

# The Landsat Data Continuity Mission

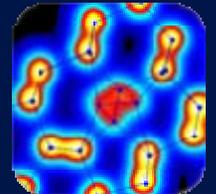
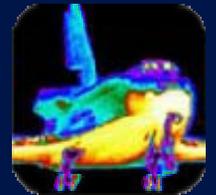


AN INCREASED POTENTIAL FOR THE LANDSAT  
DATA CONTINUITY MISSION TO  
CONTRIBUTE TO WATER QUALITY STUDIES FOR  
INLAND, CASE 2 WATERS

Aaron Gerace  
John R. Schott

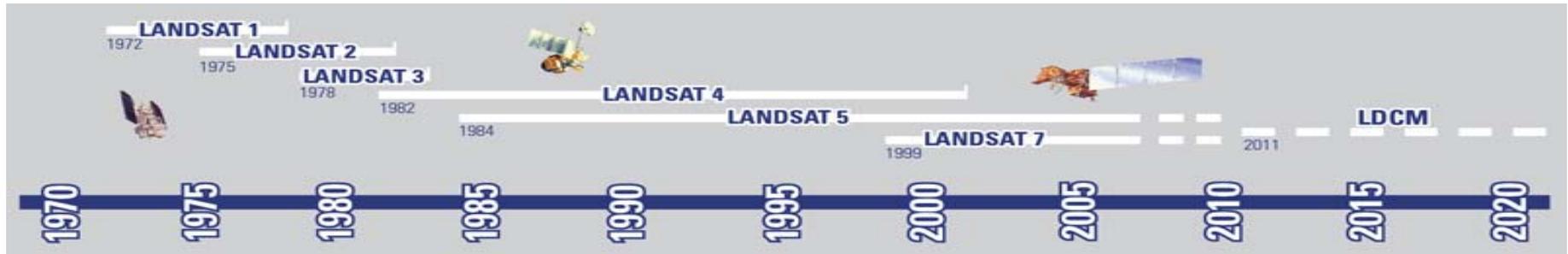
Sponsored  
by  
United States Geological Survey

Digital Imaging and  
Remote Sensing Laboratory

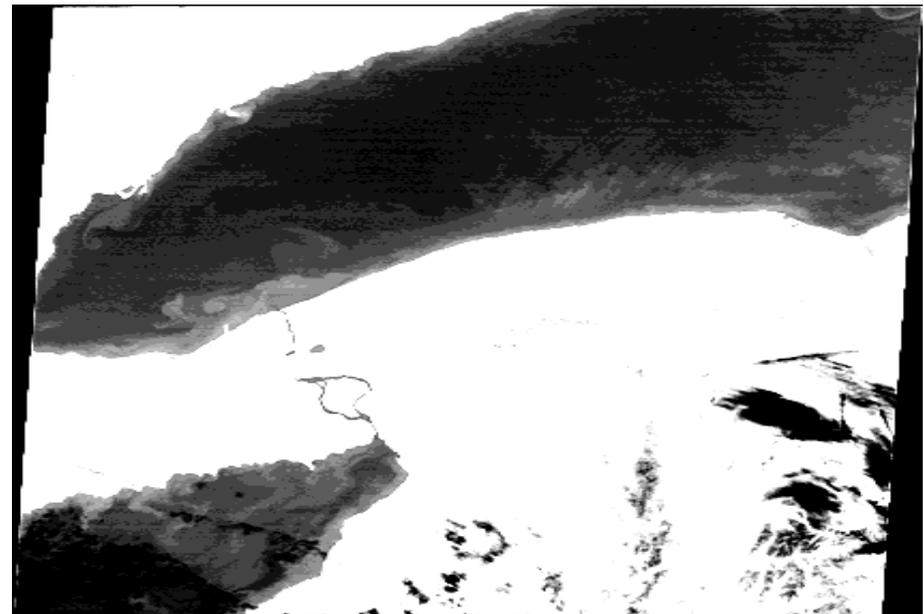


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# The Landsat Data Continuity Mission



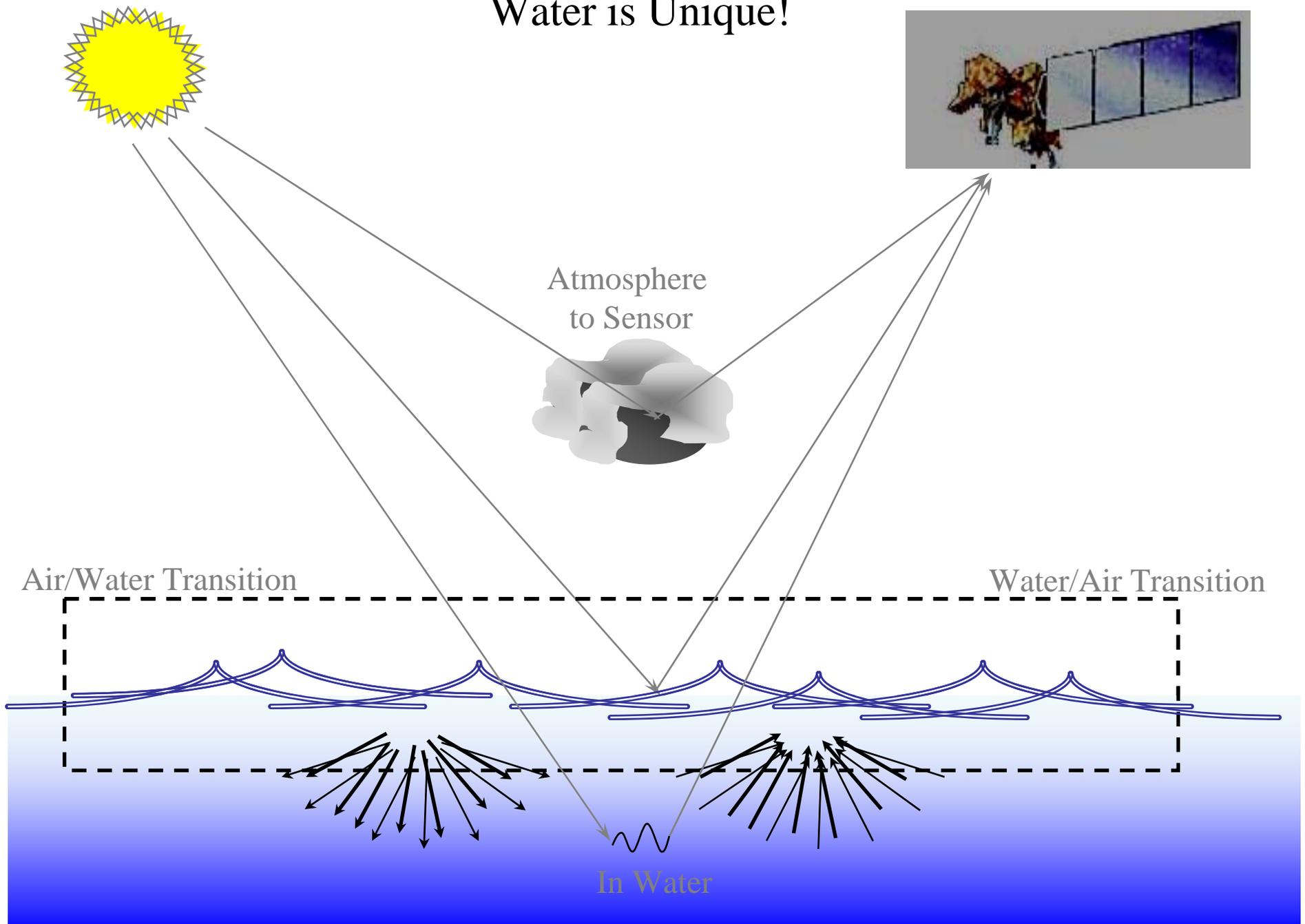
**True Color Composite**



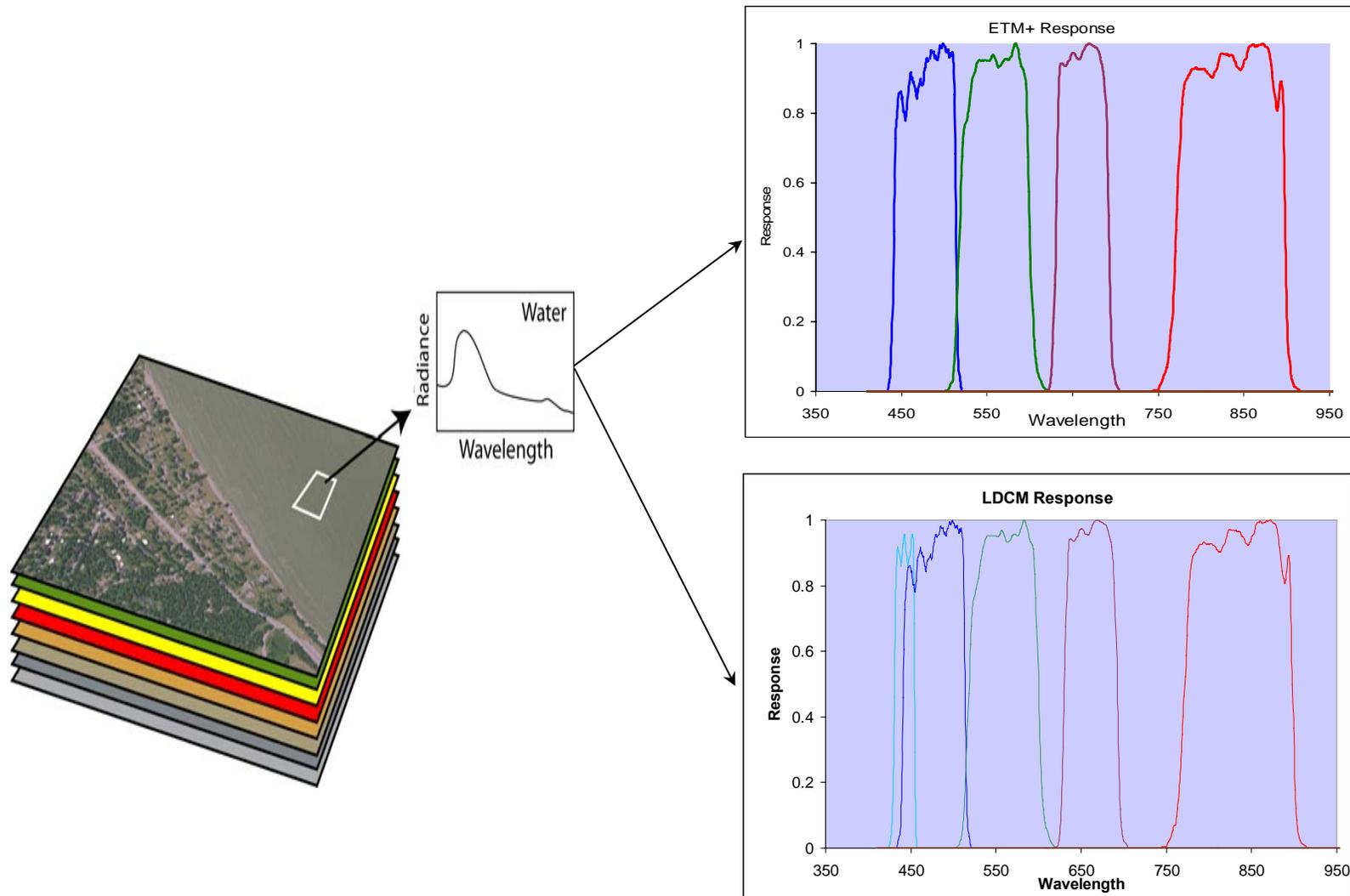
**Thermal Channel**



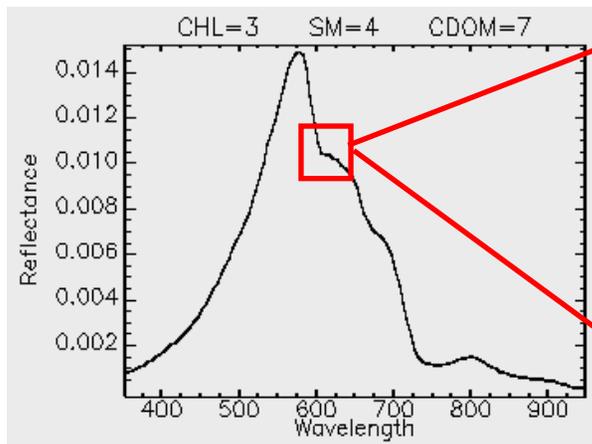
# Water is Unique!



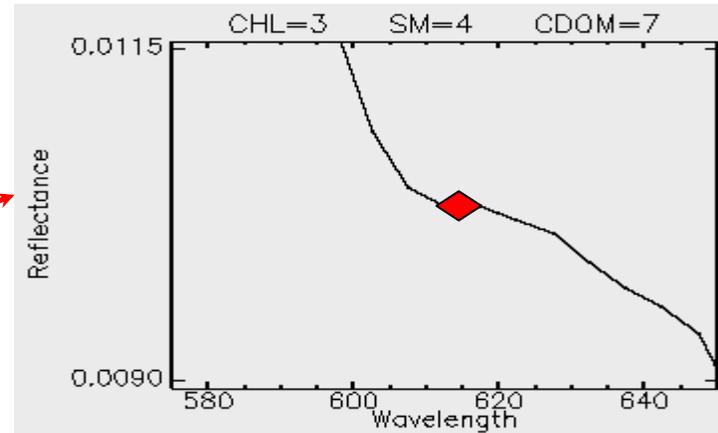
# LDCM Features: Response



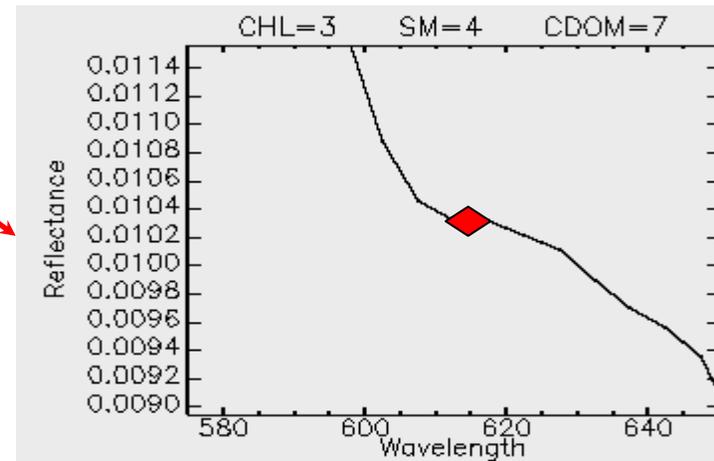
# LDCM Features: Quantization



**ETM+**

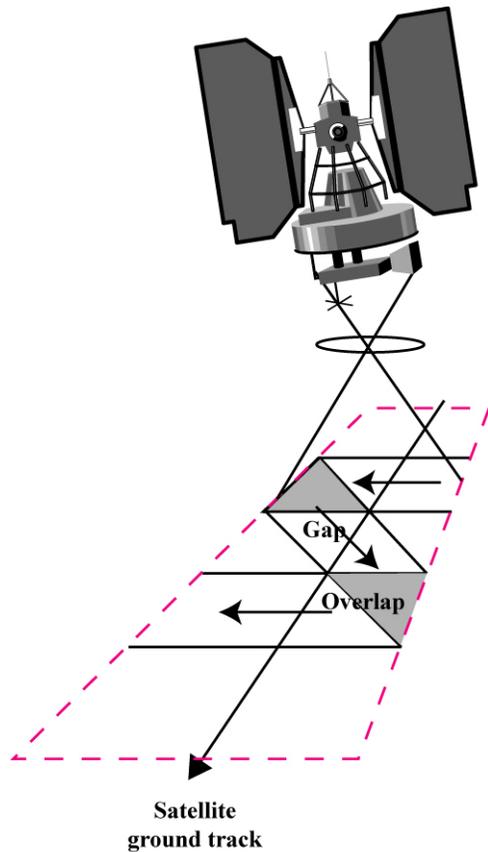


**LDCM**

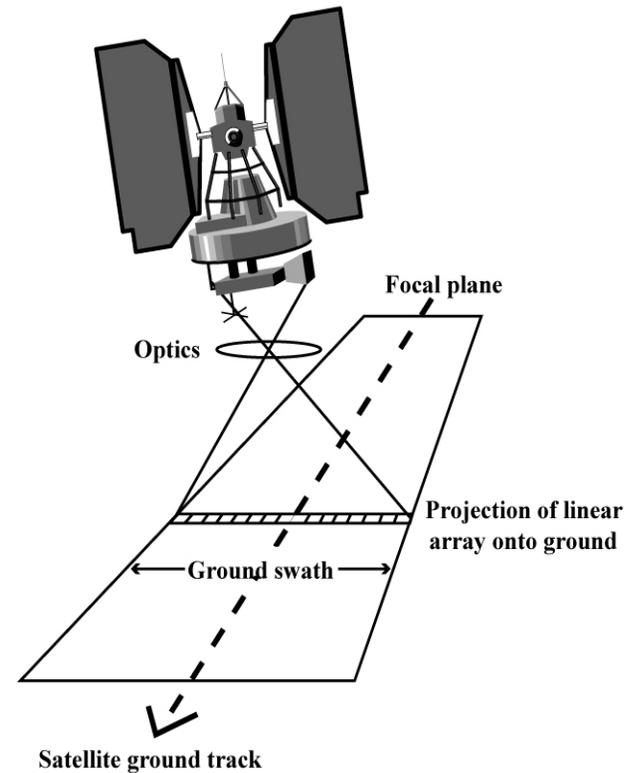


# LDCM Features: Signal to Noise

Whisk Broom Sensor



Push Broom Sensor



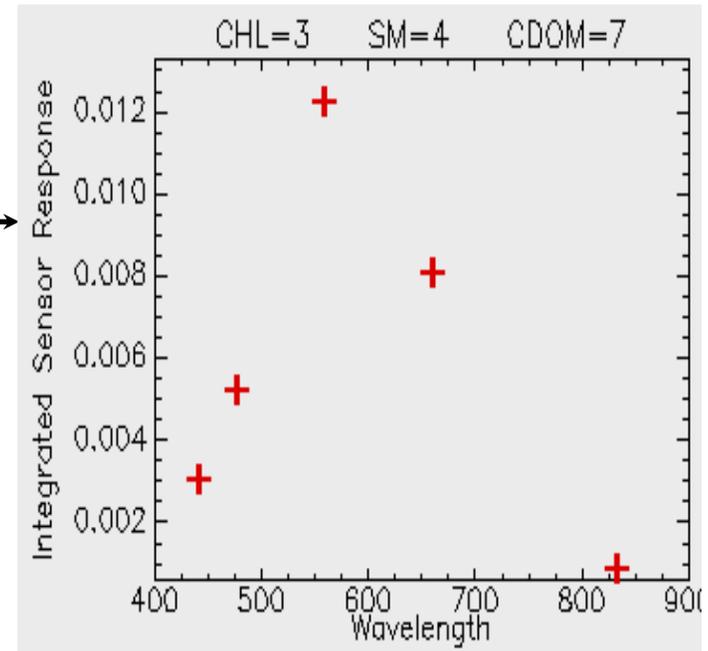
# Modeling LDCM Improvements

What do we gain from the addition of ...

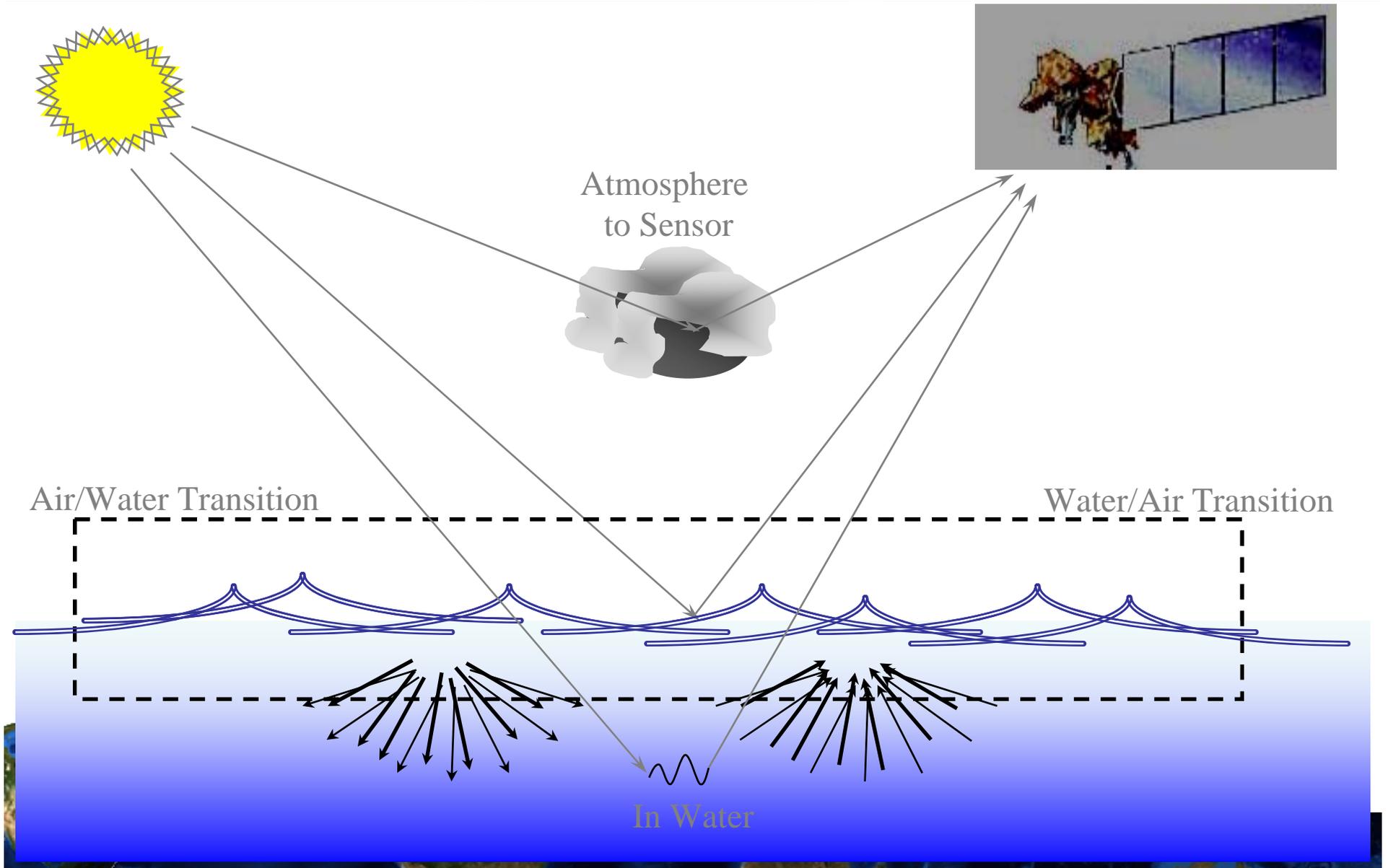
- an Aerosol Blue band
- 12 bit quantization
- Improved signal-to-noise ratios
- Can LDCM be effective in the constituent retrieval process? (perfect atm. comp.)
- Can we compensate for the atmosphere?
- Can we compensate for the lack of a thermal band?



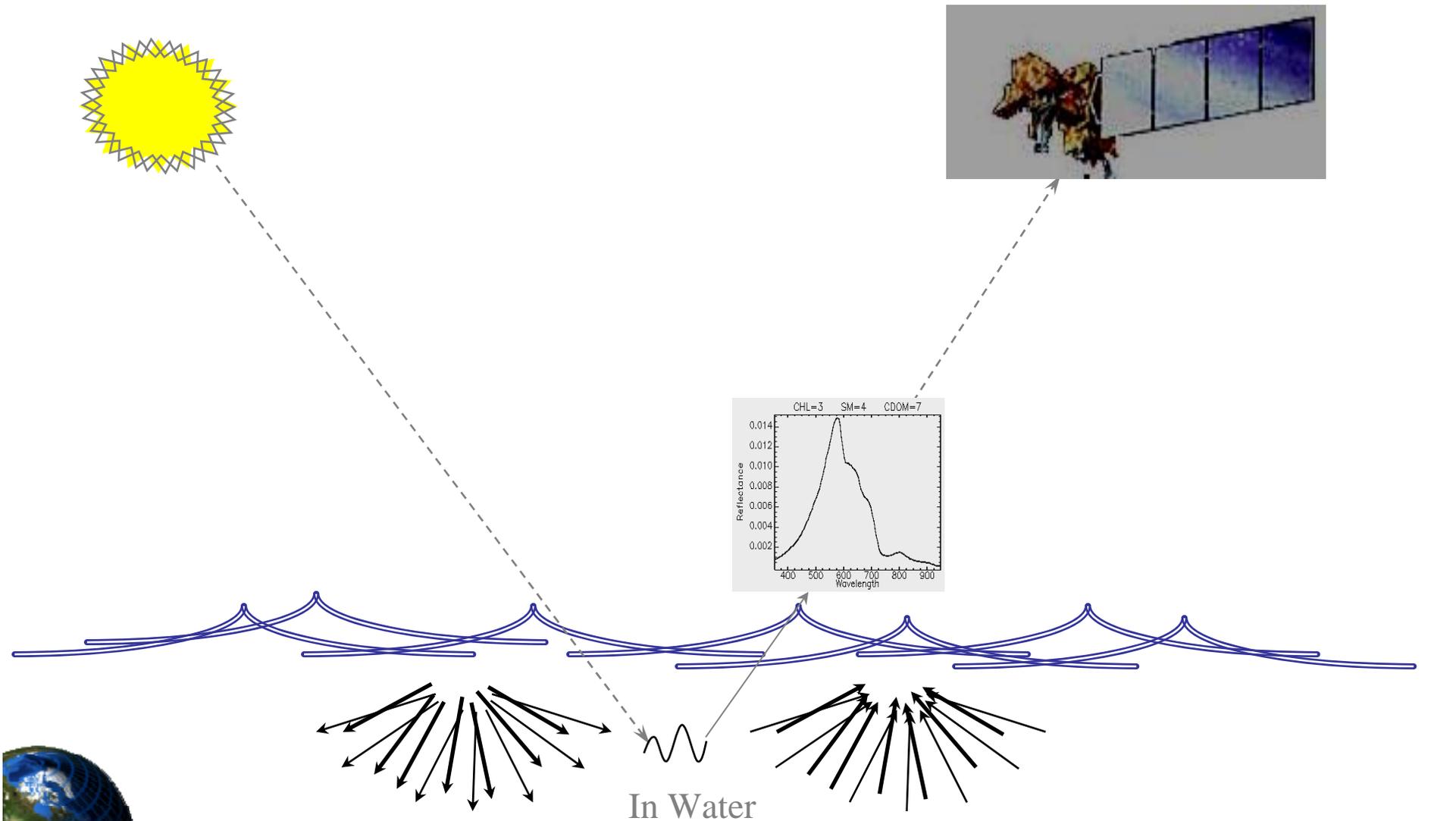
# Modeling the Process



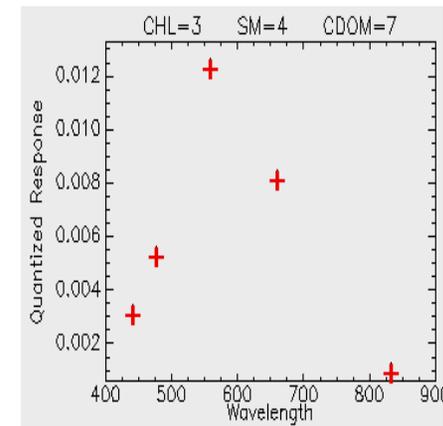
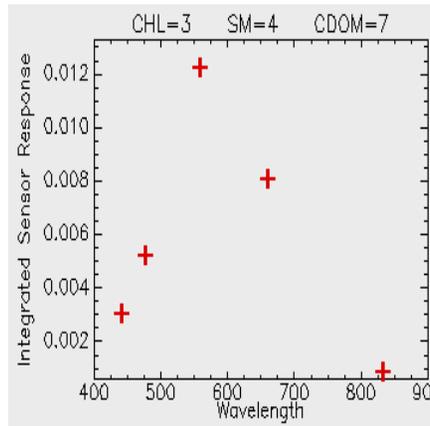
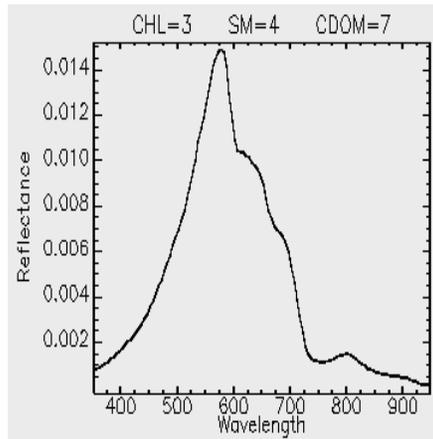
# Modeling the Process



# Modeling the Process: Hydrolight



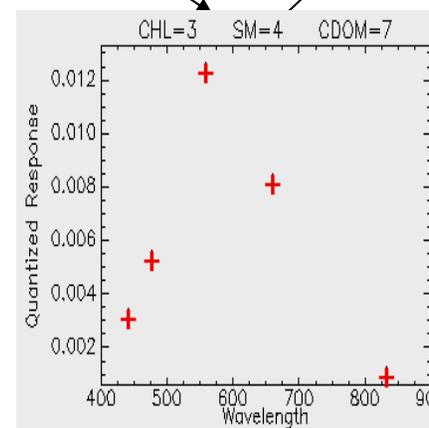
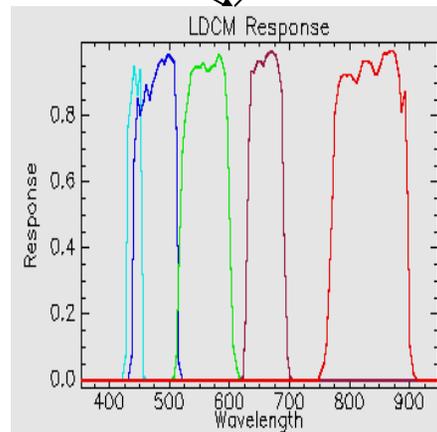
# Modeling the Process: The Sensor



**Spectrally Sample Signal**

**Add Sensor Noise**

**Quantize Signal**



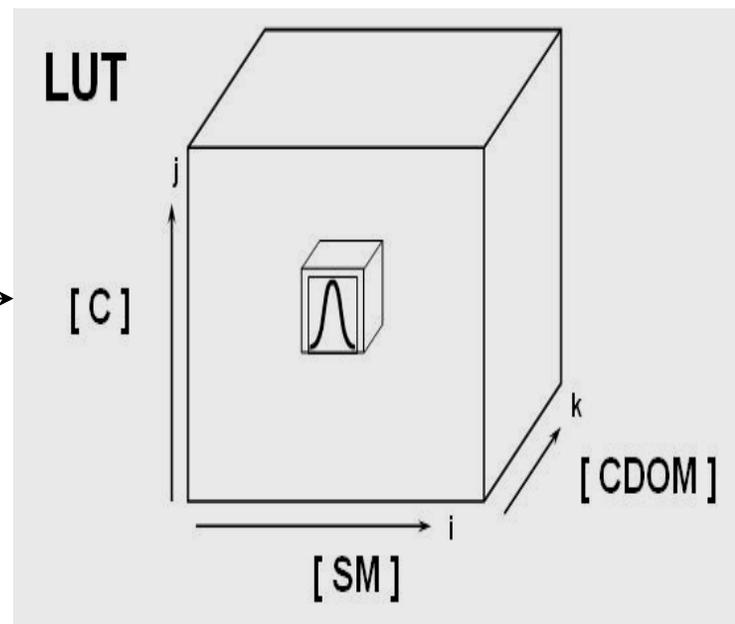
# Modeling the Process: The Scene



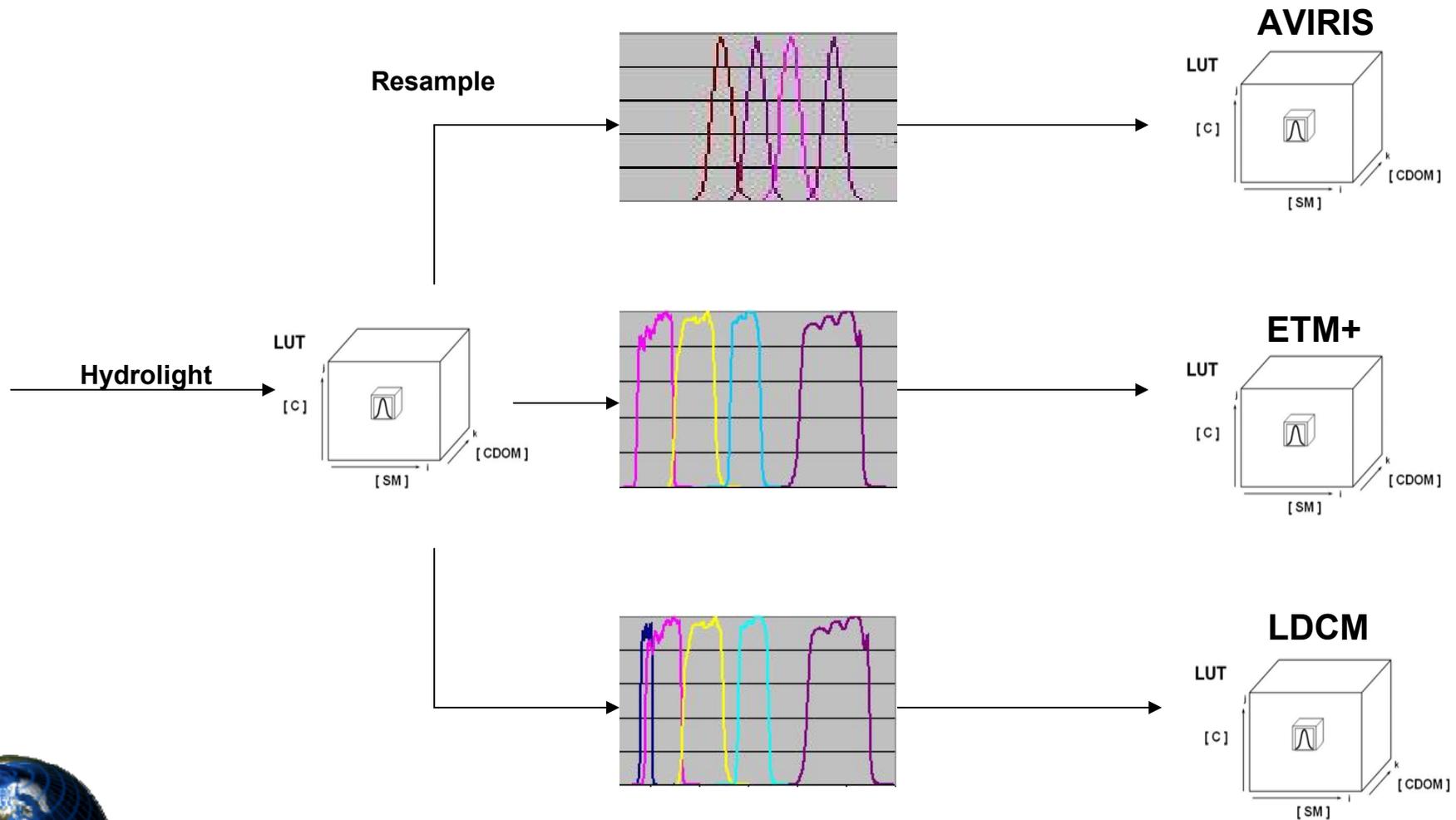
# LUT Development

C	SM	CDOM
0	0	0
.5	.5	.5
1	1	.75
3	2	1
5	4	2
7	8	4
12	10	7
24	14	10
46	20	12
68	24	14

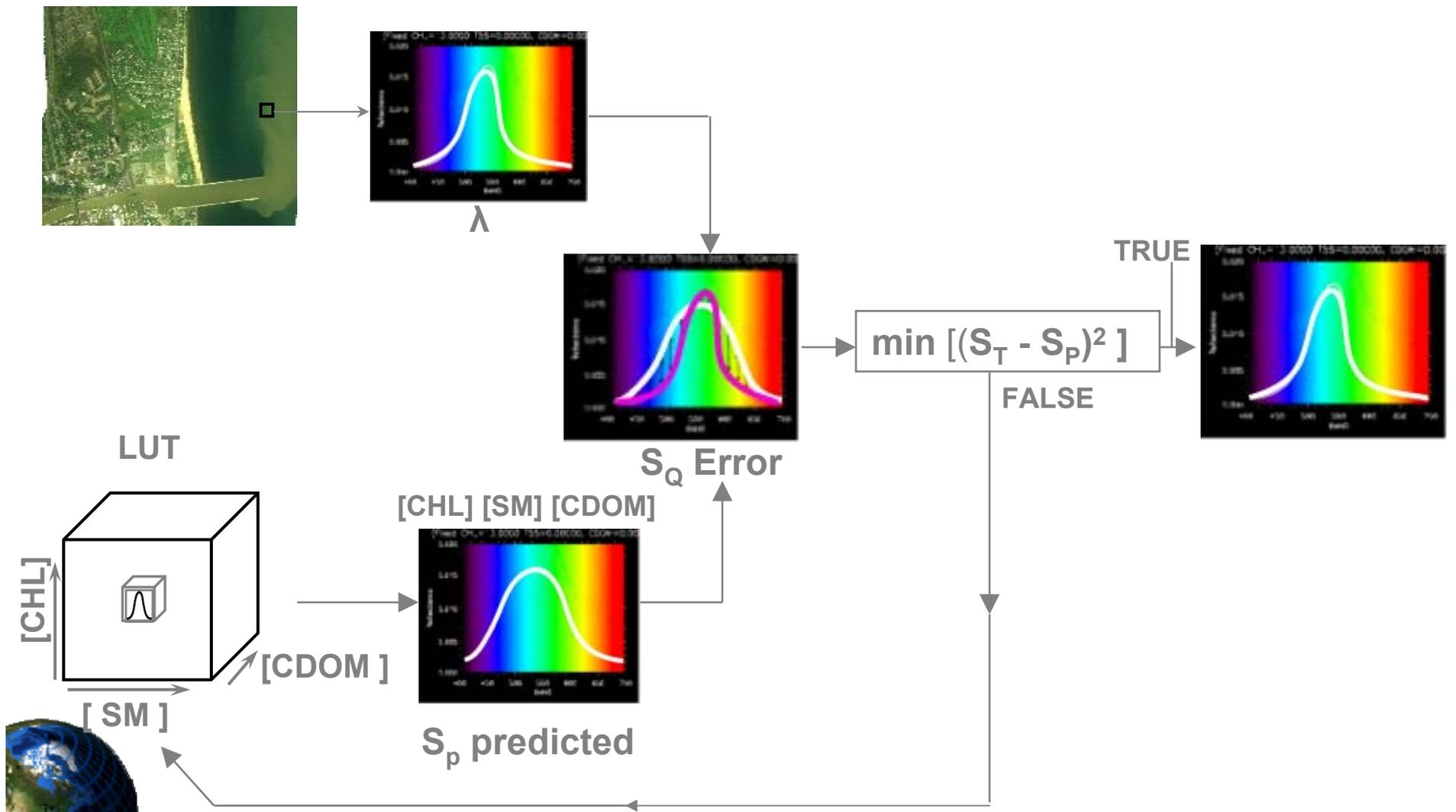
Hydrolight



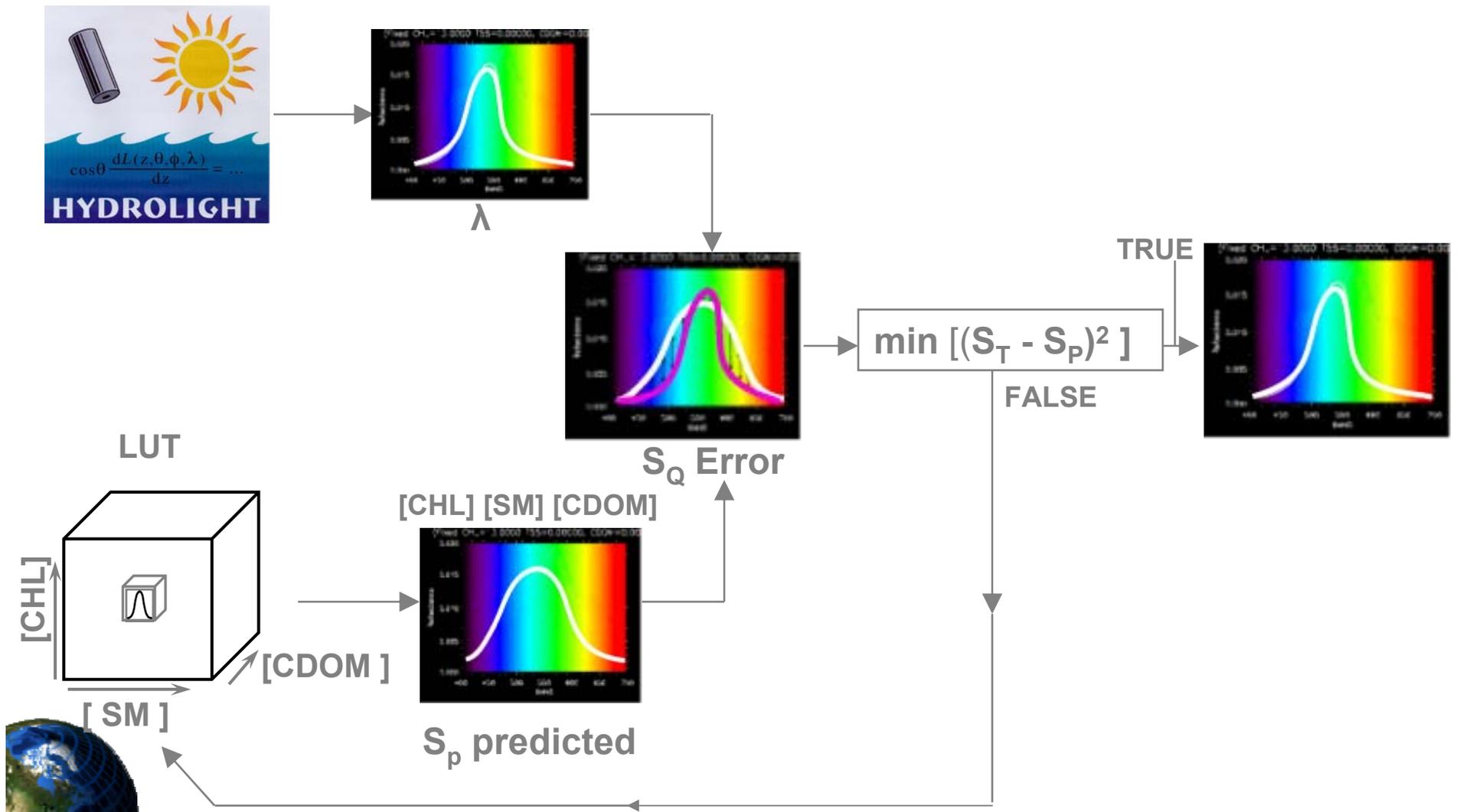
# LUT Development



# Amoeba Process

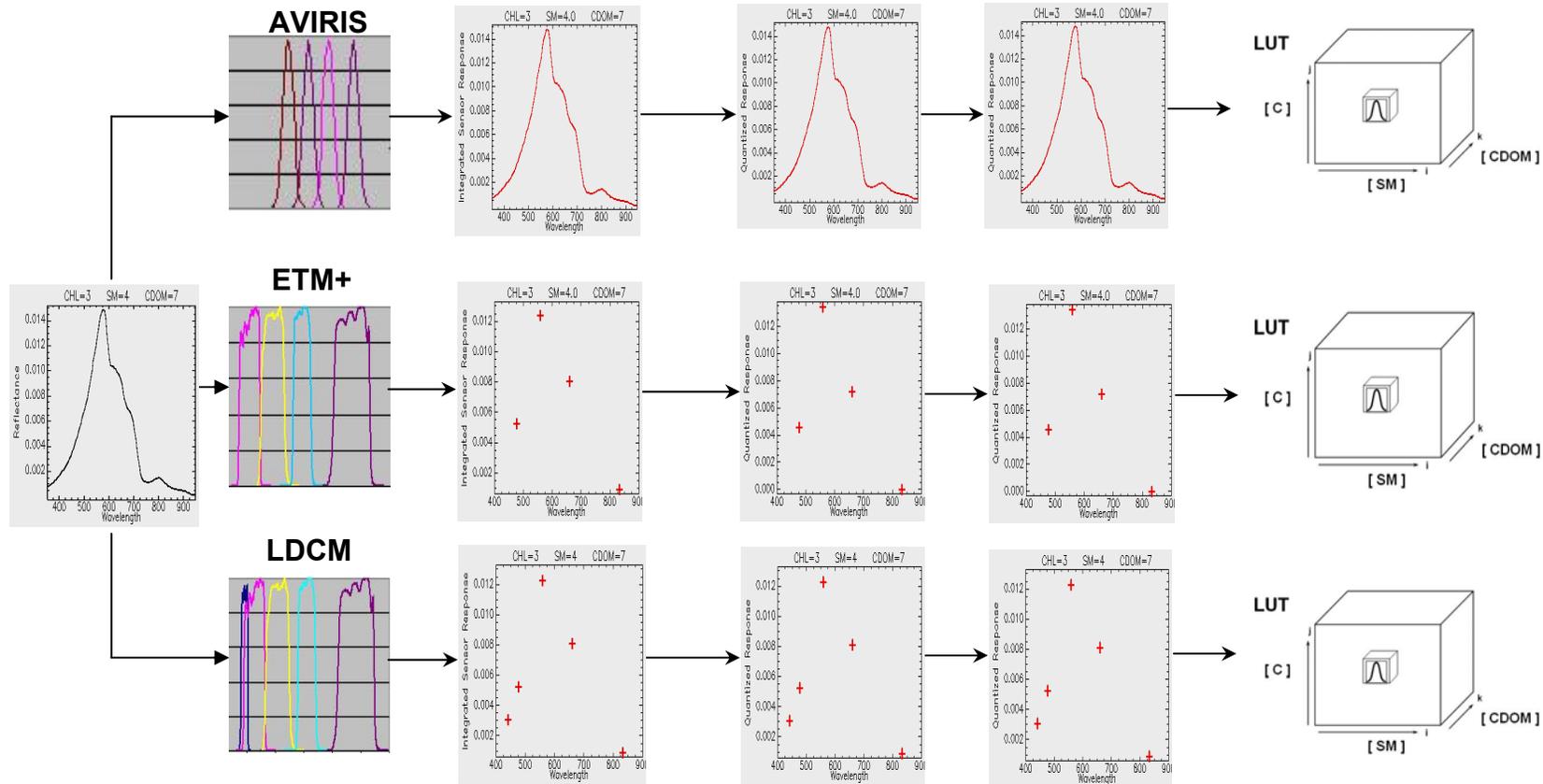


# Amoeba Process



# Process Summary

Resample    Add Noise    Quantize    Amoeba



# RMS of Residual Errors

	<b>CHL(<math>\mu\text{g/L}</math>)</b>	<b>SM(mg/L)</b>	<b>CDOM(1/m)</b>
<b>AVIRIS</b>	<b>.5</b>	<b>.1</b>	<b>.1</b>
<b>ETM+</b>	<b>.5</b>	<b>.6</b>	<b>.2</b>
<b>LDCM</b>	<b>.5</b>	<b>.5</b>	<b>.1</b>



# RMS of Residual Errors

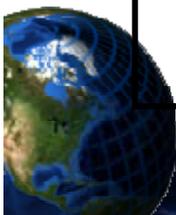
	<b>CHL(<math>\mu\text{g/L}</math>)</b>	<b>SM(mg/L)</b>	<b>CDOM(1/m)</b>
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<b>ETM+</b>	<b>.5</b>	<b>.6</b>	<b>.2</b>
<b>LDCM</b>	<b>.5</b>	<b>.5</b>	<b>.1</b>
<b>ETM+ Quantized</b>	<b>5.7</b>	<b>2.8</b>	<b>1.7</b>
<b>LDCM Quantized</b>	<b>1.2</b>	<b>.6</b>	<b>.2</b>
<b>ETM+ Noise &amp; Quantized</b>	<b>7.4</b>	<b>4.8</b>	<b>3.2</b>
<b>LDCM Noise &amp; Quantized</b>	<b>3.7</b>	<b>1.2</b>	<b>.9</b>



# RMS of Residual Errors... (As Percentages)

10% Goal

	CHL( $\mu\text{g/L}$ )		SM( $\text{mg/L}$ )		CDOM( $1/\text{m}$ )	
<b>AVIRIS</b>	<b>.5</b>		<b>.1</b>		<b>.1</b>	
<b>ETM+</b>	<b>.5</b>		<b>.6</b>		<b>.2</b>	
<b>LDCM</b>	<b>.5</b>		<b>.5</b>		<b>.1</b>	
<b>ETM+ Quantized</b>	<b>5.7</b>	<b>8.4%</b>	<b>2.8</b>	<b>11.7%</b>	<b>1.7</b>	<b>12.1%</b>
<b>LDCM Quantized</b>	<b>1.2</b>	<b>1.8%</b>	<b>.6</b>	<b>2.5%</b>	<b>.2</b>	<b>1.4%</b>
<b>ETM+ Noise &amp; Quantized</b>	<b>7.4</b>	<b>10.9%</b>	<b>4.8</b>	<b>20.0%</b>	<b>3.2</b>	<b>22.9%</b>
<b>LDCM Noise &amp; Quantized</b>	<b>3.7</b>	<b>5.4%</b>	<b>1.2</b>	<b>5.0%</b>	<b>.9</b>	<b>6.4%</b>





# Conclusions

- **Blue band contributes to retrieval of suspended materials.**
- **12 bit quantizer and improved SNR of LDCM significantly improves our ability to perform constituent retrieval.**
- **LDCM exhibits the potential to be a valuable tool in the constituent retrieval process.**

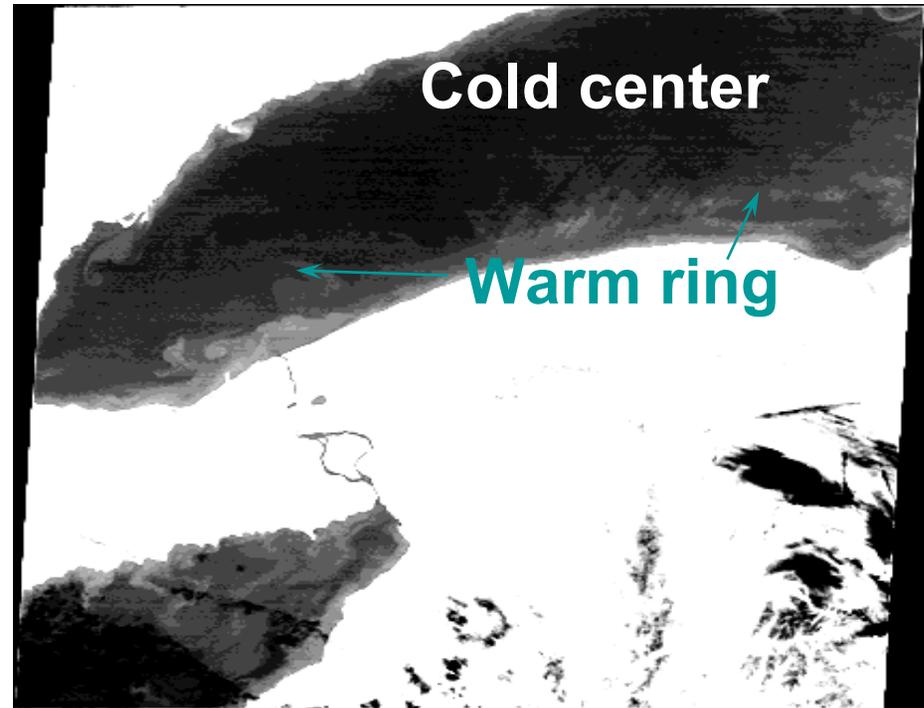


# Future Work

True Color Composite



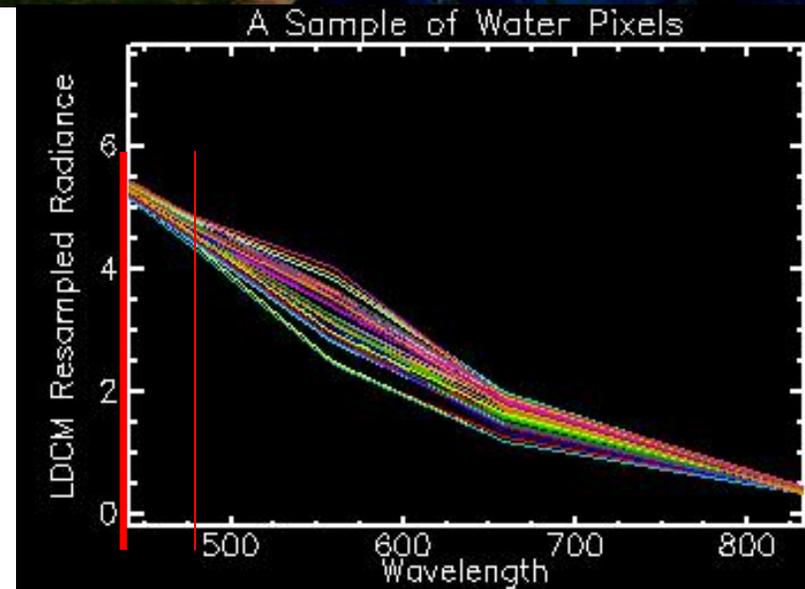
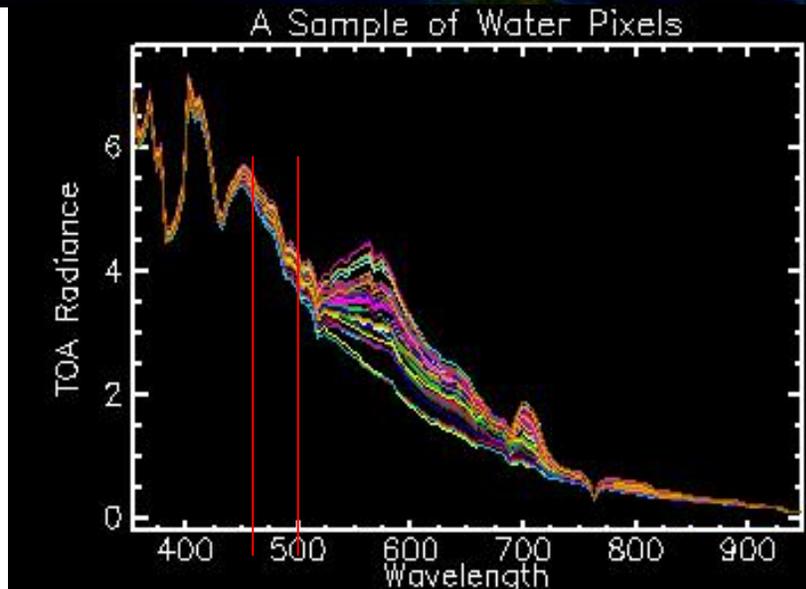
Thermal Channel



- How important is blue band for atmosphere correction?
- Role of thermal band in predicting hydrodynamics of receiving water.



# Hydrolight-generated water pixels as seen through a 40km visibility atmosphere.



- (Left) TOA Radiance, (Right) Resampled to five LDCM bands.
- Atmospheric compensation algorithm developed to take advantage of deep blue band.
  - Notice low variability at 443nm and increased variability at 482nm.
  - Correction algorithm takes ratio of 443 band and 865 band based on the assumption that variability in these bands is due solely to atmosphere.
  - This assumption breaks down for 482 band as variability due to water signal increases.

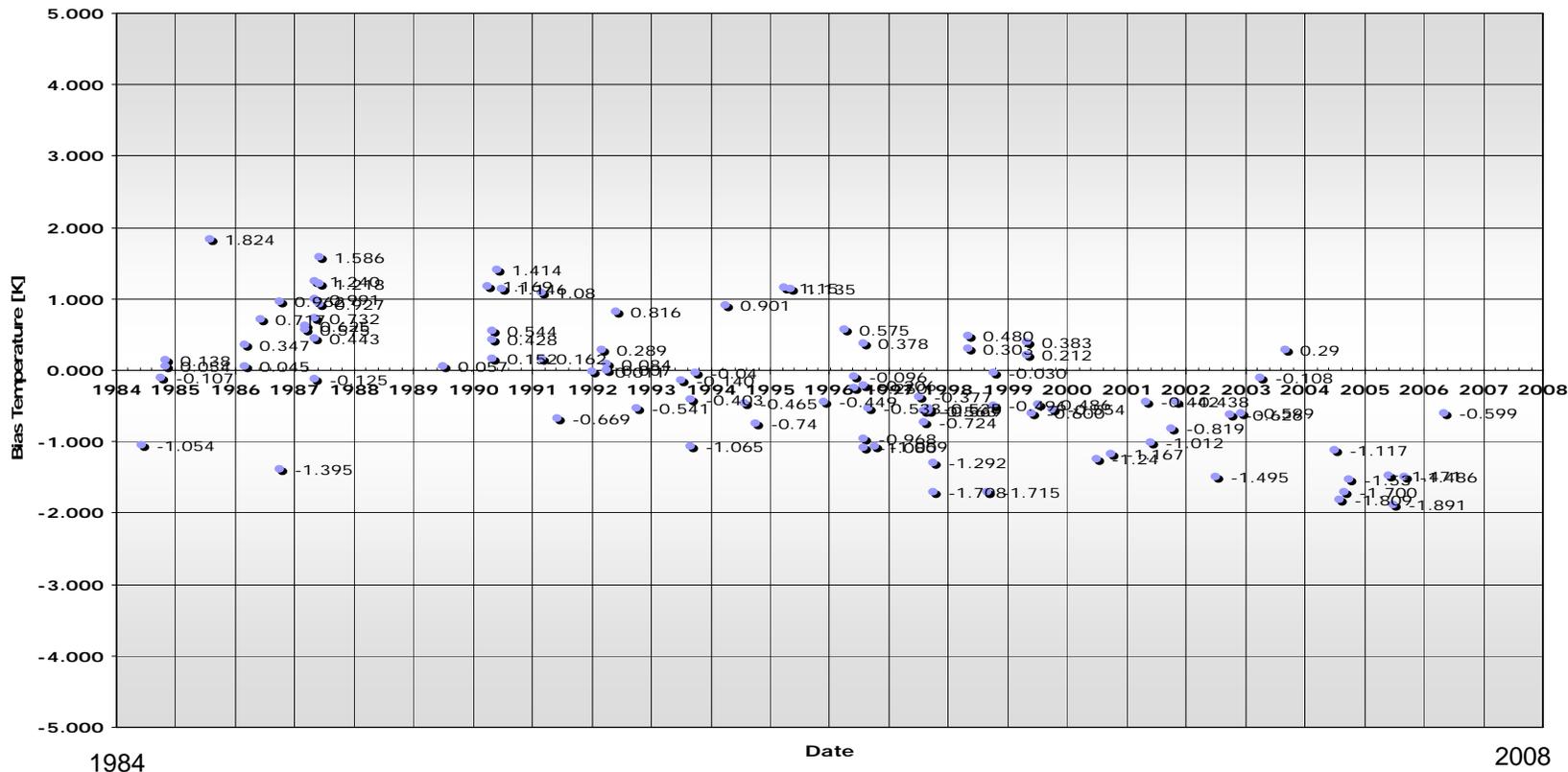




# Calibration Curve: Filtered

Bias Temperature vs Date  
[all]

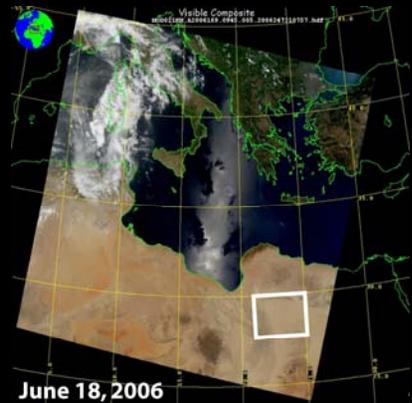
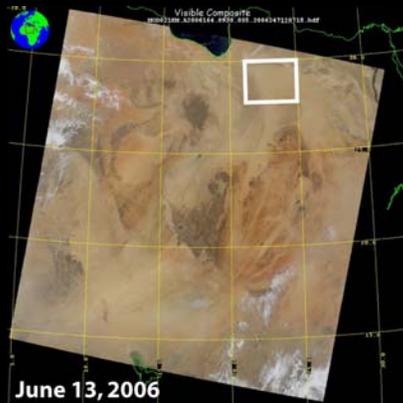
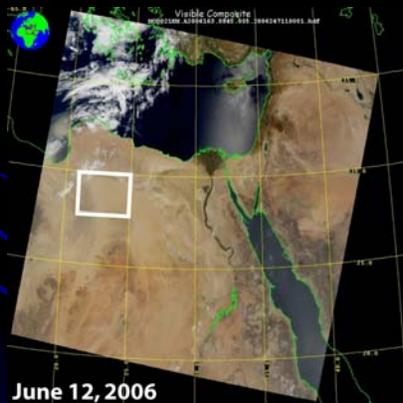
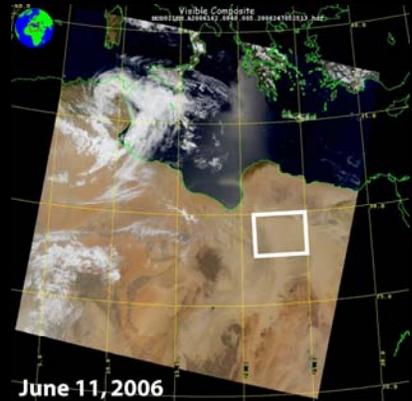
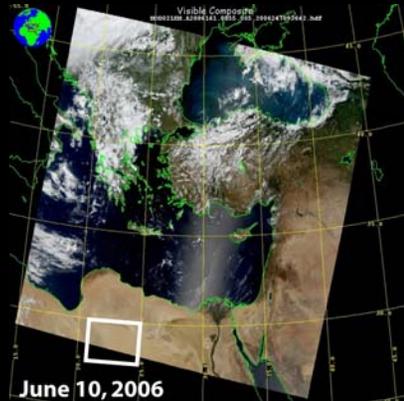
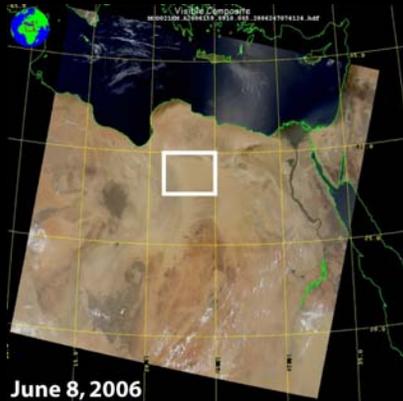
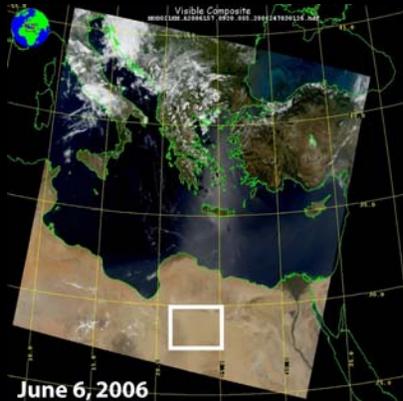
• )Current Calib. (RIT



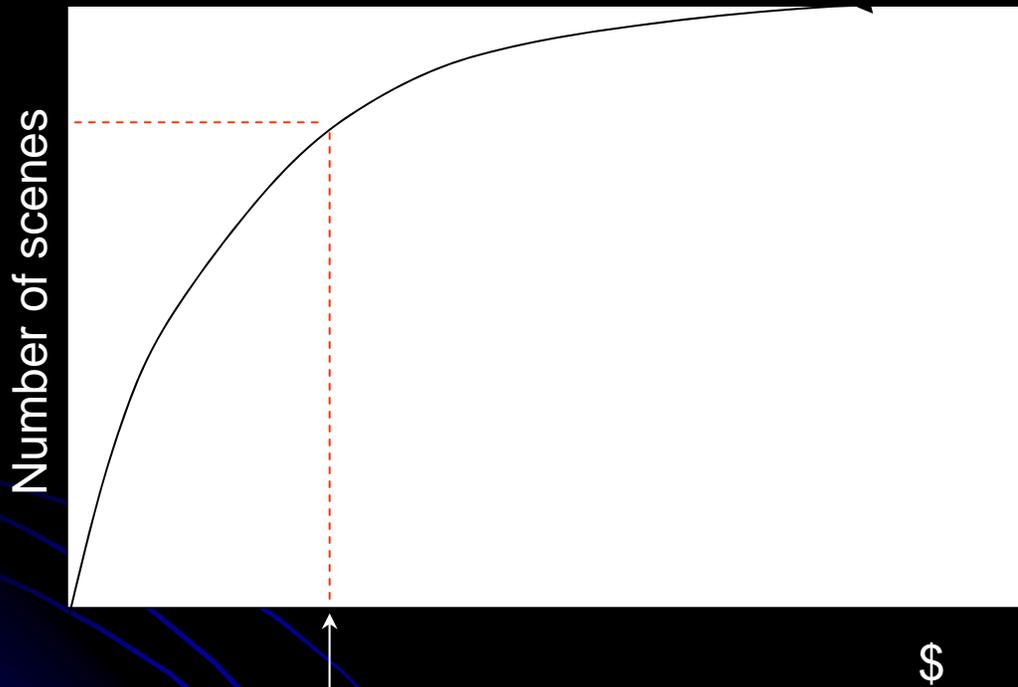
## Landsat 5 Calibration History

Digital  
Imaging and  
Remote  
Sensing  
Laboratory

Center for  
Imaging  
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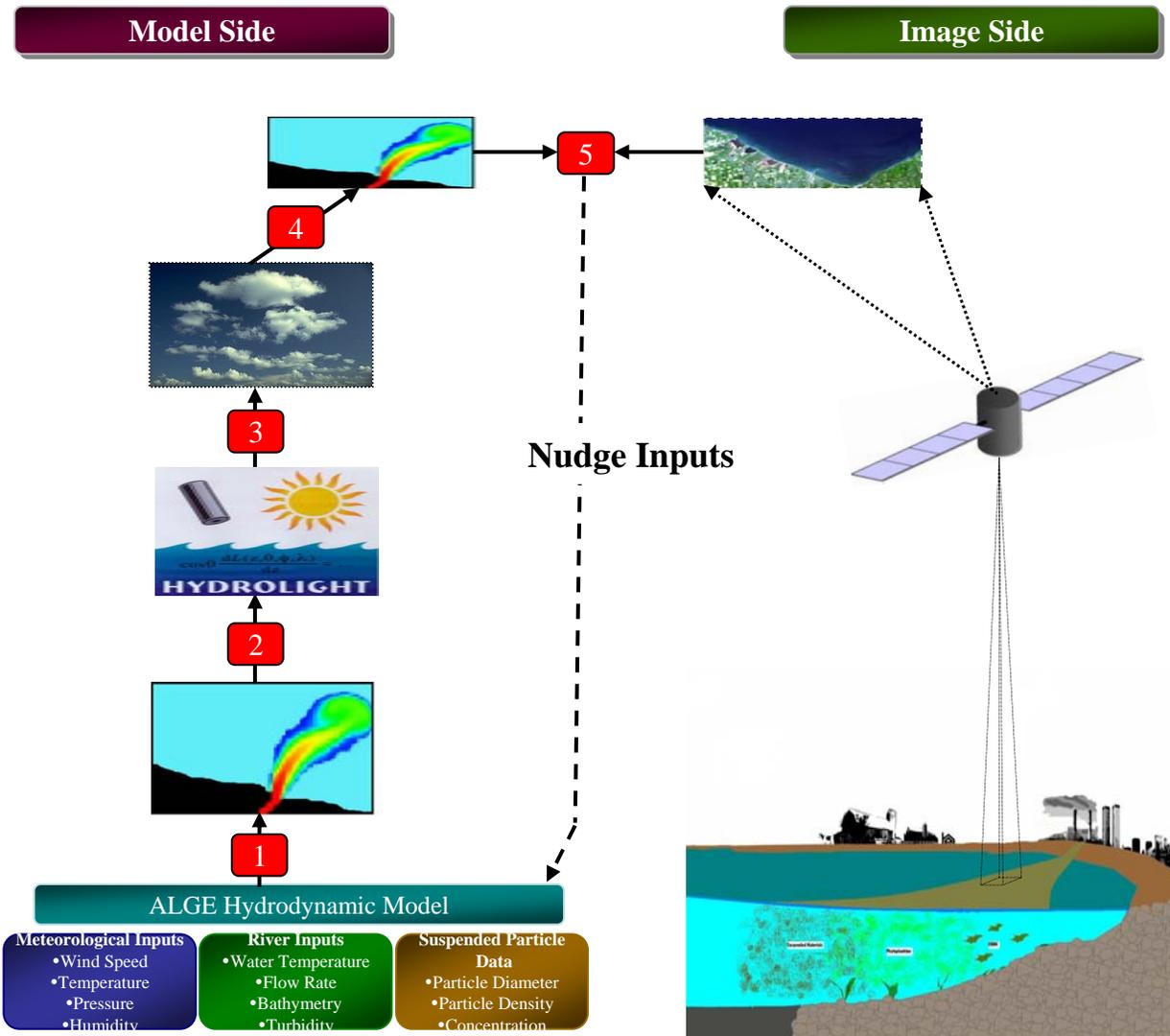


# International Archive Question

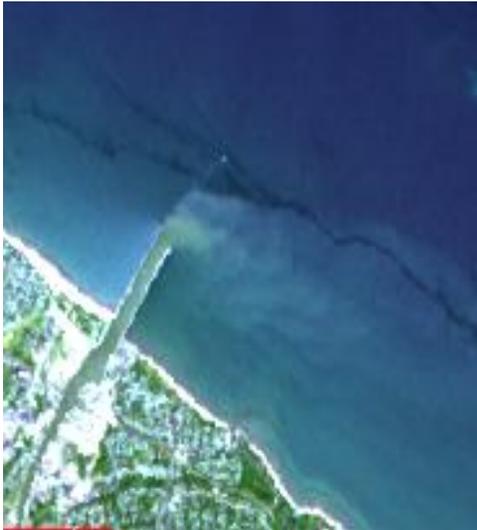


80% Solution vs. Cost of new Mission(s) →

# Using Remotely Sensed Data for Model Calibration



# Performed constituent retrieval on real data (Genesee Plume) to test algorithm



- Ran algorithm with 482nm and 865nm bands of ETM+.
- Ran algorithm with 442nm and 865nm bands of LDCM.
- Compared in situ measurements to algorithm retrieved data to find RMSE of concentrations.

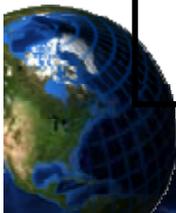
	CHL	TSS	CDOM
LDCM	1.4 2.1%	2.4 10.0%	2.7 19.3%
ETM+	1.1 1.6%	4.7 19.6%	2.1 15.0%

# RMS of Residual Errors

	<b>CHL(<math>\mu\text{g/L}</math>)</b>	<b>SM(mg/L)</b>	<b>CDOM(1/m)</b>
<b>AVIRIS</b>	<b>.5</b>	<b>.1</b>	<b>.1</b>
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# RMS of Residual Errors... (As Percentages)

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<b>LDCM Quantized</b>	<b>1.2</b>	<b>1.8%</b>	<b>.6</b>	<b>2.5%</b>	<b>.2</b>	<b>1.4%</b>
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<b>LDCM Noise &amp; Quantized</b>	<b>3.7</b>	<b>5.4%</b>	<b>1.2</b>	<b>5.0%</b>	<b>.9</b>	<b>6.4%</b>

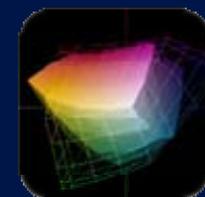
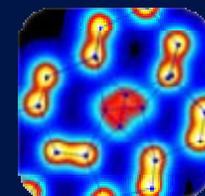




# LDCM Ratios Update

Review of Correction Algorithm &  
Results of Test on Simulated Data

Digital Imaging and  
Remote Sensing Laboratory



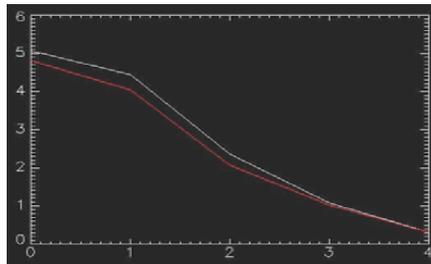
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# LDCM Approach

$$\rho_t(\lambda) = \rho_r(\lambda) + \rho_a(\lambda) + \rho_{ar}(\lambda) + \rho_g(\lambda) + t(\lambda)\rho_w(\lambda)$$

- **We remove glint to obtain...**

$$\rho_c = \rho_r(\lambda) + \rho_a(\lambda) + \rho_{ar}(\lambda) + t(\lambda)\rho_w(\lambda)$$



- **Because we are working over case 2 waters, we can't assume a zero water reflectance for NIR band.**
- **We do, however, have a spatially homogeneous body of water whose reflectance is fairly well known.**



# LDCM Procedure

- Step 1: Remove glint from image
- Step 2: Create LUT of atmospheres that implements “spatially ambient reflectance”
- Step 3: Choose “ambient” ROI and find

$$\varepsilon = \frac{\rho_c^1}{\rho_c^5}$$

to

determine appropriate atmosphere.



# The Simulation

- **Used Hydrolight to create water samples that are representative of the Rochester embayment.**
  - i.e. Lake Ontario (CHL=0.75, SM=0.50, CDOM=0.50) x 500
    - Cranberry Pond (5, 3, 5) x 500
    - Longpond (63, 22, 6) x 500
    - Genesee Plume (5, 8, 3) x 500
    - Braddocks Bay (6, 10, 9) x 500
- **Propagated water-leaving signals to TOA using an arbitrary atmosphere...Marine aerosol, 30km visibility, standard water vapor, etc.**
- **Introduced noise and quantization to the 2500 sensor-reaching signals based on LDCM specifications.**
- **Attempted to recover constituent concentrations based on “imaged” water pixels using LDCM ratio technique and LUT inversion method.**



# Results

	CHL( $\mu\text{g/L}$ )	SM( $\text{mg/L}$ )	CDOM( $1/\text{m}$ )
Perfect Atmospheric Compensation	2.2      3.2%	0.6      2.5%	0.5      3.6%
LDCM Ratio Technique use to compensate for atmosphere.	5.54      8.1%	2.56      10.4%	1.95      13.9%

- **For real data**
  - Adjacency effects
  - Rms. vs. ratio comparison

