the data is easily usable for science application

Landsat Importance to Science

- Change is occurring at rates unprecedented in human history
- The Landsat program provides the only inventory of the global land surface over time
 - ◆ at a scale where human vs. natural causes of change can be differentiated
 - ◆ on a seasonal basis
- No other satellite system is capable/committed to even annual global coverage at this scale

Amazonian Deforestation



U.S. Landsat Archive Overview

(Marketable Scenes through September 25, 2006)

- **ETM+: Landsat 7**
 - ◆ 654,932 scenes
 - ◆ 608TB RCC and L0Ra Data
 - ◆ Archive grows by 260GB Daily
- **TM: Landsat 4 & Landsat 5**
 - ◆ 671,646 scenes
 - ◆ 336TB of RCC and L0Ra Data
 - ◆ Archive Grows by 40GB Daily
- **MSS: Landsat 1 through 5**
 - ◆ 641,555 scenes
 - ◆ 14TB of Data



Landsat Data Gap Study Team (LDGST)

- **The Earth observation community is facing a probable gap in Landsat data continuity before LDCM data arrive in ~2011**
- **A data gap will interrupt a 34+ yr time series of land observations**
- **Landsat data are used extensively by a broad & diverse users**
 - ◆ Landsat 5 limited lifetime/coverage
 - ◆ Degraded Landsat 7 operations
 - ◆ Either or both satellites could fail at any time: both beyond design life
- **Urgently need strategy to reduce the impact of a Landsat data gap**
 - ◆ Landsat Program Management must determine utility of alternate data sources to lessen the impact of the gap & feasibility of acquiring data from those sources in the event of a gap
 - ◆ A Landsat Data Gap Study Team, chaired by NASA and the USGS, has been formed to analyze potential solutions

Team Membership

Edward Grigsby, NASA HQ, Co- Chair

Ray Byrnes, USGS HQ, Co- Chair

Garik Gutman, NASA HQ, Co- Chair

Jim Irons, NASA GSFC, Community Needs Working Group Lead

Bruce Quirk, USGS EDC, System Capabilities Working Group Lead

Bill Stoney, Mitretek Systems, Needs-to-Capabilities Working Group Lead

Vicki Zaroni, NASA HQ Detail, Team Coordinator and Synthesis Working Group Lead

Mike Abrams, JPL

Bruce Davis, DHS (NASA detailee)

Brad Doorn, USDA FAS

Fernando Echavarria, Dept. of State

Stuart Frye, Mitretek Systems

Mike Goldberg, Mitretek Systems

Sam Goward, U. of Maryland

Ted Hammer, NASA HQ

Chris Justice, U. of Maryland

Jim Lacasse, USGS EDC

Martha Maiden, NASA HQ

Dan Mandl, NASA GSFC

Jeff Masek, NASA GSFC

Gran Paules, NASA HQ

John Pereira, NOAA/NESDIS

Ed Sheffner, NASA HQ

Tom Stanley, NASA SSC

Woody Turner, NASA HQ

Sandra Webster, NGA

Diane Wickland, NASA HQ

Darrel Williams, NASA GSFC



Team Strategy

Objective

- **Recommend options, using existing and near-term capabilities, to store, maintain, and upgrade science-quality data in the National Satellite Land Remote Sensing Data Archive**
 - ◆ Consistent with the Land Remote Sensing Policy Act of 1992

Approach

- **Identify data “sufficiently consistent in terms of acquisition geometry, spatial resolution, calibration, coverage characteristics, and spatial characteristics with previous Landsat data...”**
 - ◆ Consistent with Management Plan for the Landsat Program

Process

- **Identify acceptable gap-mitigation specifications**
- **Identify existing and near-term capabilities**
- **Compare capabilities to acceptable specifications**
- **Synthesize findings and make recommendations**

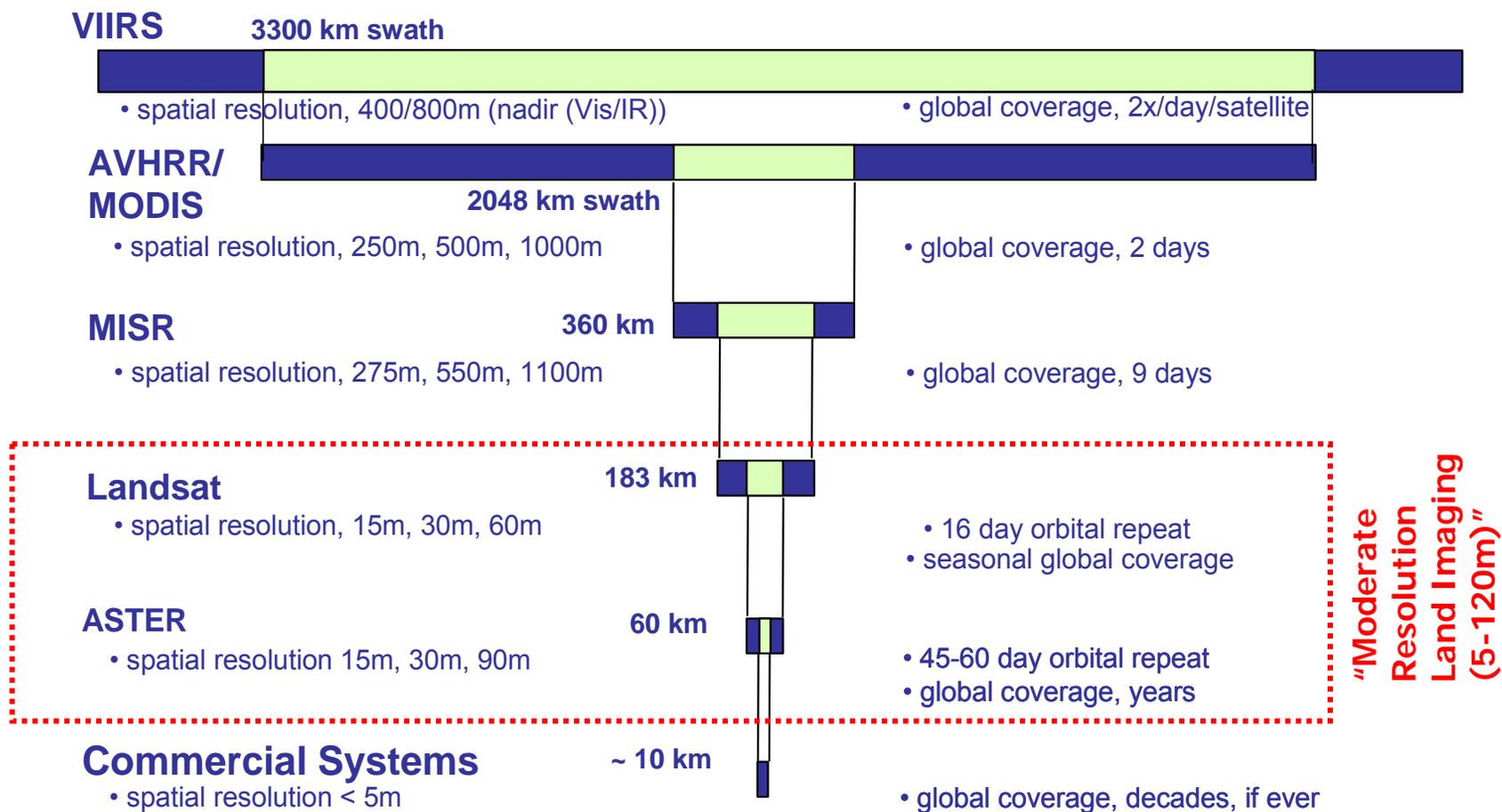


Team Assumptions

- Assume 2007 Landsat 7 failure for planning purposes
- Assume limited lifetime and capability for Landsat 5
- Focus on data acquisition vs. building a satellite
- Address DOI responsibility to store, maintain, and upgrade science-quality data in the National Satellite Land Remote Sensing Data Archive (NSLRSDA)
- OLI data available no earlier than 2010
- LDCM data specification used to define team's data quality and quantity goals
- Landsat 7 unrestricted data policy will serve as the model for acquired data

TOOLS FOR OBSERVING THE LAND

Resolution and coverage for different needs....



.... PLUS RADAR, MAGNETICS, MICROWAVE, ETC., plus airborne and in situ methods

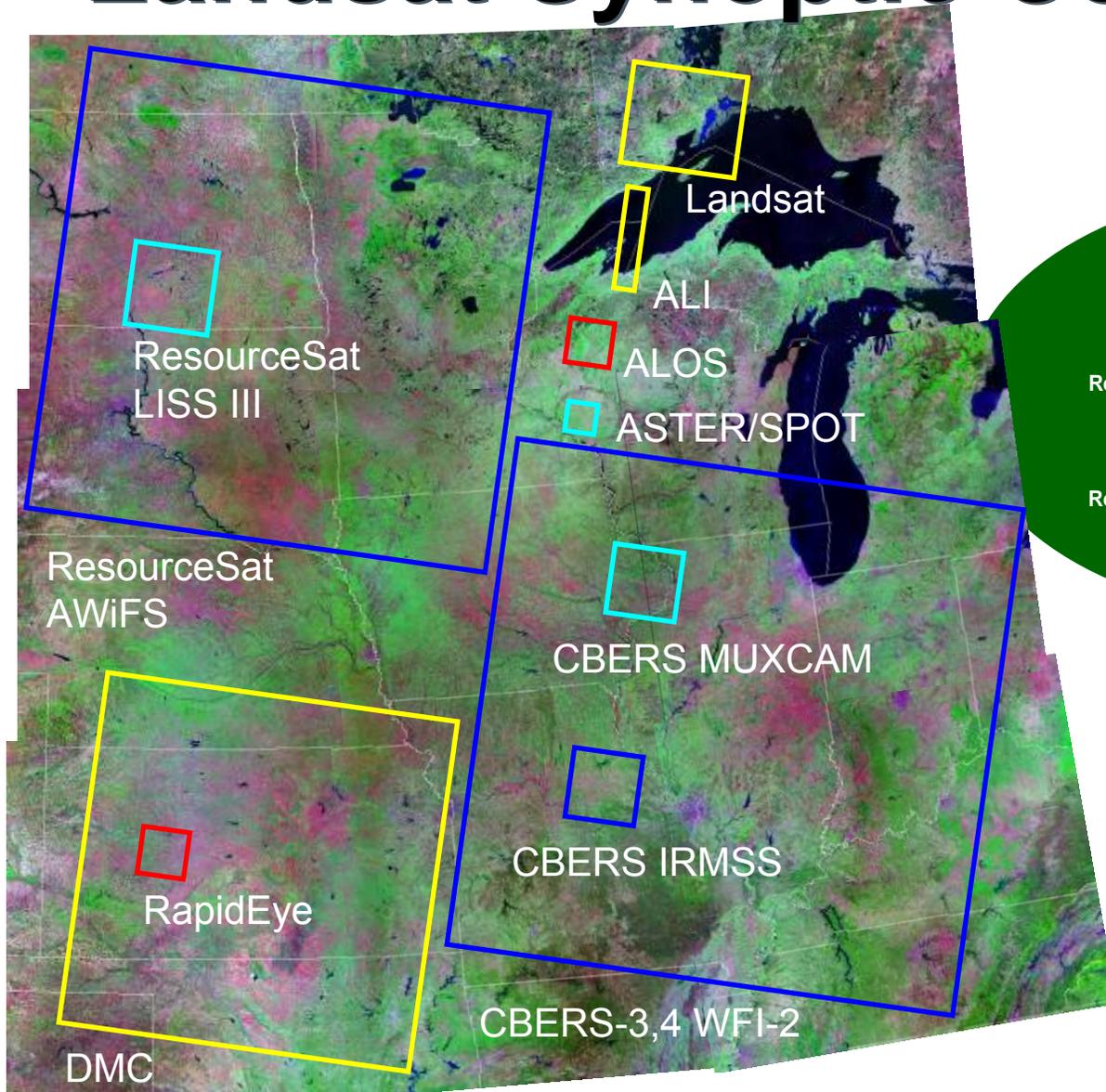
Requirements and Capabilities Analysis

- **LDCM Data Specification (“Goal”) has been vetted by science and applications communities, and supports the full range of Landsat applications**
- **Obtaining data identical to LDCM from existing systems is not possible**
- **Minimum acceptable specifications were derived to support basic global change research given available sources of Landsat-like data**
 - ◆ 2x Annual Global Coverage
 - ◆ Spatial Resolution
 - ◆ Spectral Coverage
 - ◆ Data Quality

Systems Considered

- ✓ IRS ResourceSat – 1, 2 (India)
- ✓ CBERS – 2, 2A, 3, 4 (China & Brazil)
- ✓ Rapid Eye – 1, 2, 3, 4, 5 (Germany)
- ✓ DMC (Algeria, Nigeria, UK, China)
- ✓ Terra/ASTER (US & Japan)
- ✓ High-resolution U.S. commercial systems
- ✓ IKONOS, Quickbird, OrbView-3
- ✓ ALOS (Japan)
- ✓ SPOT – 4, 5 (France)
- ✓ EO-1/ALI (US)

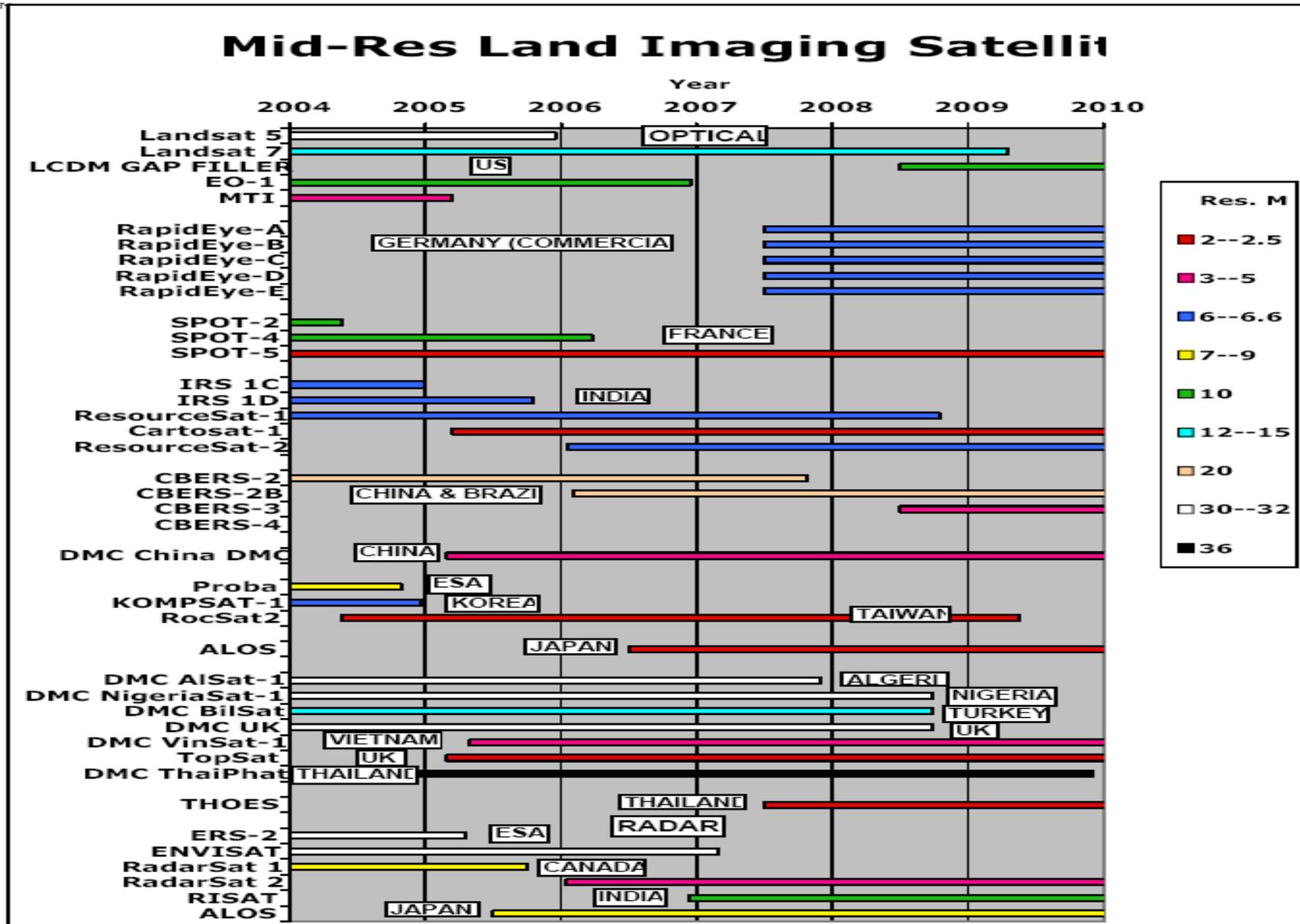
Landsat Synoptic Coverage



Satellite	Sensor	Ground Sample Distance (m)
RapidEye	REIS	6.5
ALOS	AVNIR	10
CBERS-3,4	MUXCAM	20
SPOT 5	HRG	10/20
Terra	ASTER	15/30/90
ResourceSat-1	LISS III+	23.5
Landsat 7	ETM+	15/30/60
EO-1	ALI	30
DMC	MSDMC	32
ResourceSat-1	AWiFS*	56
CBERS-3,4	WFI-2	73
CBERS-3,4	IRMSS	40/80

Note: For purposes of scene size comparison only. Locations do not represent actual orbital paths or operational acquisitions.

Systems Considered



Landsat Data Gap Synopsis

- **There is no substitute for Landsat**
 - ◆ Single source of systematic, global land observations
 - ◆ Alternate sources may reduce the impact of a Landsat data gap
- **Data quality and operational capability of potential candidate systems is currently being verified**
 - ◆ USGS currently working with ISRO ResourceSat-1 (India) and CAST/INPE CBERS (China Brazil)
- **Landsat data gap mitigation efforts could serve as prototype for Integrated Earth Observing System (IEOS -- U.S. contribution to GEOSS)**
 - ◆ Implementation plan correlates with IEOS Global Land Observing System concept
- **Several systems could meet special regional acquisition needs during some or all of the data gap period**

Data Gap Study Team Management

- **Landsat Data Gap Study Team (LDGST)**

- ◆ Developing a strategy for providing data to National Satellite Land Remote Sensing Data Archive for 1-4 years
- ◆ Policy and Management Team – Ed Grigsby and Ray Byrnes
- ◆ Technical Team – Chaired by Jim Irons

- **Data Characterization Working Group (DCWG)**

- ◆ Technical group from three field centers (USGS EROS, NASA GSFC, NASA SSC) to evaluate data from IRS-P6 and CBERS-2 sensors

- **Tiger Team Charter**

- ◆ The tiger team is charged with developing & analyzing a set of technical & operational scenarios for receiving, ingesting, archiving, and distributing data from alternative, Landsat-like satellite systems.
- ◆ The tiger team will conduct trade studies & assess the risk of the various scenarios & provide rough order magnitude costs for the alternatives

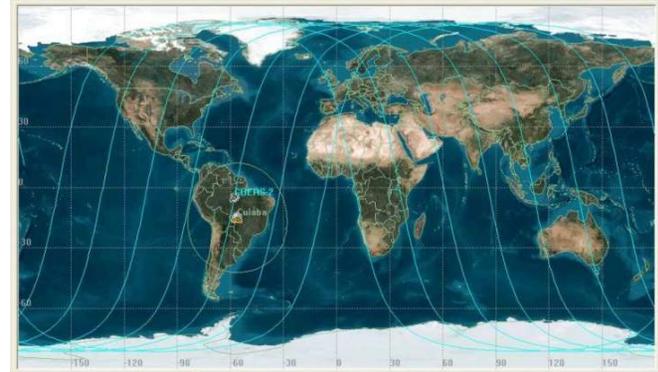
Overview of the CBERS-2 sensors

Cross-Calibration of the L5 TM and the CBERS-2 CCD sensor



China Brazil Earth Resources Satellite - CBERS

- **CBERS-1, was launched on Oct. 14, 1999**
 - ◆ The spacecraft was operational for almost 4 years
 - ◆ The CBERS-1 images were not used by user community
 - ◆ On Aug. 13, 2003, CBERS-1 experienced an X-band malfunction causing an end of all image data transmissions
- **CBERS-2 (or ZY-1B) was launched successfully on Oct. 21, 2003 from the Taiyuan Satellite Launch Center**
 - ◆ The spacecraft carries the identical payload as CBERS-1
- **CBERS Orbit**
 - ◆ Sun synchronous
 - ◆ Height: 778 km
 - ◆ Inclination: 98.48 degrees
 - ◆ Period: 100.26 min
 - ◆ Equator crossing time: 10:30 AM
 - ◆ Revisit: 26 days
 - ◆ Distance between adjacent tracks: 107 km



CBERS- Sensor Compliment

- **CBERS satellite carries on-board a multi sensor payload with different spatial resolutions & collection frequencies**
 - ◆ HRCCD (High Resolution CCD Camera)
 - ◆ IRMSS (Infrared Multispectral Scanner)
 - ◆ WFI (Wide-Field Imager)
- **The CCD & the WFI camera operate in the VNIR regions, while the IRMSS operates in SWIR and thermal region**
- **In addition to the imaging payload, the satellite carries a Data Collection System (DCS) and Space Environment Monitor (SEM)**

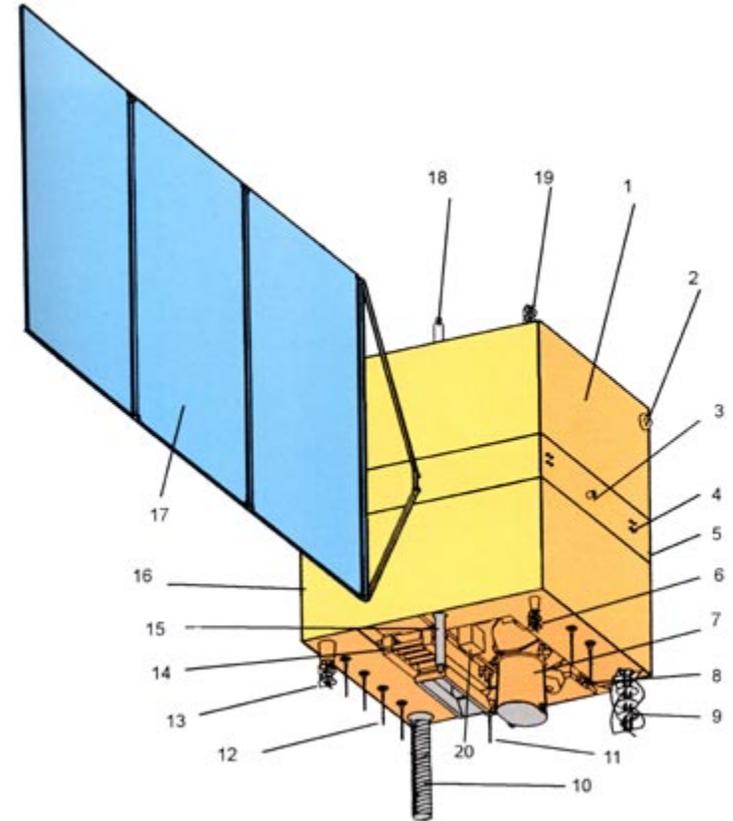
Work Share (70% China, 30% Brazil)

Pay load Module (16)

CCD (14)	China
IRMSS (7)	China
WFI (20)	Brasil
Data Transmission	China
Data collection	Brasil

Service Module (1)

Structure	Brasil
Thermal Control	China
Attitude and Orbit Control	China
Power supply	Brasil
On-board computer	China
Telemetry	Brasil



High Resolution CCD (HRCCD)

- **The HRCCD is the highest-resolution sensor offering a GSD of 20m at nadir (Pushbroom scanner)**
- **Quantization: 8 bits**
- **Ground swath is 113 km with 26 days repeat cycle**
 - ◆ Steerable upto +/- 32° across track to obtain stereoscopic imagery
- **Operates in five spectral bands - one pan & four VNIR**
 - ◆ CCD has one focal plane assembly
 - ◆ The signal acquisition system operates in two channels
 - Channel 1 has Bands 2, 3, 4
 - Channel 2 has Bands 1,3,5
 - Four possible gain settings are 0.59, **1.0**, 1.69 & 2.86

Infrared Multispectral Scanner (IRMSS)

- The IRMSS is a moderate-resolution sensor offering a GSD of 80m (pan/SWIR) & 160m (thermal)
- Quantization: 8 bits
- Ground swath is 120 km with 26 days repeat cycle
- Operates in four spectral bands - one pan, two SWIR & one thermal
 - ◆ The four spectral bands has eight detector staggered arrays mounted along track
 - ◆ IRMSS has three focal plane assemblies
 - The Pan band (Si photodiodes detectors) is located on the warm focal plane
 - The SWIR bands & the thermal band (HgCdTe detectors) are located on cold focal planes with cryogenic temps of 148K & 101K respectively
 - Four of eight thermal detectors are spare

Wide-Field Imager (WFI)

- The WFI camera provides a synoptic view with spatial resolution of 260m
- Ground swath is 885km with 3-5 days repeat cycle
- Operates in two spectral bands – (Band 3 & 4)
 - ◆ 0.63 - 0.69 μm (red) and 0.77 - 0.89 μm (infrared)
 - ◆ Similar bands are also present in the CCD camera providing complementary data

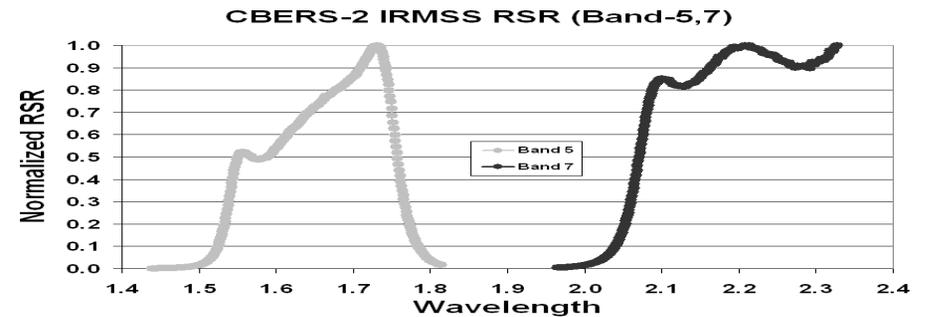
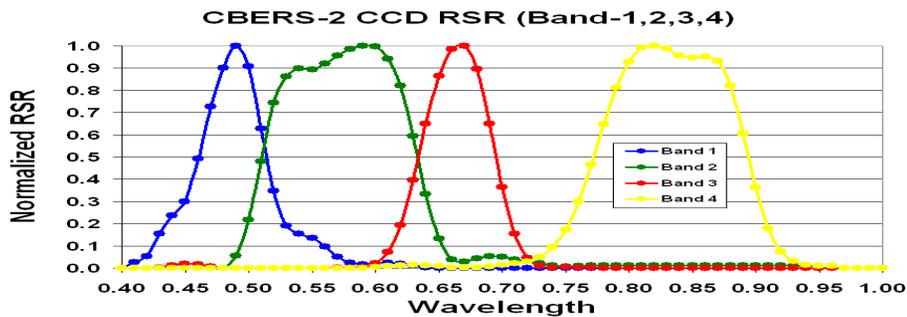
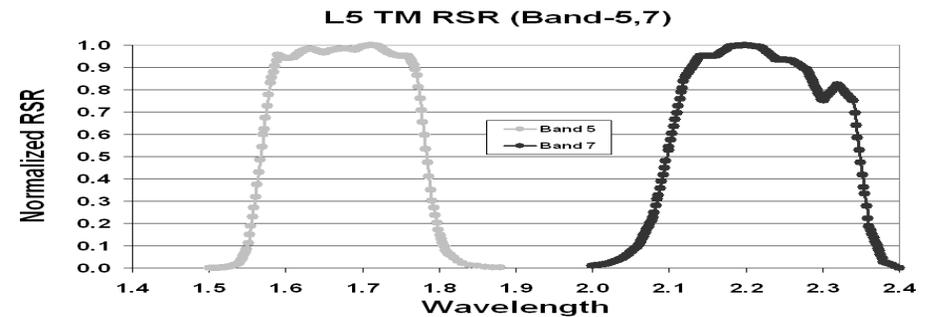
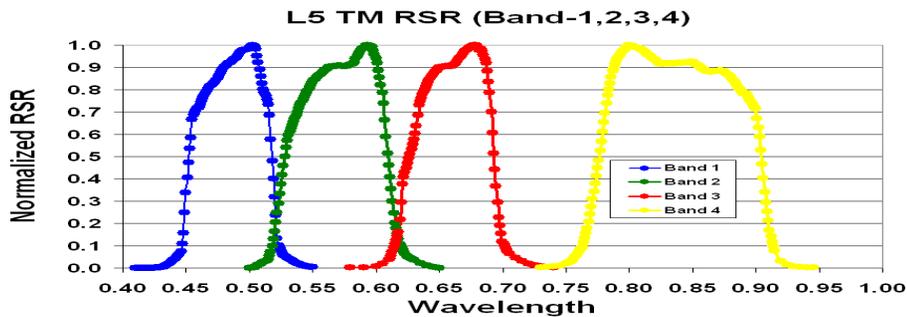
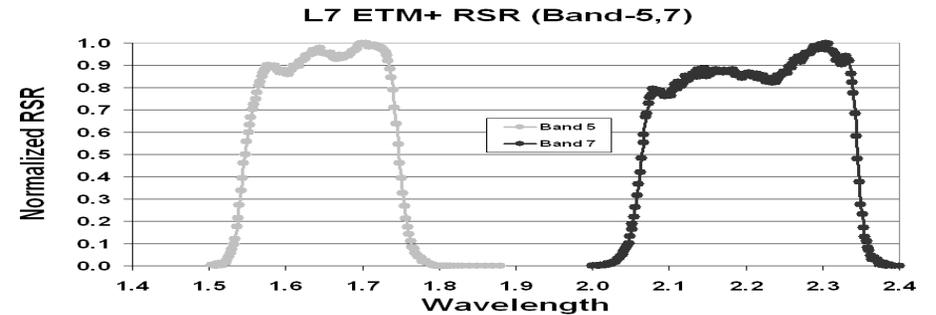
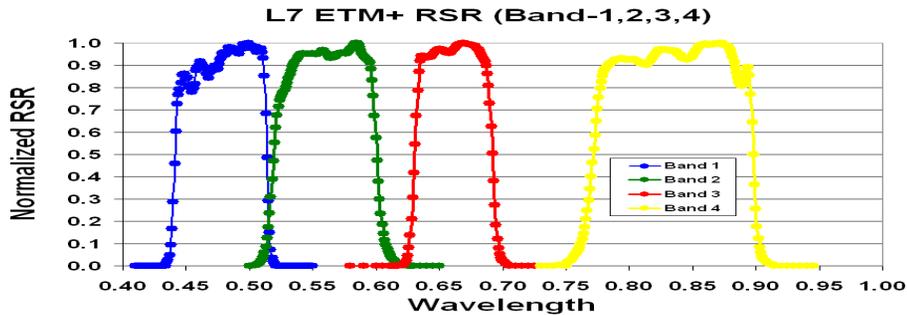
Overview of the CBERS instruments

Parameter	HRCC	IRMSS	WFI
Spectral Bands (µm)	0.51 - 0.73 (PAN)	0.50 - 1.10 (PAN)	0.63 - 0.69
	0.45 - 0.52	1.55 - 1.75 (SWIR)	0.76 - 0.90
	0.52 - 0.59	2.08 - 2.35 (SWIR)	
	0.63 - 0.69	10.4 - 12.5 (TIR)	
	0.77 - 0.89		
Spatial Resolution	20 m	80 m (PAN & SWIR) 160 m (TIR)	260 m
Swath Width (FOV)	113 km (8.32°)	120 km (8.78°)	885 km (60°)
Temporal Resolution	26 days	26 days	3-5 days
Cross-Track Pointing	±32°		
Data Rate	2 x 53 Mbit/s	6.13 Mbit/s	1.1 Mbit/s
Carrier Frequency (X-band)	8.103 and 8.321 GHz	8.216 GHz	8.203 GHz
EIRP	43 dBm	39.2 dBm	31.8 dBm
Modulation	QPSK	BPSK	QPSK
Tracking Beam Frequency	8.196 GHz	8.196 GHz	8.196 GHz

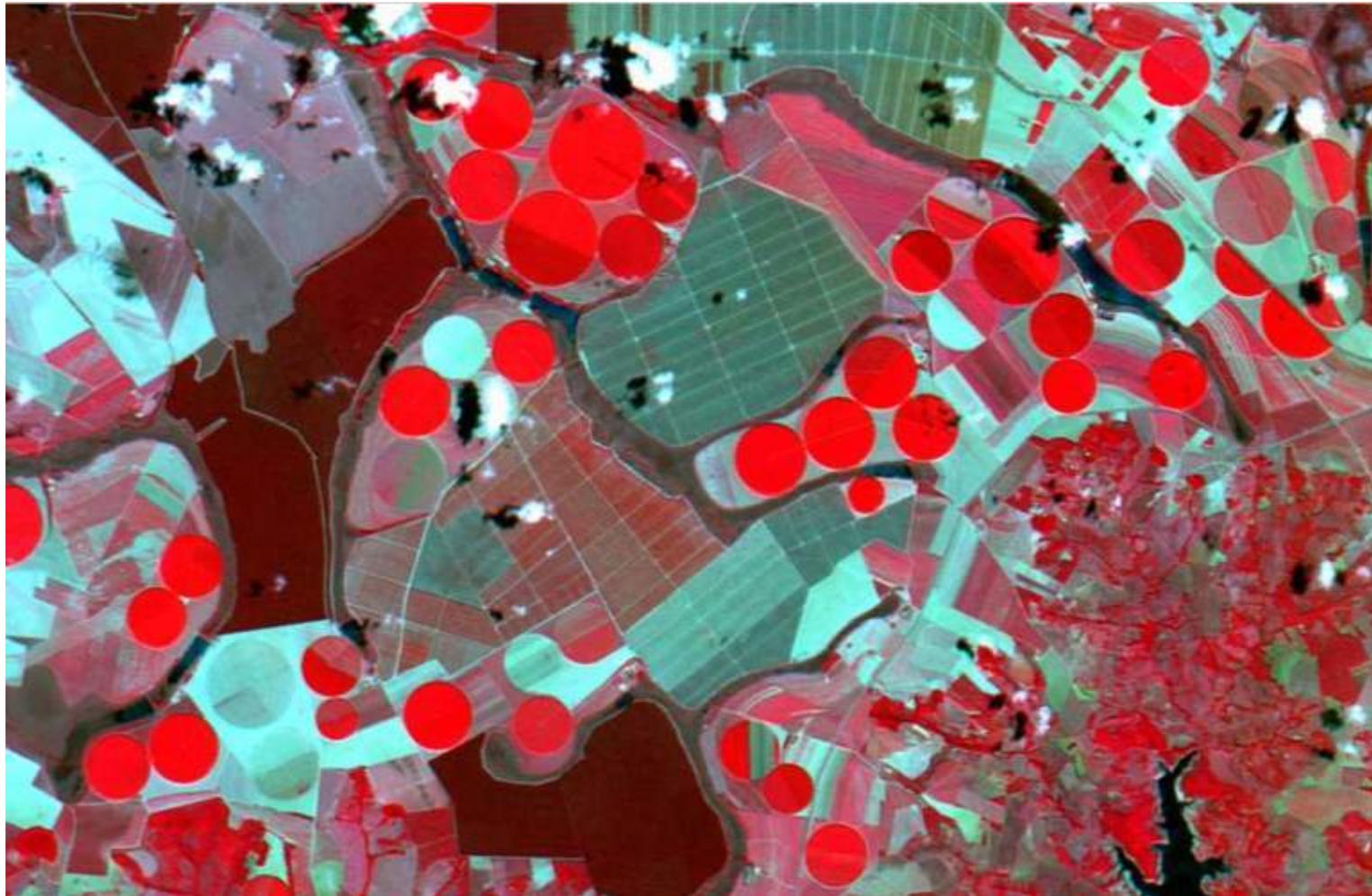
Spectral Range (µm) and Ground Sample Distance (m)							
Band	Landsat		CBERS			SPOT-4	IRS-P6
	L5 TM	L7 ETM+	HRCC	IRMSS	WFI		LISS-III
RC	16	16	26	26	5	26	24
1	0.450-0.520 (30)	0.450-0.515 (30)	0.45-0.52 (20)				
2	0.520-0.600 (30)	0.525-0.605 (30)	0.52-0.59 (20)			0.50-0.59 (20)	0.52-0.59 (23.5)
3	0.630-0.690 (30)	0.630-0.690 (30)	0.63-0.69 (20)		0.63-0.69 (260)	0.61-0.68 (20)	0.62-0.68 (23.5)
4	0.760-0.900 (30)	0.775-0.900 (30)	0.77-0.89 (20)		0.76-0.90 (260)	0.79-0.89 (20)	0.77-0.86 (23.5)
5	1.550-1.750 (30)	1.550-1.750 (30)		1.55-1.75 (80)		1.58-1.75 (20)	1.55-1.70 (23.5)
6	10.40-12.50 (120)	10.40-12.50 (60)		10.4-12.5 (160)			
7	2.080-2.350 (30)	2.090-2.350 (30)		2.08-2.35 (80)			
Pan		0.520-0.900 (15)	0.51-0.73 (20)	0.50-1.10 (80)		0.51-0.73 (10)	0.50-0.75 (5.8)



Relative Spectral Response (RSR) Profiles



CBERS-2 CCD, Minas Gerais, Brazil



CBERS-2 IRMSS

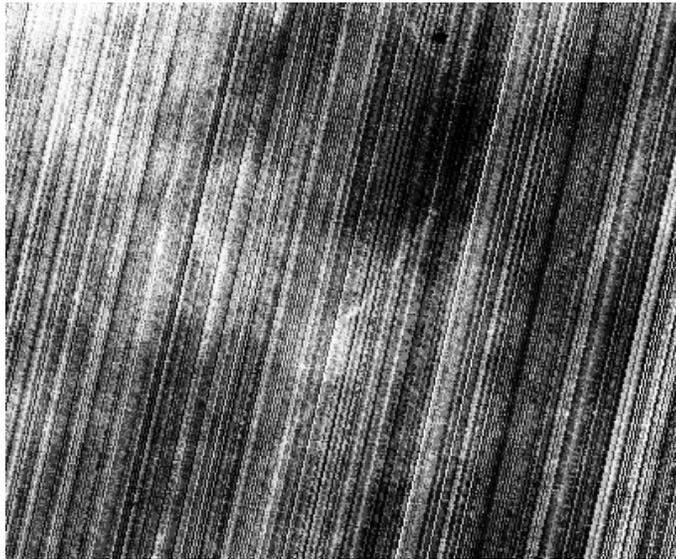


CBERS-2 CCD image, Louisiana
Obtained from on-board data recorder

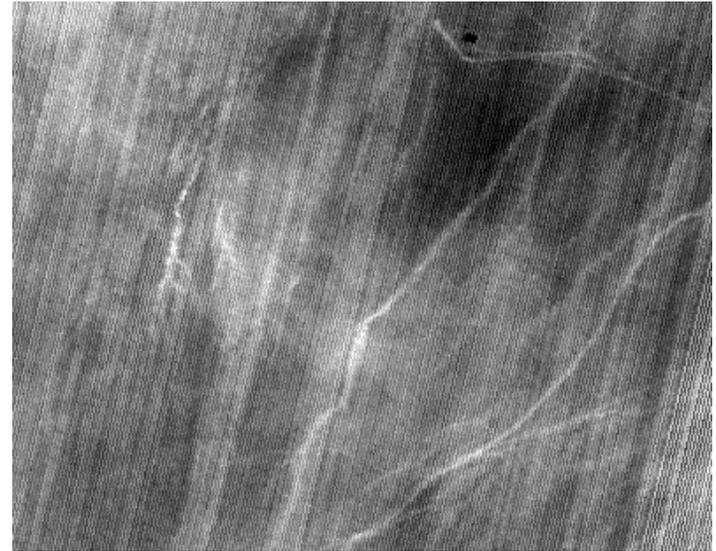


CB2-IRM-157/124, 24/3/2004, Catanduva (Brazil)

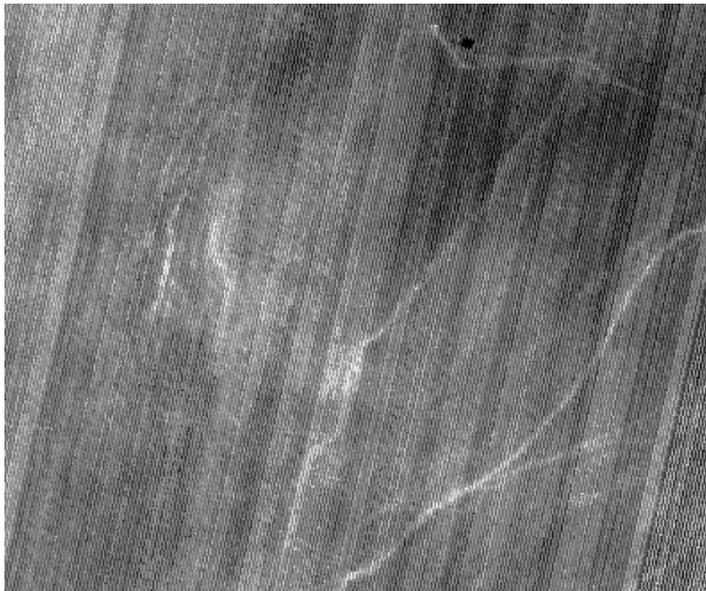
Striping in the CCD data



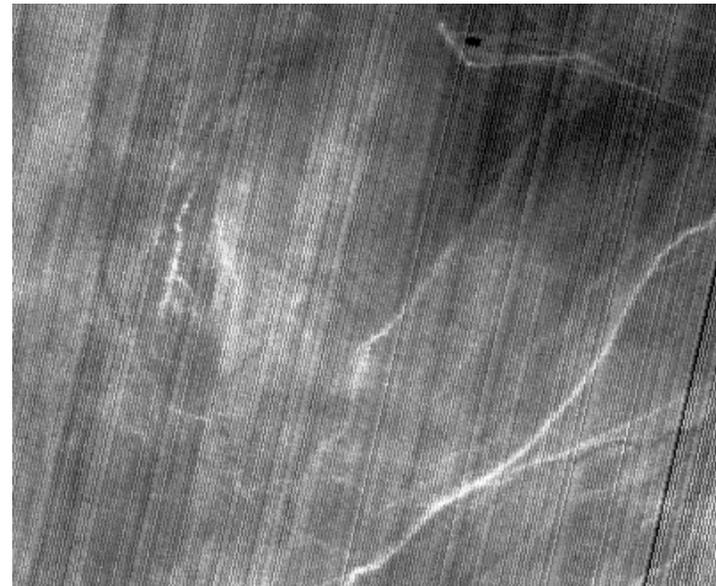
B1



B2



B3



B4

Absolute Calibration Coefficients

- Independent studies are carried out by INPE & CRESDA
 - ◆ INPE used calibration sites in the west part of State Bahia
 - ◆ CRESDA used Gobi desert (Dunhuang) test site in China

$$L^* = DN_n / CC_n$$

L^* = spectral radiance at the sensors aperture $W/(m^2 \cdot sr \cdot \mu m)$

DN = Digital number extracted from the image in band n

CC_n = absolute calibration coefficient for band n

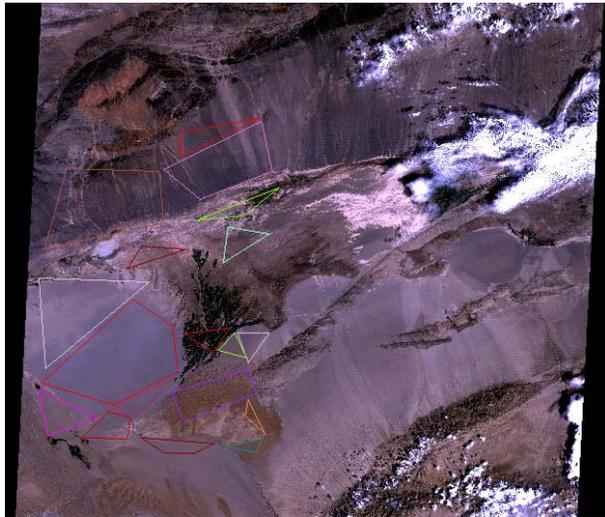
CBERS-2 CCD Vicarious Absolute Calibration Coefficients (CC _n)						
	Test-Site	CCD_1	CCD_2	CCD_3	CCD_4	CCD_Pan
Pre-launch		0.9800	1.5900	1.2000	2.2900	1.2500
Brazil						
25th June 2004	Bahia	1.228	2.357	1.215	2.553	1.628
16th August 2004		1.0090	1.9300	1.1540	2.1270	1.4830
Oct_3th New		0.862	1.544	0.874	1.933	0.995
Oct_3th Old		0.978	1.721	1.057	1.936	1.223
Oct_6th New		0.84	1.558	0.89	2.095	1.03
Oct_6th Old		0.97	1.74	1.083	2.105	1.263
China						
19th August 2004		0.9917	1.6761	1.0096	2.0613	
25th August 2004	Dunhuang	1.0292	1.7254	1.0356	2.1515	
24th August 2005	Dunhuang	1.0288	1.8096	1.1079	2.2783	

CBERS-2 CCD absolute calibration accuracy relative to L5 TM

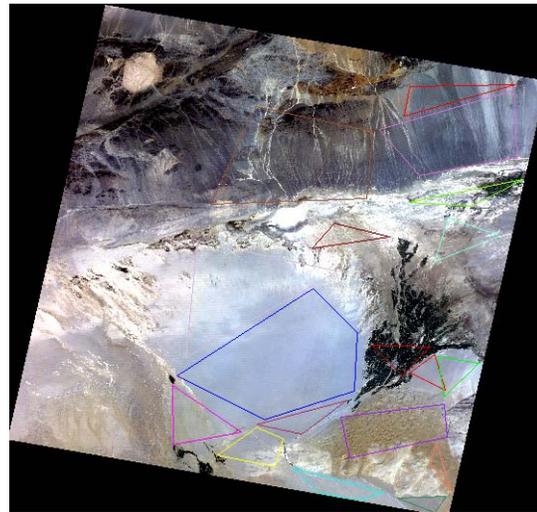
- **Data continuity within the Landsat Program requires consistency in interpretation of image data acquired by different sensors**
 - ◆ A critical step in this process is to put image data from subsequent generations of sensors onto a common radiometric scale
- **To evaluate CBERS-2 CCD utility in this role, image pairs from the CBERS-2 CCD & L5 TM sensors were compared**
 - ◆ The cross-calibration was performed using image statistics from large common areas observed by the two sensors
- **It is very difficult to get coincident image pairs from the two satellites (different WRS)**

Agency	Sensor	Date	DOY	Path	Row	Look angle	Sun Elevation	GMT
CRESDA	CBERS-2 CCD	8/25/2004	237	23	55	-6.03	56.60	
	L5 TM	8/25/2004	237	137	32	0.00	53.37	
INPE	CBERS-2 CCD	12/30/2004	365	154	126		64.23	13:14:15
	L5 TM	12/29/2004	364	219	76	0.00	59.32	12:50:15
INPE	CBERS-2 CCD	11/16/2005	320	151	126		66.47	12:58:05
	L5 TM	11/16/2005	320	217	76	0.00	63.03	12:40:25

L5 TM and CBERS-2 CCD Image Pairs

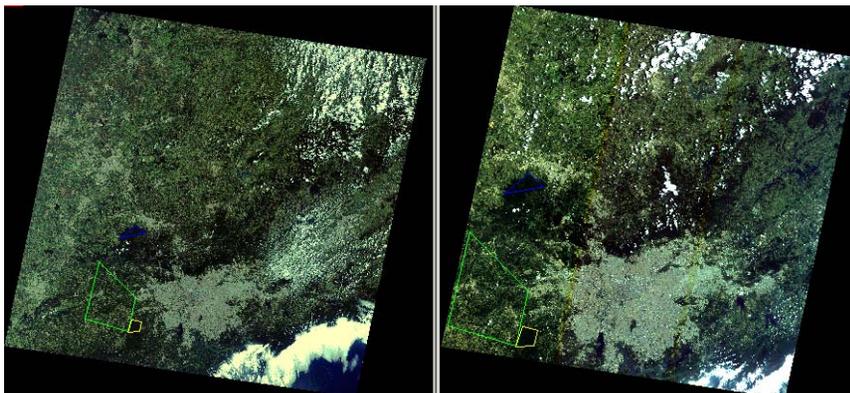


L5 TM WRS Path = 137 Row = 032
Nadir looking

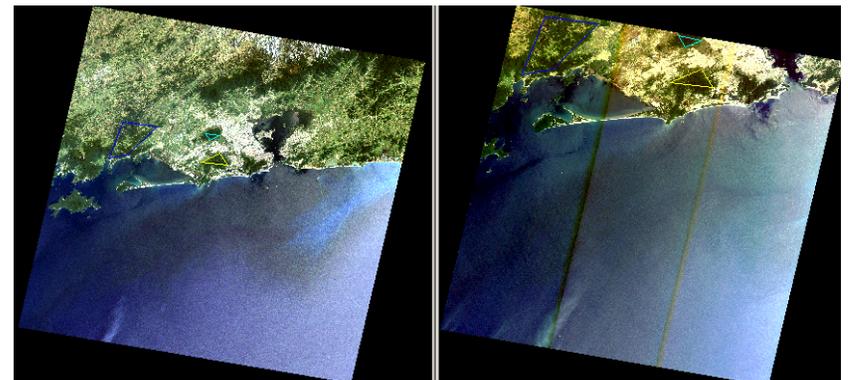


CBERS-2 CCD Path = 23 Row = 55 side-
looking (off-nadir-look-angle=-6.0333)

Gobi (Dunhuang) desert test site
Data acquired on
Aug 25, 2004 (20 min apart)

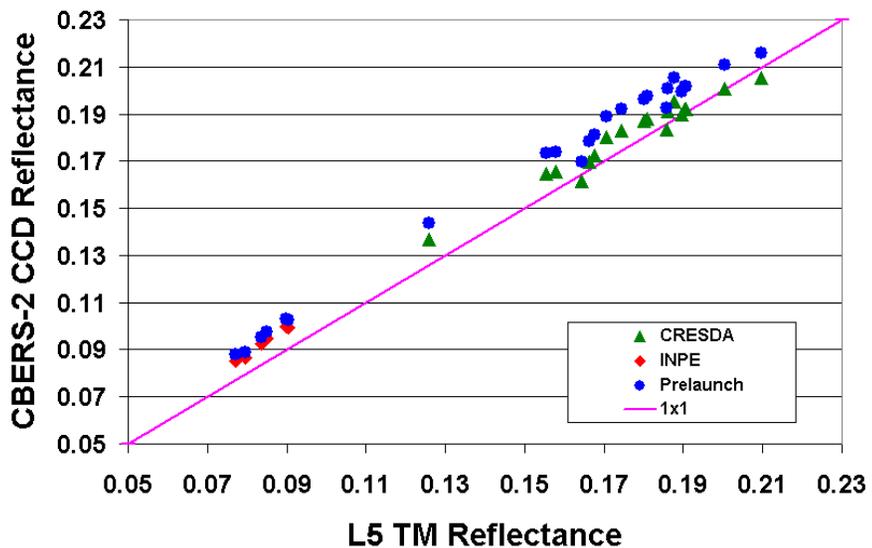


L5 TM WRS Path = 219 Row = 076
Nadir looking Acquisition Date: Dec 29, 2004
CBERS-2 CCD Path = 154 Row = 126
Acquisition Date: Dec 30, 2004

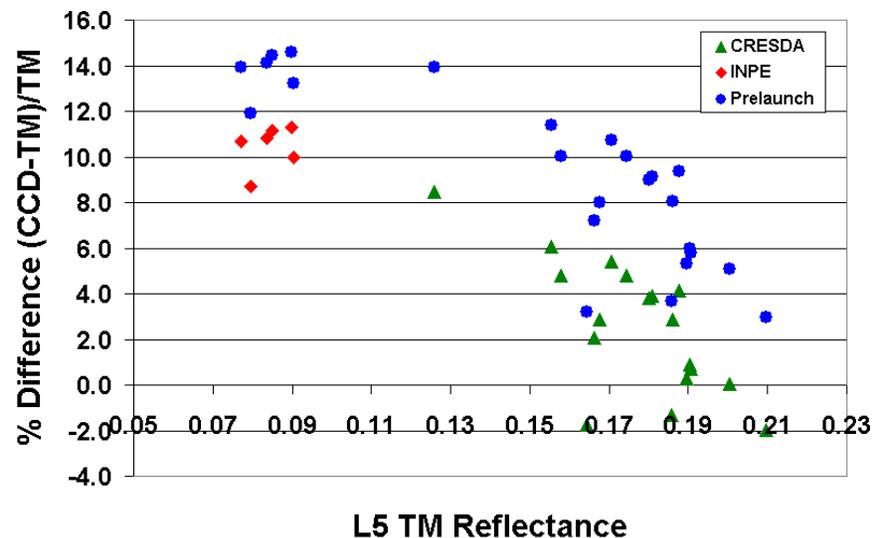


L5 TM WRS Path = 217 Row = 076
Nadir looking Acquisition Date: Nov 16, 2005
CBERS-2 CCD Path = 151 Row = 126
Acquisition Date: Nov 16, 2005

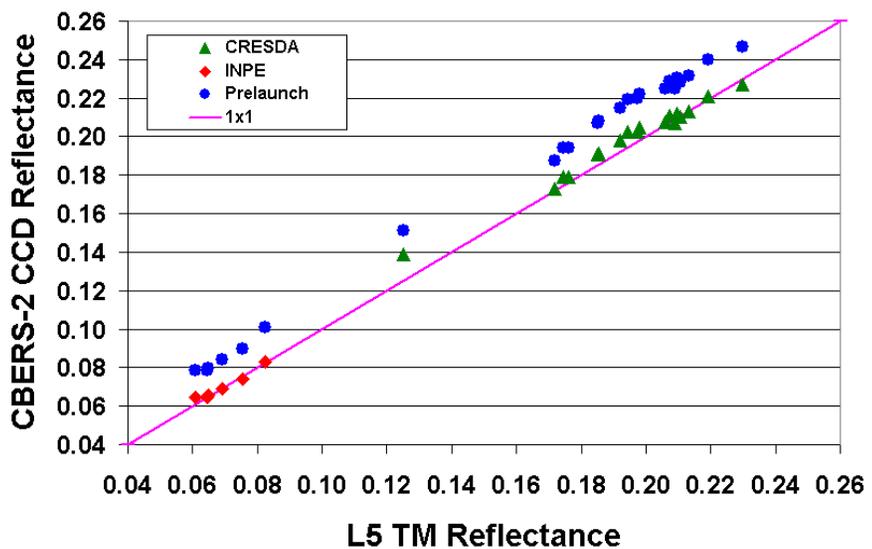
Reflectance obtained from L5 TM and CBERS-2 CCD (Band 1)



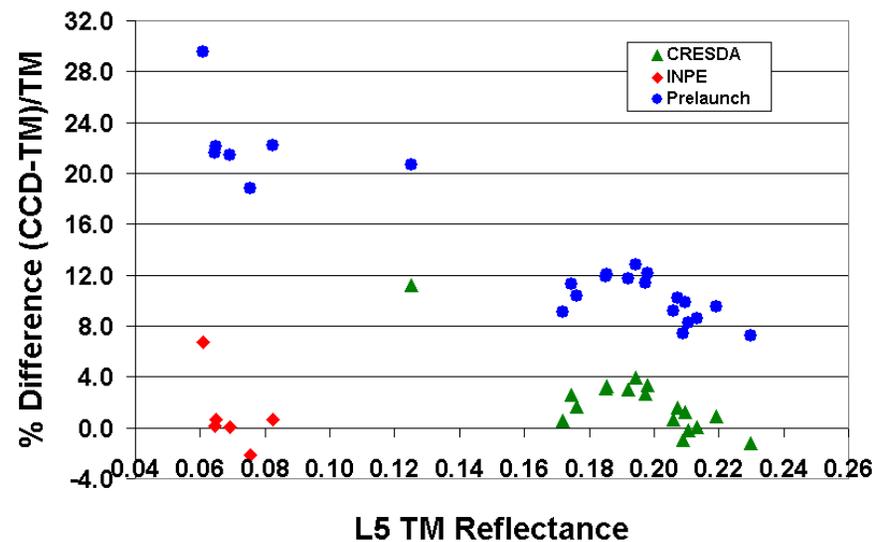
CBERS-2 CCD % difference relative to L5 TM (Band 1)



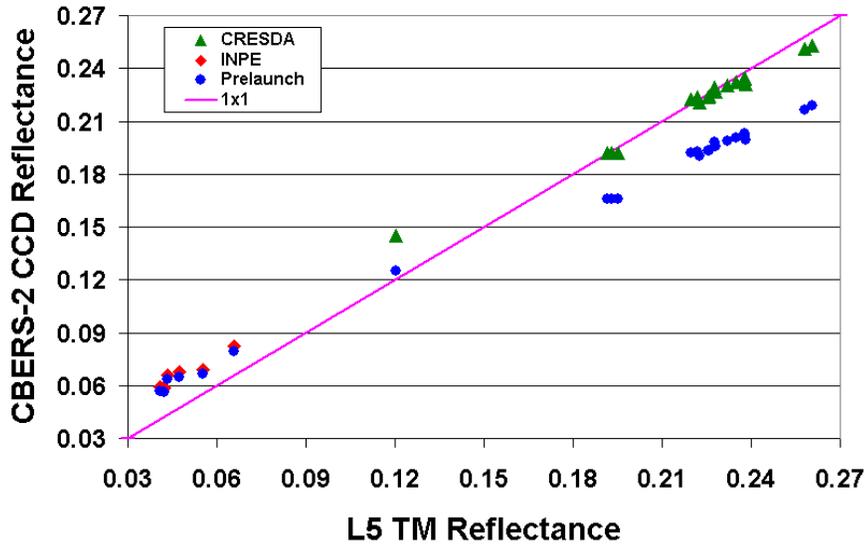
Reflectance obtained from L5 TM and CBERS-2 CCD (Band 2)



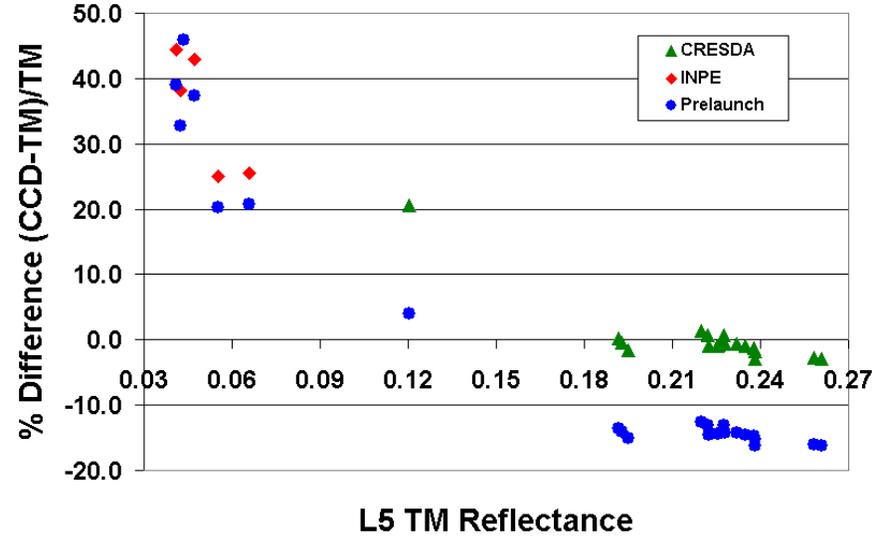
CBERS-2 CCD % difference relative to L5 TM (Band 2)



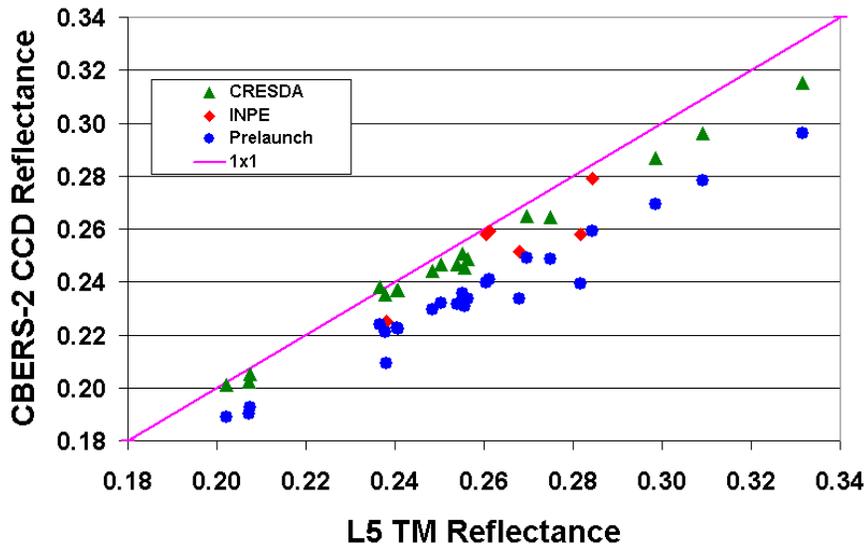
Reflectance obtained from L5 TM and CBERS-2 CCD (Band 3)



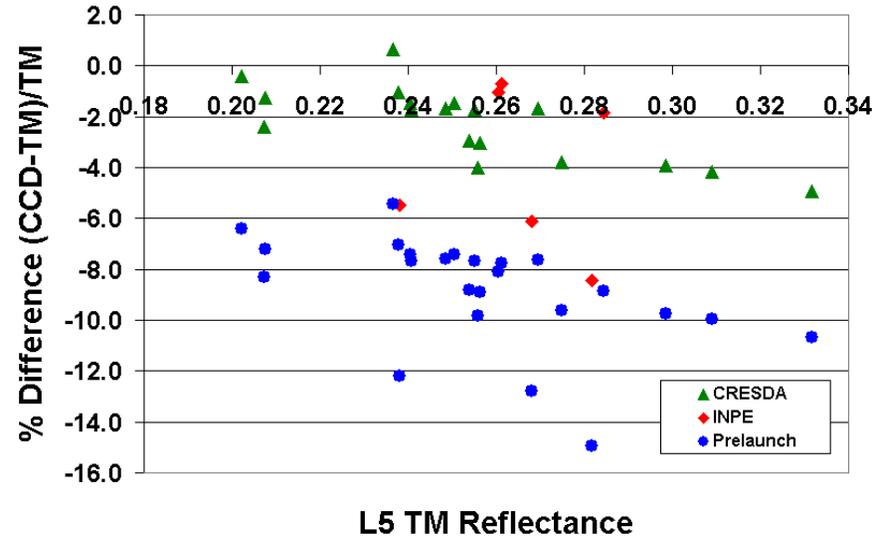
CBERS-2 CCD % difference relative to L5 TM (Band 3)



Reflectance obtained from L5 TM and CBERS-2 CCD (Band 4)

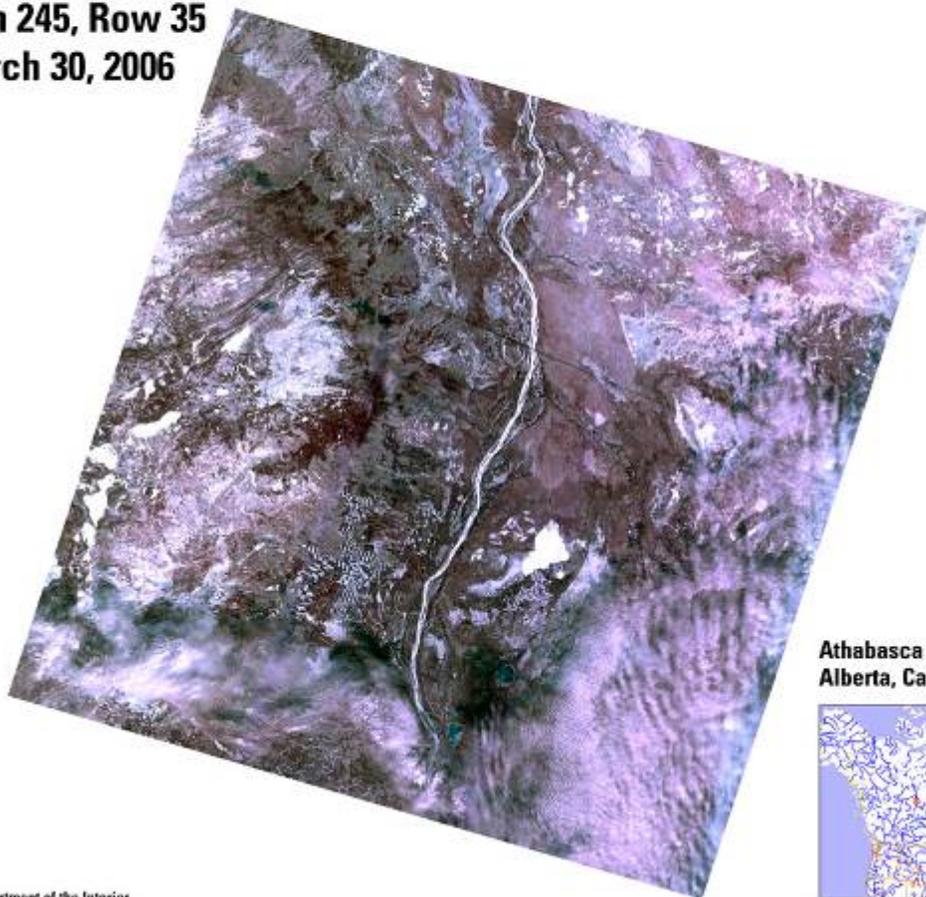


CBERS-2 CCD % difference relative to L5 TM (Band 4)



First CBERS-2 imagery downlinked to USGS EROS

Path 245, Row 35
March 30, 2006

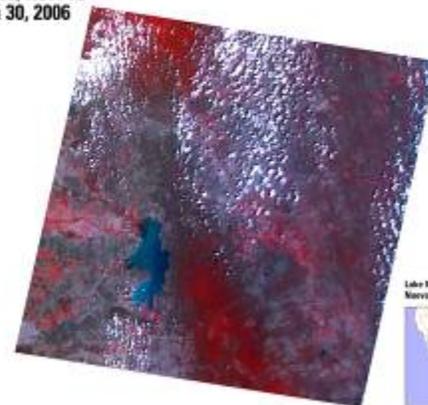


**Athabasca River,
Alberta, Canada**



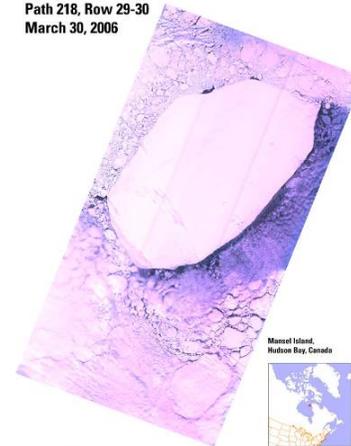
U.S. Department of the Interior
U.S. Geological Survey

CBERS-2 data downlinked to USGS EROS
Path 218, Row 73
March 30, 2006



U.S. Department of the Interior
U.S. Geological Survey

CBERS-2 data downlinked to USGS EROS
Path 218, Row 29-30
March 30, 2006



U.S. Department of the Interior
U.S. Geological Survey

The first China-Brazil Earth Resources Satellite (CBERS-2) data downlink at USGS Center for EROS in support of the Landsat Data Gap Study

The USGS Center for EROS Director, R.J. Thompson, visiting with Jose Bacellar from Brazilian National Institute for Space Research (INPE) after a successful China-Brazil Earth Resources Satellite (CBERS-2) data downlink



- **“CBERS in a box” works - The CBERS-2 capture and processing system is a small computer that can perform the following tasks**
 - ingest the raw data
 - show the image data in a “moving window” display
 - record the raw data in the computer’s hard disk
 - process the raw data to level 1 products
 - generate quick looks to populate the Data Catalog of the system
 - make the level 1 data available to the users

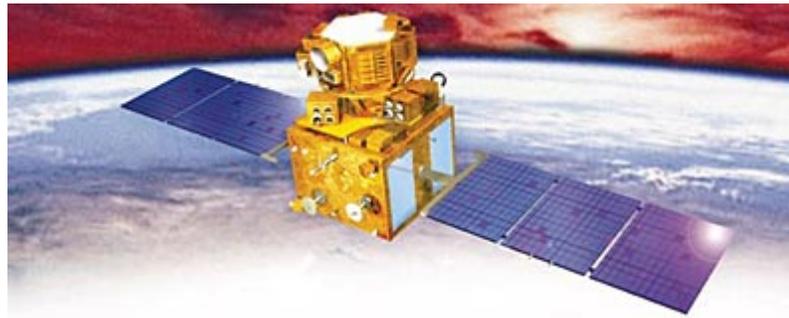
Challenges and Future Plans

- **CBERS-2 High Density Data Recorder (HDDR) is not in use due to power limitations**
- **The IRMSS stopped working in Apr 2005 due to power supply failure**
- **Limited coincident Landsat/CBERS image-pairs**
 - ◆ Limited data distribution policies outside the country
 - ◆ Limited documentation available
 - ◆ No L7 data downlink in Brazil
- **CBERS-2B test downlink at USGS EROS (CBERS cal visit to EROS 2/20/07)**
- **Analyze IRMSS data**
- **Evaluate the raw data (artifacts, noises)**
 - ◆ Evaluate the relative calibration of the CCD data
 - ◆ Evaluate Bias estimates
 - ◆ Night time acquisitions
- **Perform similar cross-calibration experiment**
 - ◆ Data processed from INPE
 - ◆ Data processed from CRESDA
 - ◆ Same datasets processed at INPE and CRESDA
 - ◆ Temporal scale (image pairs from 2003-2005)
- **Perform joint field Vicarious calibration campaign**



Overview of the IRS-P6 Sensors

Cross Calibration of the L7 ETM+ and L5 TM with the IRS-P6 AWiFS and LISS-III Sensors



Resourcesat-1 (IRS P6)

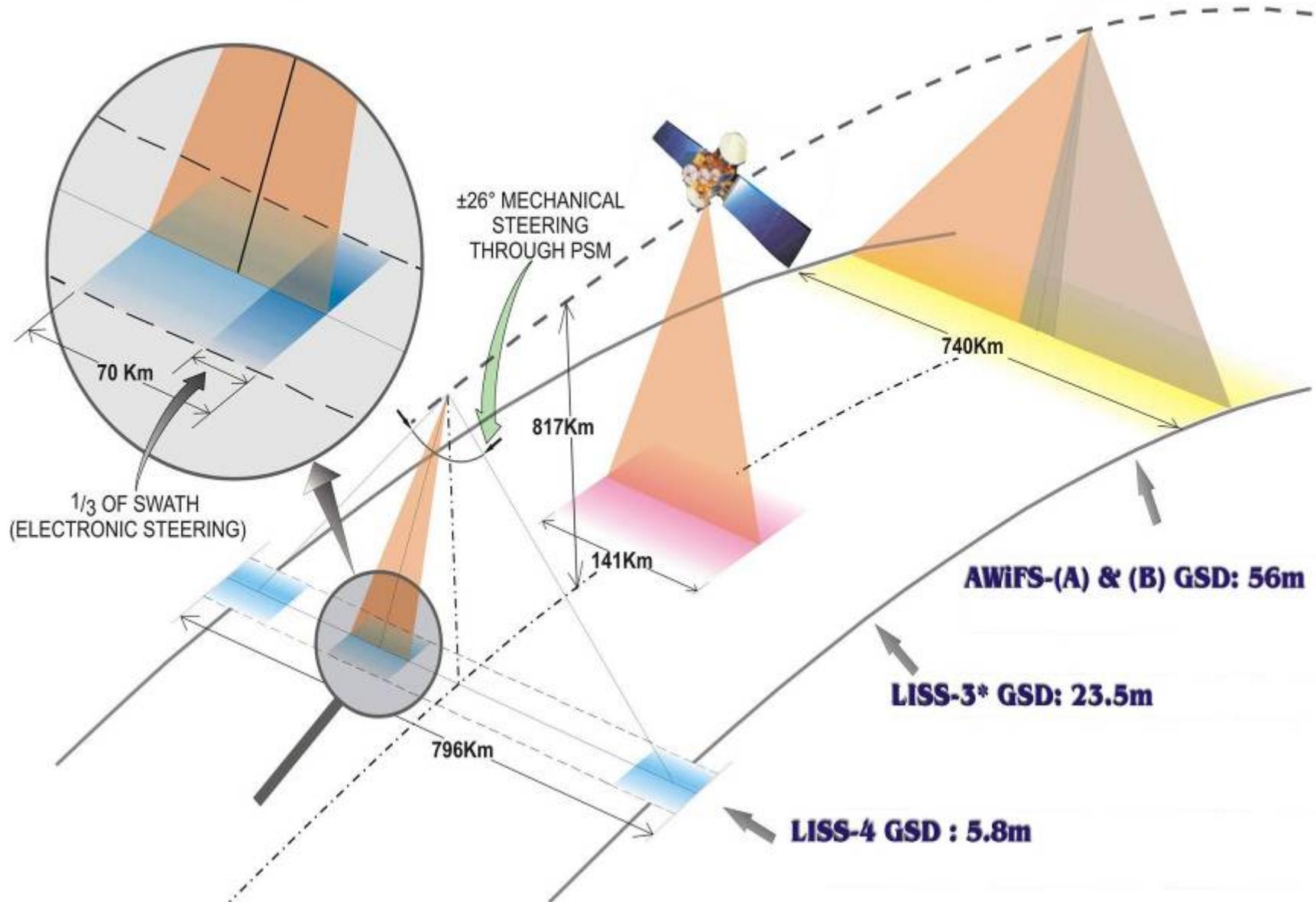
- The RESOURCESAT-1 satellite was launched in to the polar sun-synchronous orbit (altitude of 817 km) by PSLV-C5 launch vehicle on October 17, 2003 with a design life of 5 years
- RESOURCESAT-1 is also called IRS-P6
 - ◆ Most advanced Remote Sensing Satellite built by ISRO
 - ◆ Tenth satellite of ISRO in IRS series
 - ◆ Other ISRO operational satellites are IRS 1-C, IRS 1-D, IRS P-2, IRS P-3

Resourcesat-1 Orbit and Coverage Details	
Orbit Altitude	817 Km
Orbit Inclination	98.69 deg
Orbit period	101.35 min
Number of Orbits per day	14.2083
Equatorial crossing time	10.30 a.m.
Repetivity (LISS-3)	24 days
Repetivity (LISS-4)	5 days
Distance between adjacent paths	117.5 km
Distance between successive ground tracks	2,820 km
Lift-off Mass	1360 kg
Ground trace velocity	6.65 km/sec
Orbits/cycle	341
Semi major axis	7195.11
Eccentricity	0.001
Mission Life	5 years

ResourceSat-1 Overview

- **RESOURCESAT-1 carries three sensors**
 - ◆ High Resolution Linear Imaging Self-Scanner (**LISS-IV**)
 - ◆ Medium Resolution Linear Imaging Self-Scanner (**LISS-III**)
 - ◆ Advanced Wide Field Sensor (**AWiFS**)
- **All three cameras are “push broom” scanners using linear arrays of CCDs**
- **RESOURCESAT-1 also carries an On-board Solid State Recorder (OBSSR) with a capacity of 120 Giga-Bits to store the images**

IRS-P6 THREE TIER IMAGING



Advanced Wide Field Sensor (AWiFS)

- The AWiFS with twin cameras is a moderate-resolution sensor offering a GSD of 56m at nadir
- Quantization: 10 bits
- Combined ground swath is 740km with five day repeat cycle
- Operates in four spectral bands – three VNIR one SWIR

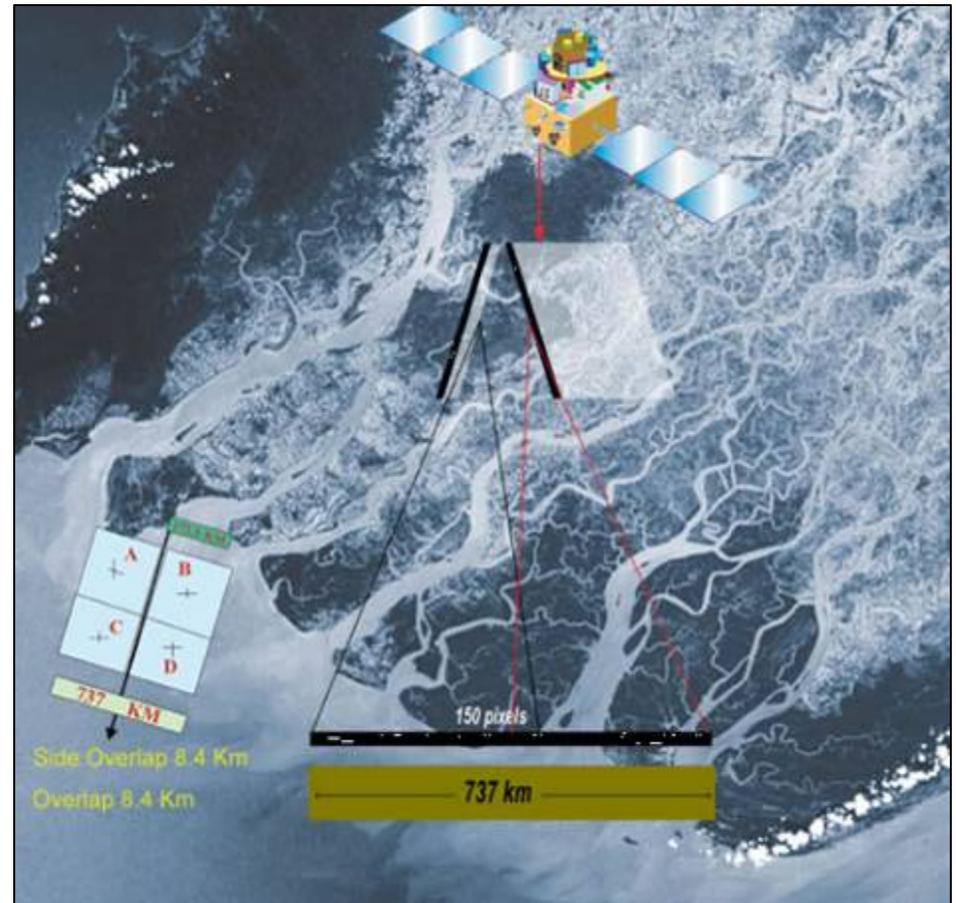
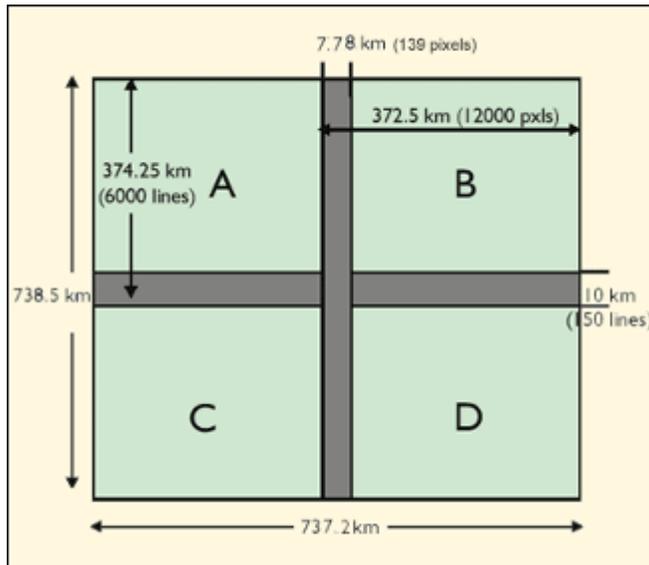
VITAL FACTS:

- Instrument: Pushbroom
- Bands (4): 0.52-0.59, 0.62-0.68, 0.77-0.86, 1.55-1.70 μm
- Spatial Resolution: 56 m (near nadir), 70 m (near edge)
- Radiometric Resolution: 10 bit
- Swath: 740 km
- Repeat Time: 5 days
- Design Life: 5 years



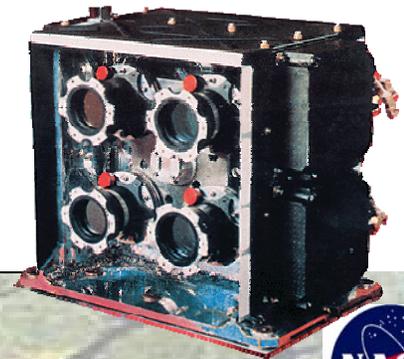
AWiFS Sensor Collection Mode

The AWiFS camera is split into two separate electro-optic modules (AWiFS-A and AWiFS-B) tilted by 11.94 degrees with respect to nadir



Medium Resolution Linear Imaging Self-Scanner (LISS-III)

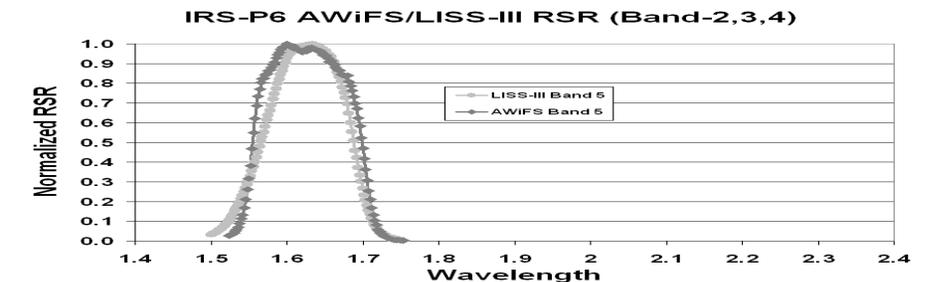
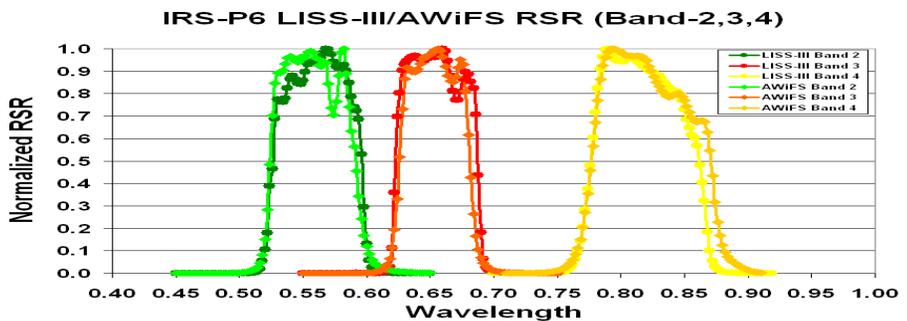
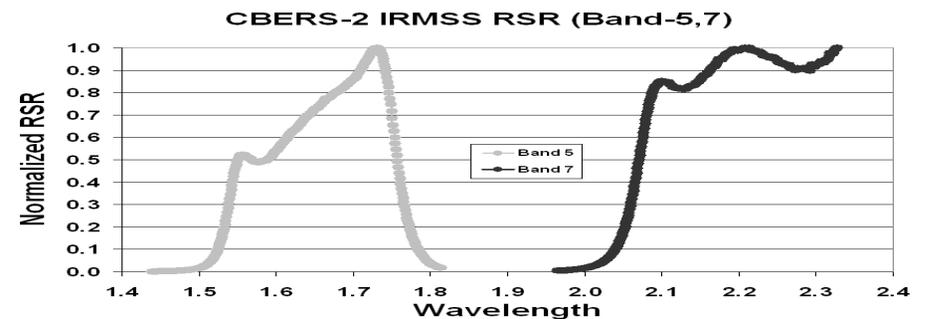
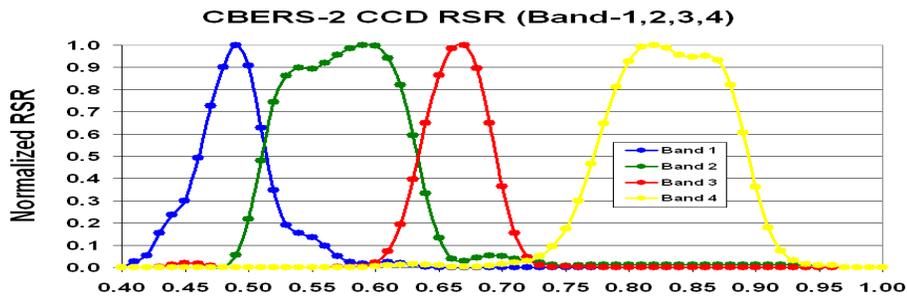
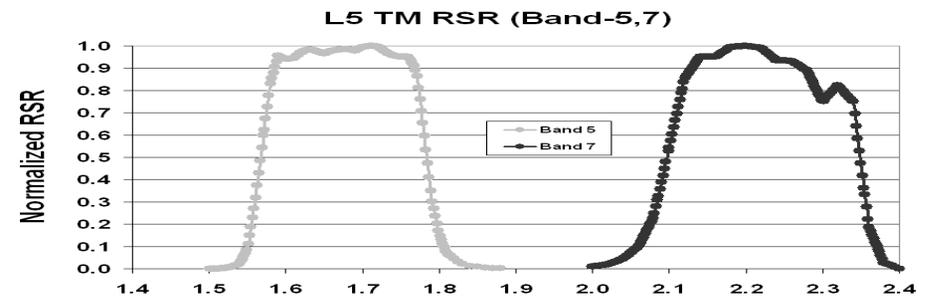
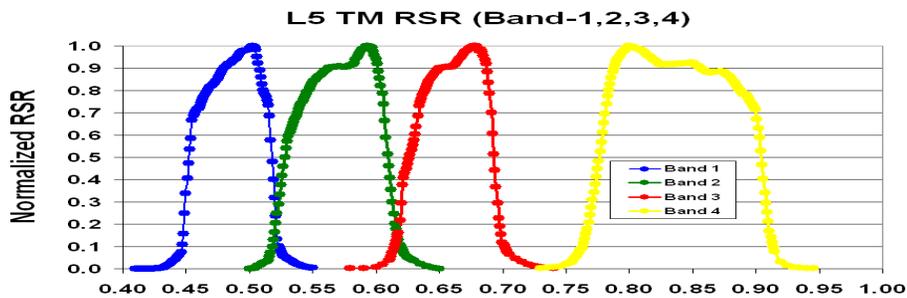
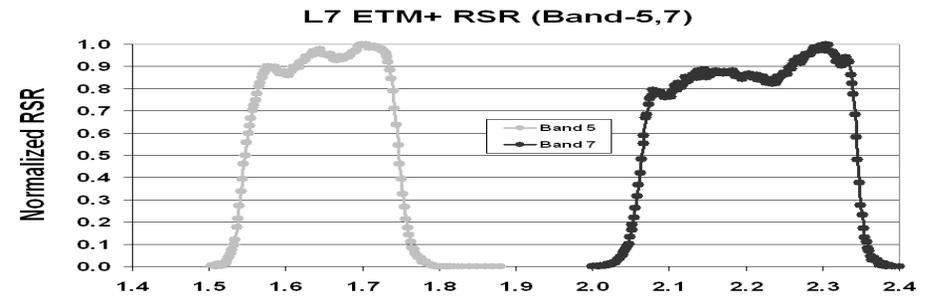
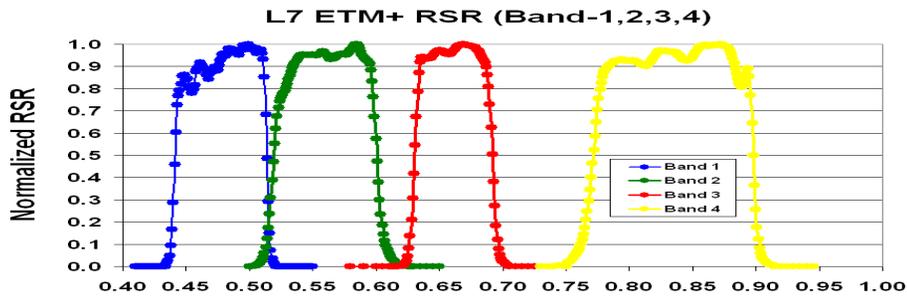
- The LISS-III is a medium resolution sensor offering a GSD of 23.5m
- Quantization: 7 bits (SWIR band 10 bits – selected 7 transmitted)
- Ground swath is 141 km with 24 day repeat cycle
- Operates in four spectral bands - three VNIR one SWIR
- Each band consists of a separate lens assembly & linear array CCD
 - ◆ The VNIR bands use a 6000 element CCD with pixel size 10x7 microns
 - ◆ The SWIR band uses a 6000 element CCD with pixel size 13x13 microns
 - ◆ The data from the VNIR bands are digitized to 7 bits while the data from SWIR band are digitized to 10 bit
 - ◆ The VNIR bands could be operated in any one of the four selectable gains by command, while the SWIR band is configured with single gain setting covering the full dynamic range



IRS-P6 Sensor Specifications

Resourcesat-1 Specifications			
	LISS IV	LISS III	AWiFS
Resolution (m)	5.8	23.5	56
Swath (km)	23.9 km (Mx)	141km	740 km
Spectral Bands (µm)	B2: 0.52-0.59	B2: 0.52-0.59	B2: 0.52-0.59
	B3: 0.62-0.68	B3: 0.62-0.68	B3: 0.62-0.68
	B4: 0.77-0.86	B4: 0.77-0.86	B4: 0.77-0.86
		B5: 1.55-1.70	B5: 1.55-1.70
Quantization (bits)	7	7	10
Integration Time (msec)	0.877714	3.32	9.96
No. of gains	Single gain	Four for B2,3,4	Single gain
Sensor	Pushbroom	Pushbroom	Pushbroom
CCD Arrays	1 * 12288	1 * 6000	2 * 6000
CCD Size (µm)	7 µm x 7 µm	10 µm x 7 µm	10 µm x 7 µm
Focal Length (mm)	982	347.5	139.5
Cross-track FOV for pixel (radian)	0.0000071	0.0000288	0.0000717
Power (W)	216	70	114
Weight (kg)	169.5	106.1	103.6
Data Rate (MBPS)	105	52.5	52.5
Repeat Cycle (days)	5	24	5

Relative Spectral Response (RSR) Profiles



Conversion to Radiance

$$L^* = \frac{(L_{\max} - L_{\min}) Q_{\text{cal}}}{Q_{\text{calmax}}} + L_{\min}$$

Where

- **L^* = spectral radiance at the sensors aperture $W/(m^2 \cdot sr \cdot \mu m)$**
- **Q_{cal} = Calibrated Digital Number**
- **Q_{calmax} = maximum possible DN value**
 - ◆ 255 for LISS-IV & LISS-III products,
 - ◆ 1023 for 10-bit AWiFS and 255 for 8-bit AWiFS products
- **L_{\max} & L_{\min} = scaled spectral radiance (provided in the header file)**
 - ◆ For GeoTIFF products, these values are found in the Image Description field of the GeoTIFF header
 - ◆ For Fast Format products, values are in the HEADER.DAT
 - ◆ For LGSOWG products, values are in the leader file

Header File Information (Lmax & Lmin)

LISS-IV Mono Band 3:

On board gain number for band 3 3
Minimum / maximum radiance for band 3 [mw/cm2/str/um] ... 0.00000 9.92230

LISS-III:

On board gain number for band 2 3
On board gain number for band 3 3
On board gain number for band 4 3
On board gain number for band 5 2
Minimum / maximum radiance for band 2 [mw/cm2/str/um] ... 0.00000 12.06400
Minimum / maximum radiance for band 3 [mw/cm2/str/um] ... 0.00000 15.13100
Minimum / maximum radiance for band 4 [mw/cm2/str/um] ... 0.00000 15.75700
Minimum / maximum radiance for band 5 [mw/cm2/str/um] ... 0.00000 3.39700

AWiFS-A camera (A&C quadrant scenes):

On board gain number for band 2 8
On board gain number for band 3 9
On board gain number for band 4 8
On board gain number for band 5 9
Minimum / maximum radiance for band 2 [mw/cm2/str/um] ... 0.00000 52.34000
Minimum / maximum radiance for band 3 [mw/cm2/str/um] ... 0.00000 40.75000
Minimum / maximum radiance for band 4 [mw/cm2/str/um] ... 0.00000 28.42500
Minimum / maximum radiance for band 5 [mw/cm2/str/um] ... 0.00000 4.64500

AWiFS-B camera (B&D quadrant scenes):

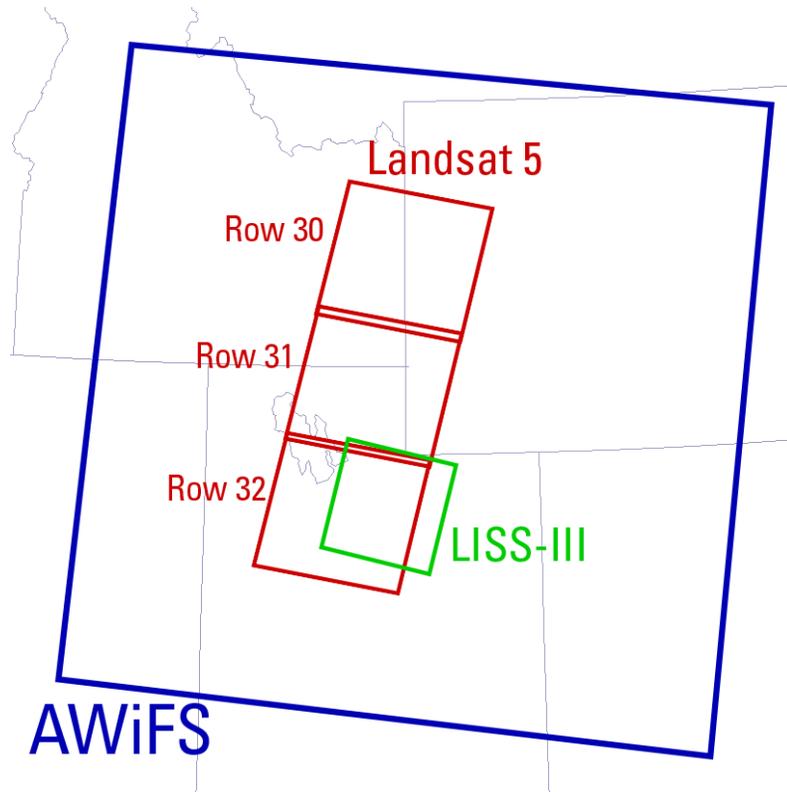
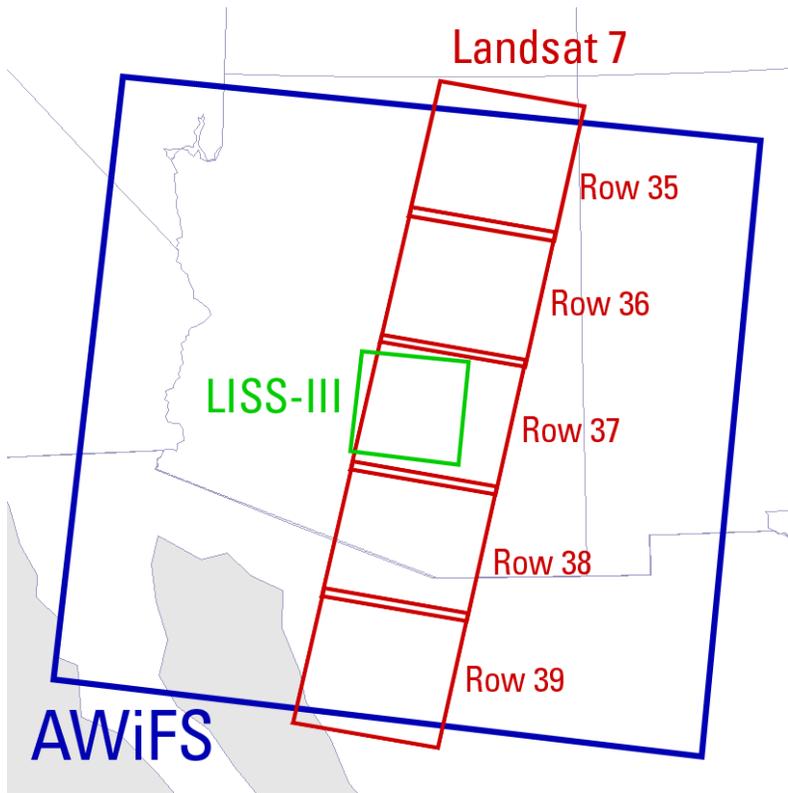
On board gain number for band 2 8
On board gain number for band 3 9
On board gain number for band 4 8
On board gain number for band 5 9
Minimum / maximum radiance for band 2 [mw/cm2/str/um] ... 0.00000 52.34000
Minimum / maximum radiance for band 3 [mw/cm2/str/um] ... 0.00000 40.75000
Minimum / maximum radiance for band 4 [mw/cm2/str/um] ... 0.00000 28.42500
Minimum / maximum radiance for band 5 [mw/cm2/str/um] ... 0.00000 4.64500



Cross-Calibration Methodology

- **Co-incident image pairs from the two sensors were compared**
- **The cross-cal was performed using image statistics from large common areas observed by the two sensors**
 - ◆ Define Regions of Interest over identical homogenous regions
 - ◆ Calculate the mean and standard deviation of the ROIs
 - ◆ Convert the satellite DN to reflectance
- **Perform a linear fit between the satellites to calculate the cross-calibration gain and bias**

Image boundaries of scenes used



Comparison Scenes Used -- Mesa, AZ

Mesa, Arizona collection, June 29, 2005

Instrument	Product ID	Path	Row	Solar Elevation
Landsat 7 ETM+	L71036035_03520050629	36	35	65.21 °
Landsat 7 ETM+	L71036036_03620050629	36	36	65.53 °
Landsat 7 ETM+	L71036037_03720050629	36	37	65.77 °
Landsat 7 ETM+	L71036038_03820050629	36	38	65.94 °
Landsat 7 ETM+	L71036039_03920050629	36	39	66.02 °
AWiFS Quad A	AW257047A001	257	47	69.50 °
AWiFS Quad B	AW257047B001	257	47	72.60 °
AWiFS Quad C	AW257047C001	257	47	70.30 °
AWiFS Quad D	AW257047D001	257	47	73.60 °
LISS-III	L32570470101	257	47	71.48 °

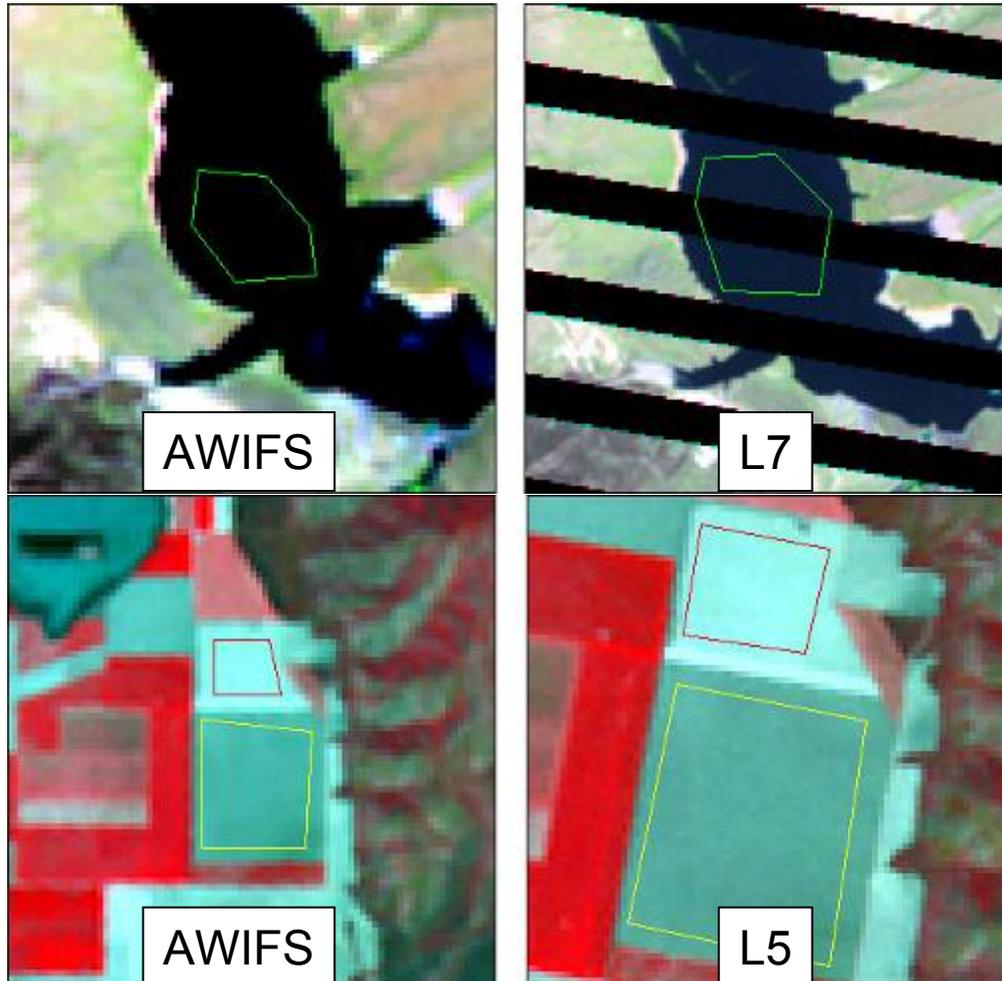
Comparison Scenes Used -- SLC, UT

Salt Lake City, Utah collection, June 19, 2005

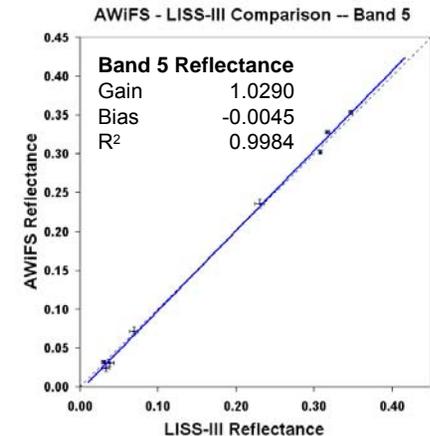
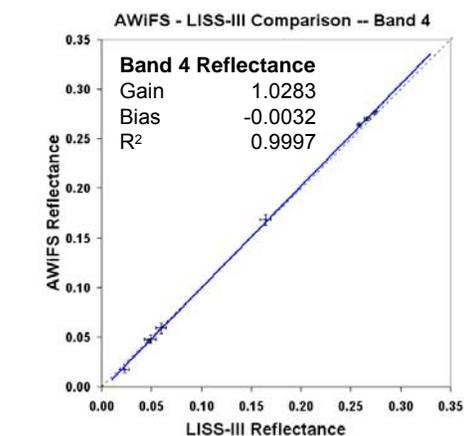
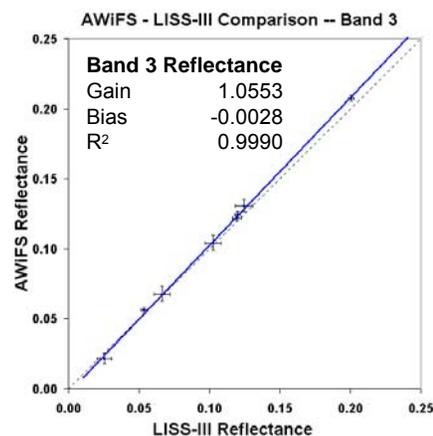
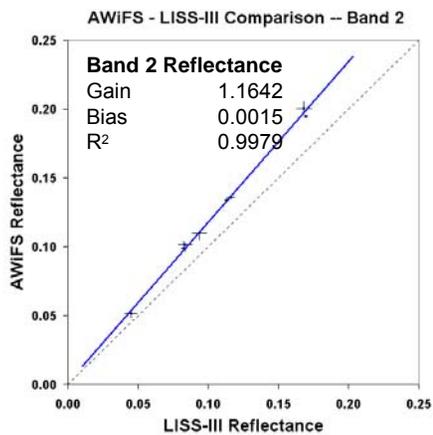
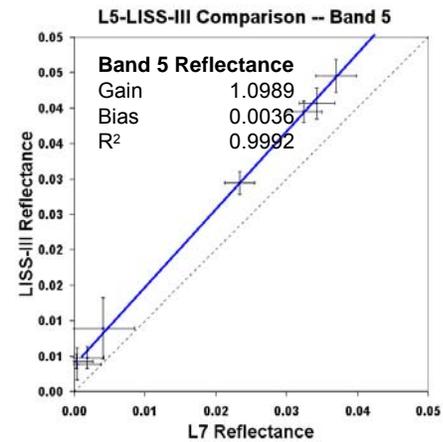
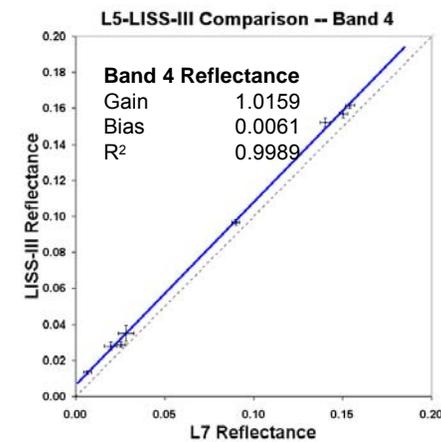
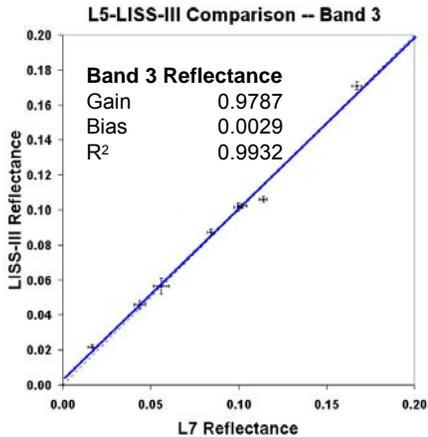
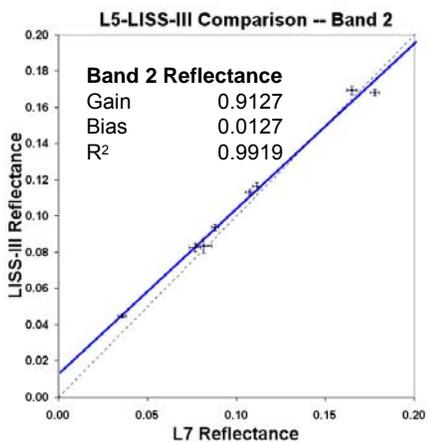
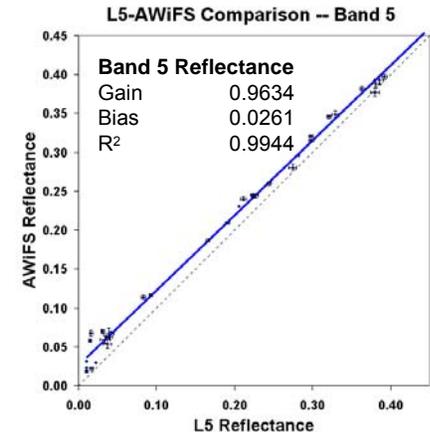
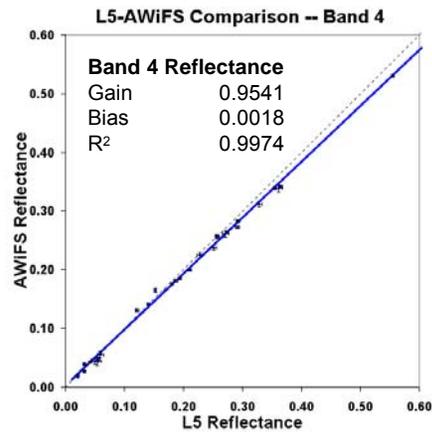
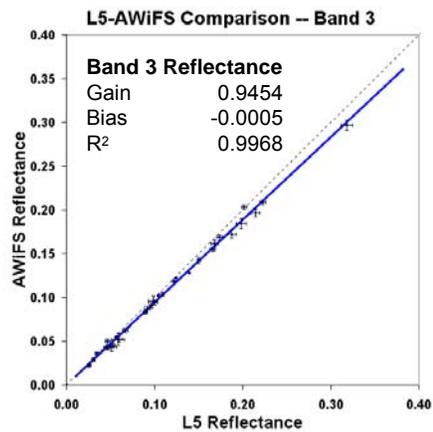
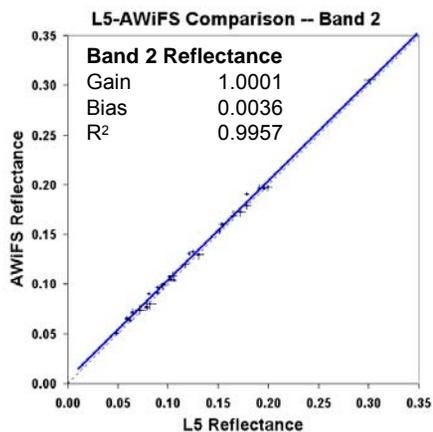
Instrument	Product ID	Path	Row	Solar Elevation
Landsat 5 TM	LT5038030000517010	38	30	62.95 °
Landsat 5 TM	LT5038031000517010	38	31	63.59 °
Landsat 5 TM	LT5038032000517010	38	32	64.18 °
AWiFS Quad A	000010491201	255	40	65.50 °
AWiFS Quad B	000010491301	255	40	68.10 °
AWiFS Quad C	000010491401	255	40	67.50 °
AWiFS Quad D	000010491501	255	40	70.30 °
LISS-III	000010491601	255	41	68.64 °

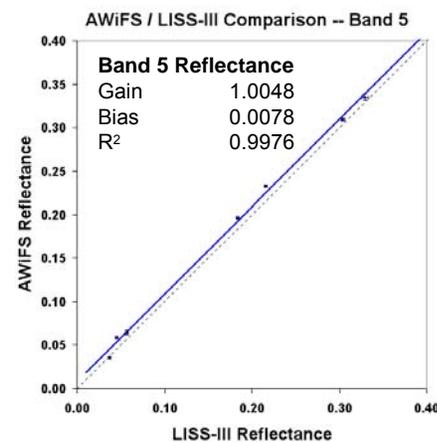
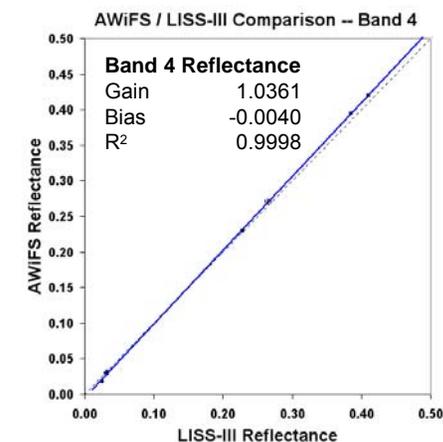
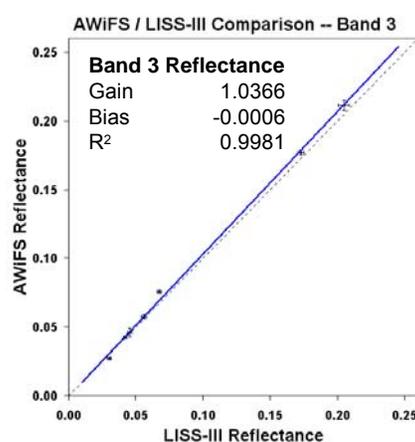
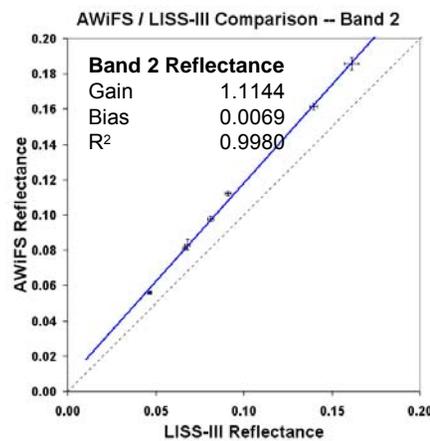
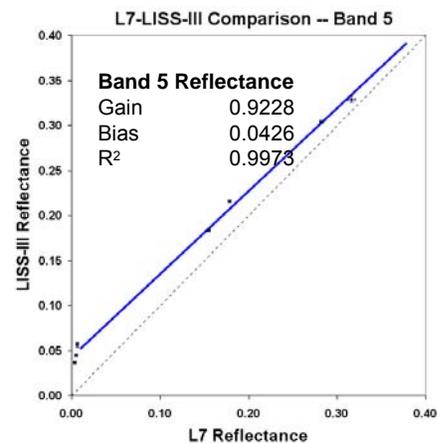
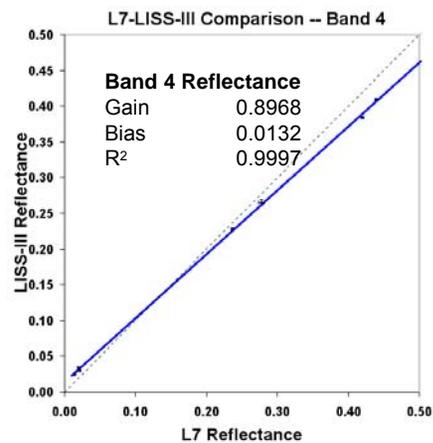
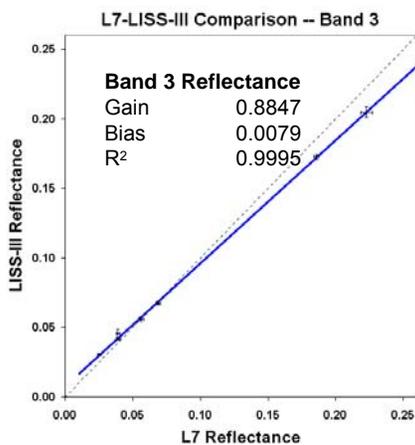
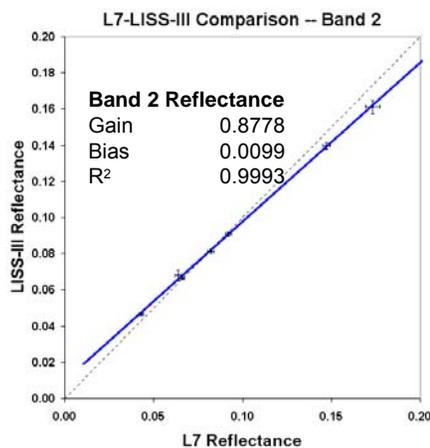
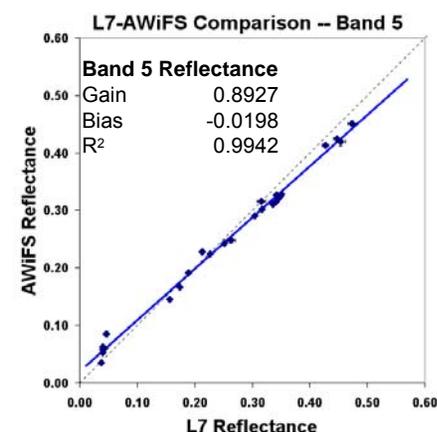
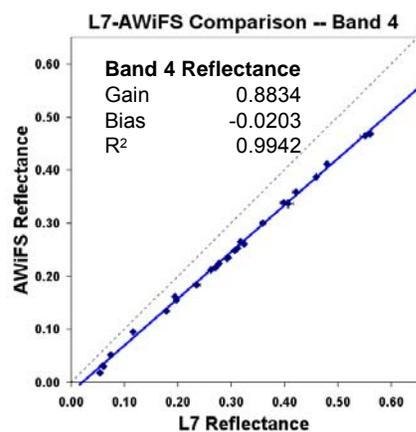
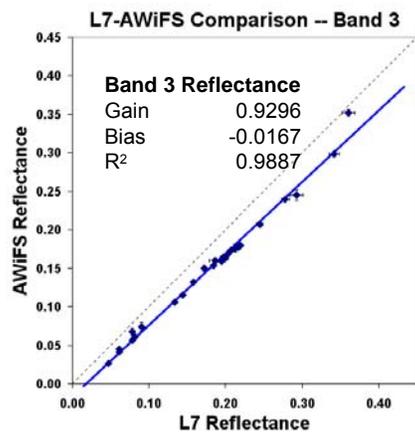
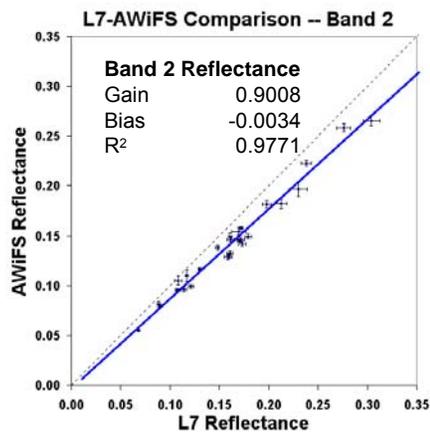


Regions of Interest (ROI)



- ROI were selected in both AWiFS and Landsat data
- Mesa, AZ collection --
 - ◆ Five WRS-2 L7 scenes
 - ◆ 27 ROIs
- SLC, UT collection --
 - ◆ Three WRS-2 L5 scenes
 - ◆ 34 ROIs
- All AWiFS quadrants were represented in both collections
- ROIs were selected over homogenous regions (standard deviation < 10 DN)
- Gaps in L7 data were discarded





Cross-Cal Summary

- An initial cross calibration of the L7 ETM+ and L5 TM with the IRS-P6 AWiFS and LISS-III Sensors was performed
- The approach involved calibration of nearly simultaneous surface observations based on image statistics from areas observed simultaneously by the two sensors
- The results from the cross calibration are summarized in the table below
 - ◆ The IRS-P6 sensors are within 5.5% of each other in all bands except Band 2 (16.4% difference)
 - ◆ Differences due to the Relative Spectral Responses (RSR) were not taken into account
 - ◆ Atmospheric changes between the two image-pairs were not accounted
 - ◆ acquisition time between the two sensors were 30-min apart
 - ◆ Registration problems while selecting the regions of interest (ROI)

Differences between Sensors

	ETM+	TM	AWiFS	LISS-III
ETM+		-	8-12%	8-13%
TM	-		0-6%	2-10%
AWiFS	8-12%	0-6%		1-16%
LISS-III	8-13%	2-10%	1-16%	

Cross-calibration results normalized to the AWiFS sensor

Sensor	Band			
	2	3	4	5
L5	1.00	1.06	1.05	1.04
L7	1.11	1.08	1.13	1.12
AWiFS	1.00	1.00	1.00	1.00
LISS-III (Mesa)	0.90	0.96	0.97	1.00
LISS-III (SLC)	0.86	0.95	0.97	0.97

LDGST Qs

A		B
Questions		Priority
Data Quality (calibration) Questions		1=Primary 2=Secondary
3 Radiometry		
4	How are your data calibrated radiometrically? Please describe the procedures used and provide any documentation?	1
5	Is there any special (Lunar, Solar, Stellar) calibration acquisitions performed?	1
6	How are detector gains determined? (Prelaunch, vicarious, internal calibrator)	1
7	Are the radiometric calibrations and corrections updated over time to reflect sensor changes?	1
8	Have you characterized the linearity and stability of the sensors response? If yes, how?	1
9	What are the known artifacts (such as Striping, noises) in the Instrument?	1
10	How are the artifacts compensated in the L1 products?	1
11	If there are dead or inoperable detectors, how are they compensated for in the Image products?	1
12	How does the system respond to saturation point targets? What is the recovery time? Saturation radiance in products?	1
13	How is detector-to-detector normalization performed to remove striping effects?	1
14	What levels of radiometric calibration/correction are applied to each of your product levels?	1
15	What is the absolute radiometric accuracy? What are these numbers based on?	1
16	How are the detector biases determined? How are biases applied during processing?	1
17	The Spectral Response Profiles that we have seen are incomplete. Do you have complete profiles?	1
18	How is the spectral response determined? Is there variability in spectral response or filter response across the focal plane?	1
19	Has there been any measurement of out-of-band spectral response?	1
20	Have you found any problems with stray light? If so, please describe them and how they were measured.	1
21	What is the Signal-to-noise ratio (SNR)? At what radiance level was this determined?	1
22	Is there any night imaging capability?	1
23	Are the data in Level 1 products linearly scaled to absolute radiance?	2
24	What is the equation used to convert the DN-to-radiance for each of the products?	2
25	Is there any on-board radiometric calibration capability? If yes, please describe?	2
26	What is the Solar Exoatmospheric Spectral Irradiance (ESUN) values used for reflectance conversion?	2
27	What solar spectrum profiles were used to calculate the ESUN values?	2
28	Describe the focal plane layout and detector dimensions?	2
29	What focal length(s) are your sensors?	2
30	What is the aperture diameter for your sensor(s)?	2
31	What types of detectors are used? (material)	2
32	Is the sensor gain adjustable? Are there multiple gain settings?	2
33 Geometry		
34	How are your data calibrated geometrically? Please describe the procedures used and provide any documentation?	1
35	What is the internal geometric stability? (relative geometric accuracy) How has it changed over time?	1
36	What is the absolute geodetic/geopositional accuracy? How has it changed over time?	1
37	What level of geometric calibrations and corrections are performed for each of your data product levels?	1
38	What is the band-to-band registration accuracy?	1
39	What source of ground truth do you use to measure your geometric/geodetic accuracy, including elevation data?	1
40	Do you have any off-nadir capability? If so what is the range?	2
41 Spatial		
42	How are your data characterized and calibrated spatially?	1
43	What measurements do you use? (Edge, FWHM line spread, MTF at Nyquist)	1
44	What is the sensor spatial response? How was it determined?	1
45	How is the spatial response (MTF) monitored on orbit? How has it changed over time?	1
46	Is there spatial compensation (MTF) performed on data products? If so, please describe the algorithms and effects.	1
47 Operational Questions		
48 Image scheduling		
49	Do you have an overall plan to acquire data regionally/globally? If so, please describe it.	1
50	What is the image request process from submission to competition?	1
51	How are the instruments scheduled?	1
52	Are images collected on the basis of on-demand tasking?	1
53	How are imaging priorities determined?	1
54	What is the maximum amount of data that can be collected and received from your sensors?	1
55	What is the typical amount of data received at present?	1
56	What factors limit the amount of data that can be collected and received?	1
57	We would like to know the factors that affect imaging capabilities and capacities.	1
58	How quickly can the organization respond to emergencies?	1

A		B
59	Do you have internal plans to monitor disasters?	1
60	What is the longest continuous imaging swath that a sensor can collect?	1
61	Are there any geographical constraints to imaging anywhere around the world?	1
62	How precisely is your equatorial crossing time maintained?	1
63	How precisely is your ground track maintained?	1
64	What is the designed (and projected) life of the satellite?	1
65	What are the follow-on missions?	1
66	Can all of your sensors collect imagery simultaneously?	2
67	Can you provide the acquisition calendar for the satellites?	2
68	Can we get the image shape files? (ability to locate where a path/row will be)	2
69 Ground receiving stations, On-board data storage and transmission		
70	How are data transmitted to the ground and to the central archive/processing centers?	1
71	Can you store data and transmit data simultaneously?	1
72	Do you compress the data on-board? If so, lossless or loss compression?	1
73	Where are the ground receiving stations located?	2
74	What are the receiving antenna requirements?	2
75	What types of antennae are on board? (Omni-directional or spot?)	2
76	What are the data transmission rates and frequencies?	2
77	Can data be transmitted to more than one receiving station simultaneously?	2
78	Is there an on-board data recorder? If so, what is the capacity?	2
79 Data production and distribution		
80	How are data processed and distributed?	1
81	Are there more than one processing/distribution sites?	1
82	Can we get a raw (LDRp) product?	1
83	Do you have a "default" processing level or configuration (resampling, projections, datum, etc.)?	1
84	Are the products produced at variable lengths, i.e. multiple scenes in length?	1
85	Is there any data compression applied to the output products? If so, what method is used?	1
86	What is the turn around time between imaging and the availability of the products?	1
87	Are the raw data archived? If so, who is responsible for the archive? How long are data held? What is the data storage media?	1
88	What, if any, differences are there in the processing systems used at different IGS?	1
89	What are the various product levels that are available?	2
90	Are the products produced in different quantization levels (i.e. 8-bit, 10-bit, etc)? If so, what options are produced?	2





Landsat Data Gap Studies: Summary

U.S. Department of the Interior
U.S. Geological Survey





**NASA/USGS LDSGT technical group
with Dr. Navalgund, the director of
ISRO SAC, Ahmedabad, India**

**NASA/USGS LDSGT
technical group at IRSO HQ
in Bangalore, India**

June 10-20, 2006





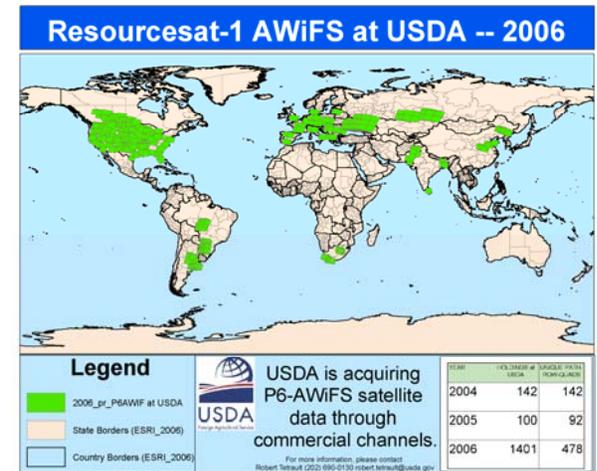
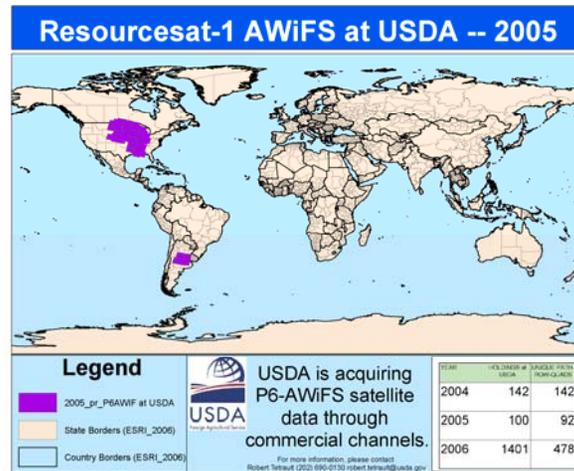
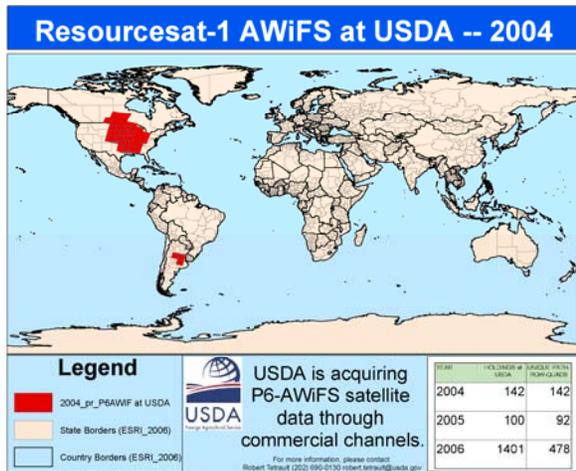
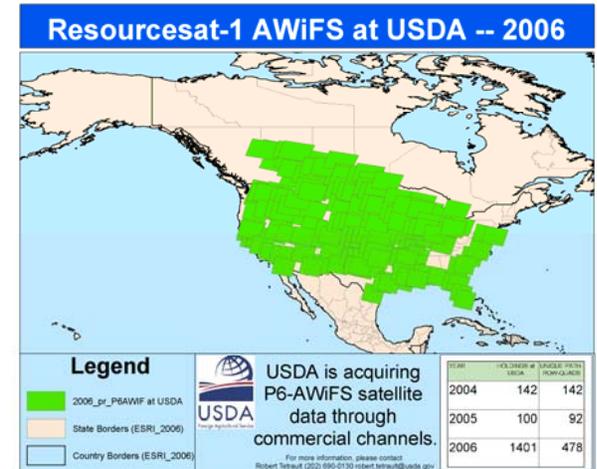
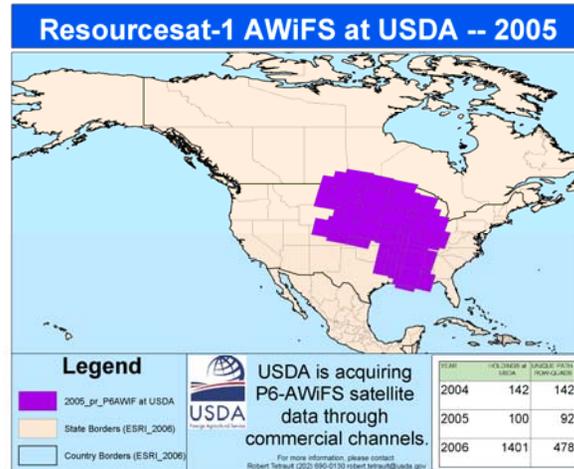
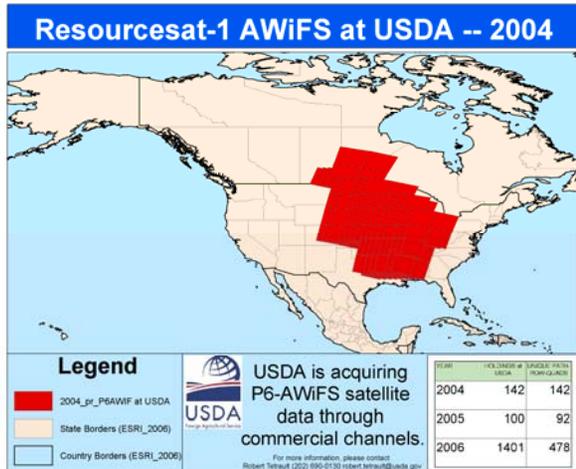
NASA/USGS technical group with Dr. Camara, the director of INPE, Brazil



USGS Deputy Director and NASA Program Executive with INPE Director

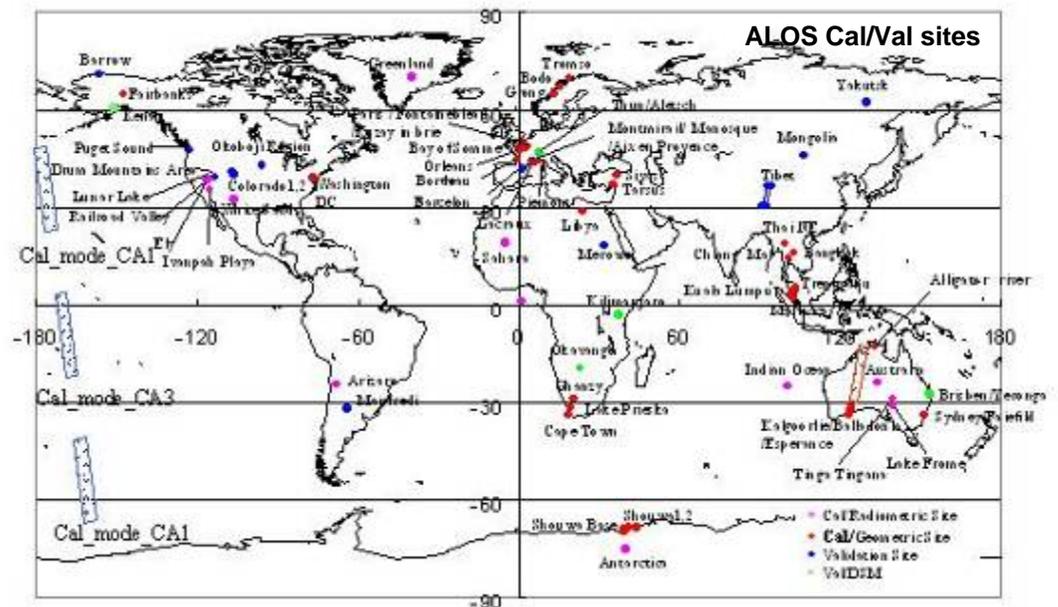
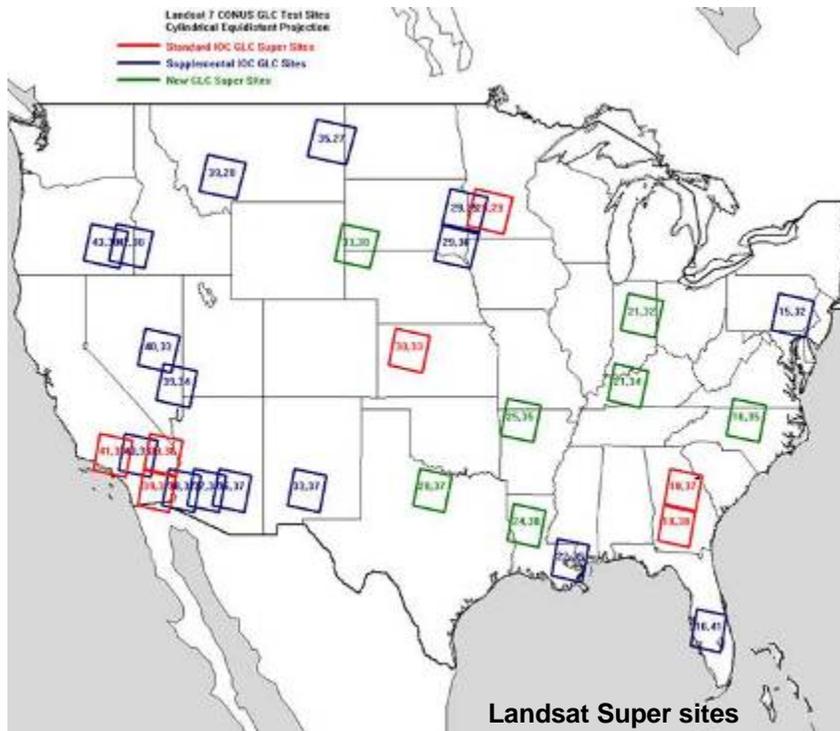


AWiFS USDA Data Holdings



CEOS Calibration-Validation Sites

- **World-wide Cal/Val Sites for**
 - ◆ Monitoring various sensors
 - ◆ Cross calibration
 - ◆ Integrated science applications
- **Prime Sites for data collection**
 - ◆ Site description
 - ◆ Surface Measurements
 - ◆ FTP access via Cal/Val portals



USGS Recommendations to CEOS

- **Coordinate and provide world-wide Cal/Val sites**
 - ◆ Coordinate and provide ground control points
 - ◆ Coordinate and plan vicarious calibration field campaigns
- **Maintain a fully accessible Cal/Val portal to provide**
 - ◆ instrument characteristics of current & future systems,
 - ◆ seamless access of Cal/Val site data for users
 - ◆ database of in-situ data, documentation of best practices
 - ◆ Info regarding co-incident imagery
- **Reinvigorate IVOS subgroup**
 - ◆ Workshop at ESA ESTEC (2004) was a great success!
 - ◆ Coordinate and schedule regular communication between IVOS subgroup members
 - ◆ Members provide monthly Cal/Val Status on action items
- **Update CEOS WGCV IVOS web pages with membership information, IVOS presentations, and technical links**

On-going Cross-cal work at USGS

- L7 ETM+ and L5 TM sensor
- L5 TM and L4 TM sensor
- L7 ETM+ (L5 TM) and EO-1 ALI sensor
- L7 ETM+ (L5 TM) and Terra MODIS and ASTER sensors
- L7 ETM+ (L5 TM) and CBERS-2 CCD sensor
- L7 ETM+ (L5 TM) and IRS-P6 AWiFS and LISS-III sensor
- L7 ETM+ (L5 TM) and ALOS AVNIR-2 sensor
- L7 ETM+ (L5 TM) and DMC SurreySat

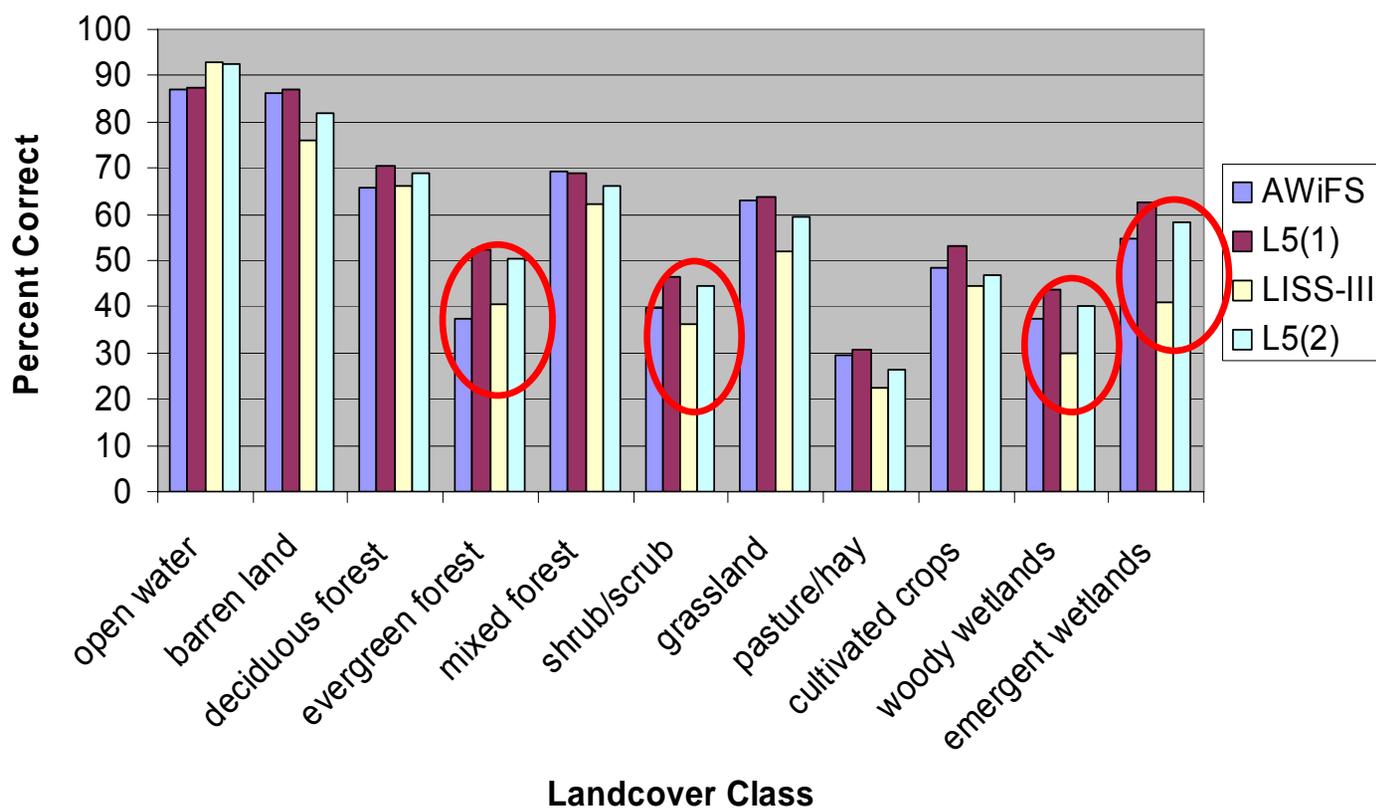
Joint Agency Commercial Imagery Evaluation (JACIE) Team

- JACIE team formed in 2000 - NASA, NGA, USGS (added USDA this year!)
- USGS is chair of JACIE; preparing to host 6th Annual Conference on March 20-22, 2007 in Fairfax, VA
- <http://www.usm.edu/ncpc/jacie/index.html>
- Demonstrate relevance of JACIE to US role in terrestrial monitoring
- Enhanced scope to Satellite & Aerial sensors useful to the remote sensing community – U.S. and International systems
- Provide imagery users with an independent assessment with respect to product quality and usability
- Support new applications and understanding of remotely sensed data
- Provides government/industry communication/cooperation model



NLCD Viability Sample test - Salt Lake Land Cover, AWiFS, LISS-III & L5 Combined - 2006

**Landcover Classification Tests -
Percent Correctly Classified, Per Class**



Landsat 5 was markedly better than AWiFS/LISS-III with these classes: evergreen, shrub/scrub, woody wetlands, emergent wetlands.

Landcover class differences most likely due to lack of Bands 1&7 on IRS-P6.

AWiFS temporal benefits are exceptional.

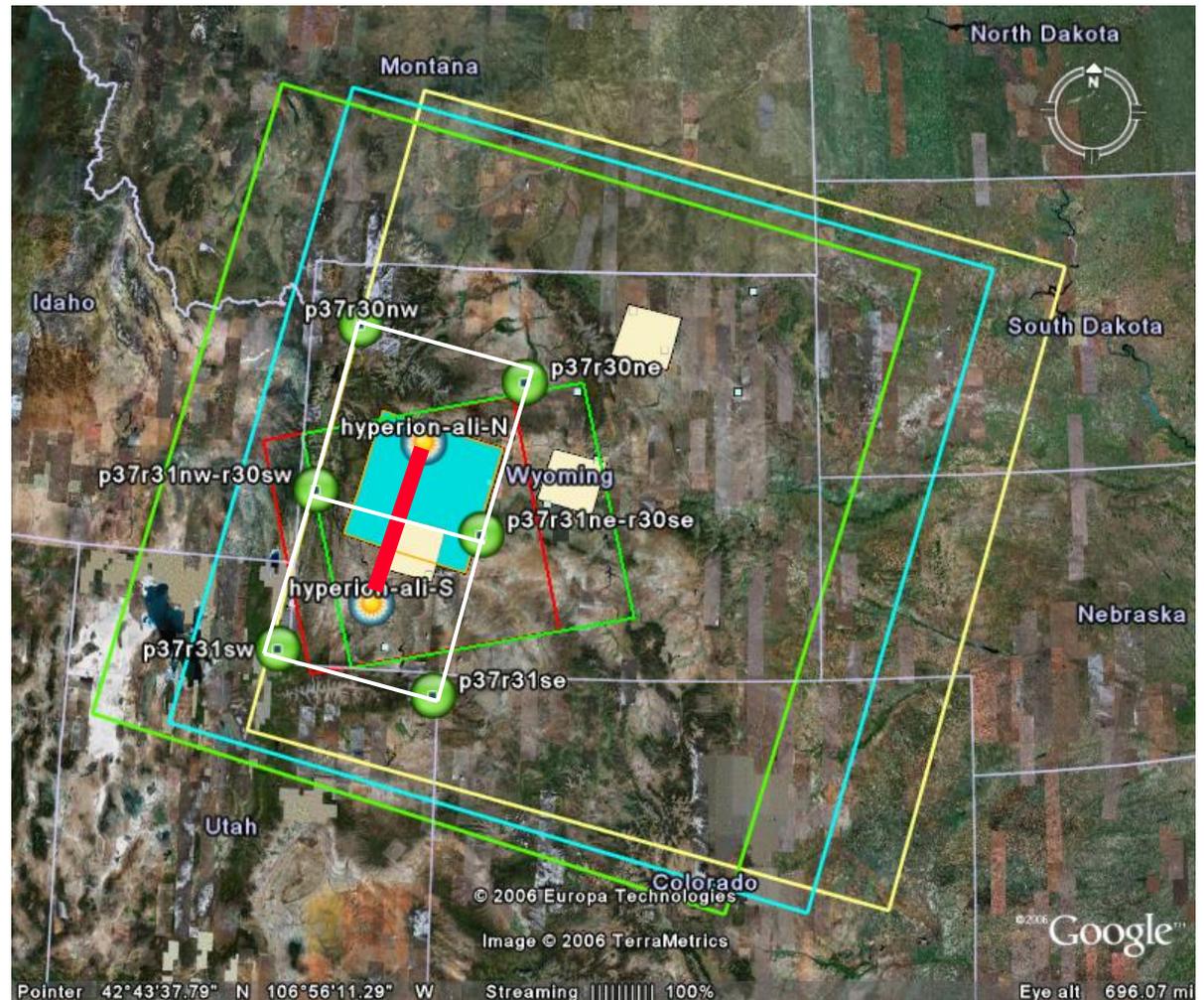
Experimental results w/limited data - **more testing required!**

Multiple Satellites Used in Science

- **2006 Data included:**

- ◆ Landsat-5
- ◆ Landsat-7
- ◆ EO-1 ALI
- ◆ EO-1 Hyperion
- ◆ ASTER
- ◆ IRS AWiFS
- ◆ IRS LISS-III
- ◆ Surrey DMC
- ◆ DG Quickbird

- **To support Sagebrush study in Wyoming, USA**

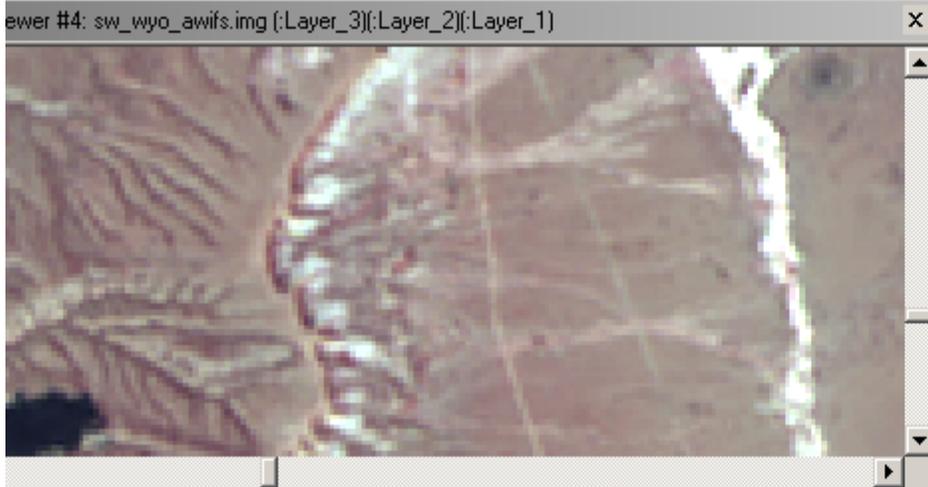


The result is three scales of models, grounded to field measurements

Quickbird (2.4m)



Landsat TM (30m)



IRS AWIFS (56m)

Viewer #5

Proposed products include models of
% shrub, % sagebrush,
% herbaceous, % bare ground, % litter,
shrub height, and % shrub species

LDGST Information Resources

- **Briefing Slides – current presentation**
- **DCWG Slides – available**
- **DMC Report – bring finalized for JACIE**
- **ResourceSat report – technical report completed, waiting for combined report – est. availability Feb 07**
- **CBERS report - technical report completed, waiting for combined report – est. availability Feb 07**
- **LDGST Qs Answers**
- **ISRO trip report - complete**
- **INPE trip report – being finalized**

Characterization & Data Gap Summary

- There are many instruments providing image data for civil science purposes
 - ◆ GEOSS, GEO, CEOS, Future of Land Imaging Team, LDGST
- Some instruments may be able to meet at least some of the Landsat user community needs
- Technical advances have enabled the creation of many multi-spectral satellites
 - ◆ 20+ countries medium to high resolution satellites and 66 Civil Land Imaging Satellites by 2010
- All the data has value but it needs to be well understood
 - ◆ Calibration/Validation required
 - ◆ Stable base mission (LANDSAT/LDCM) with cross band coverage
- **USGS continues to assess Landsat Data Gap mission and future technologies**
 - ◆ **USGS is interested in datasets for assessment purposes, please contact USGS if interested**
- Precise high resolution data provides a great compliment to global science assessment and is a must for ER

LDGST Summary

- **There is no substitute for Landsat**
 - ◆ Single source of systematic, global land observations
 - ◆ Alternate sources may reduce the impact of a Landsat data gap
- **We are characterizing multiple systems to understand which data sets may be compatible with the Landsat data record and can potentially supplement the Landsat data archive, but no decisions have been made yet**
- **Landsat Data Gap Study Team will:**
 - ◆ Finalize recommendations and strategy for implementation
 - ◆ Present findings to U.S. civil agency management and the White House Office of Space and Technology Policy
 - ◆ Implement recommendations